

Fig. 1

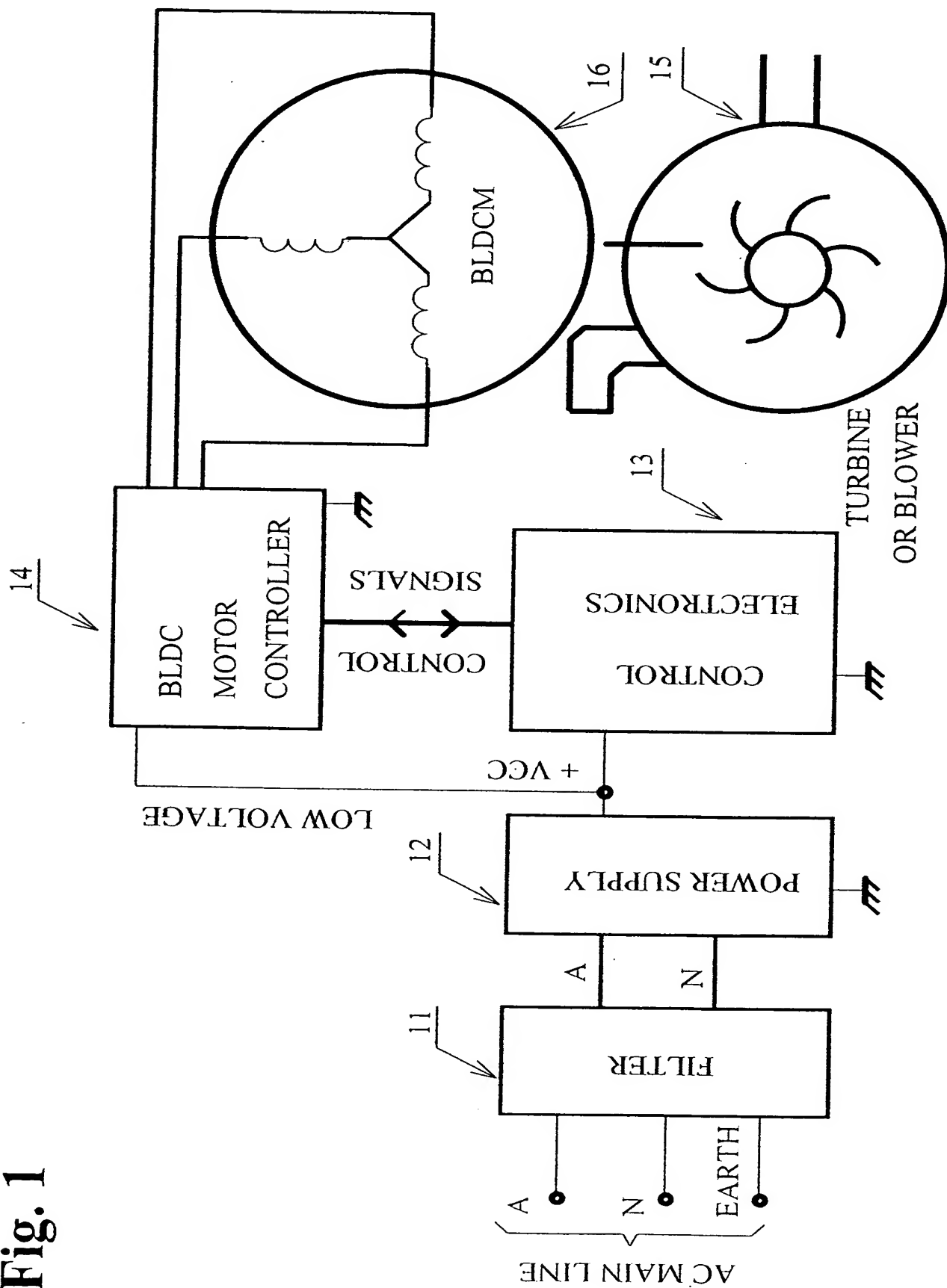


Fig. 2

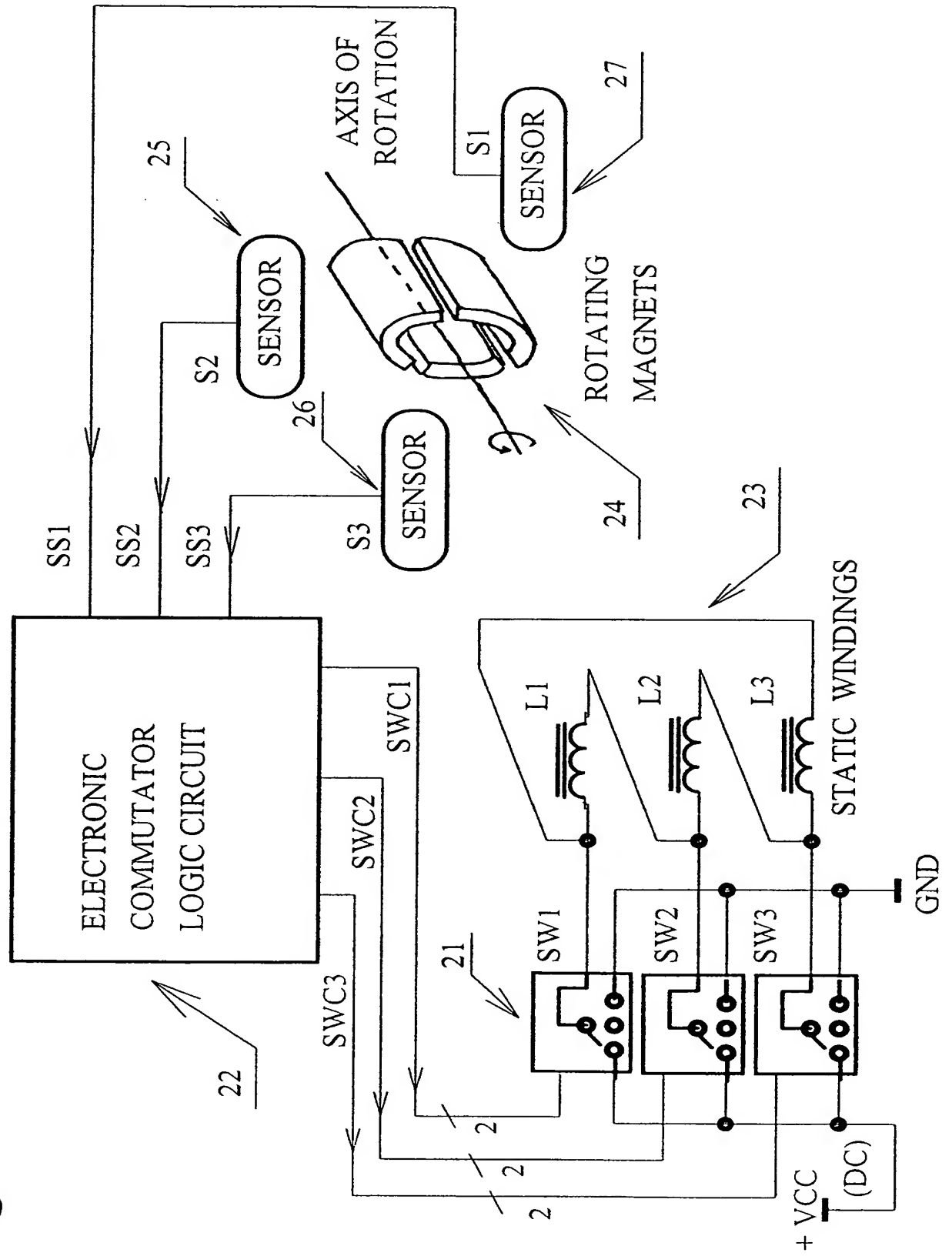
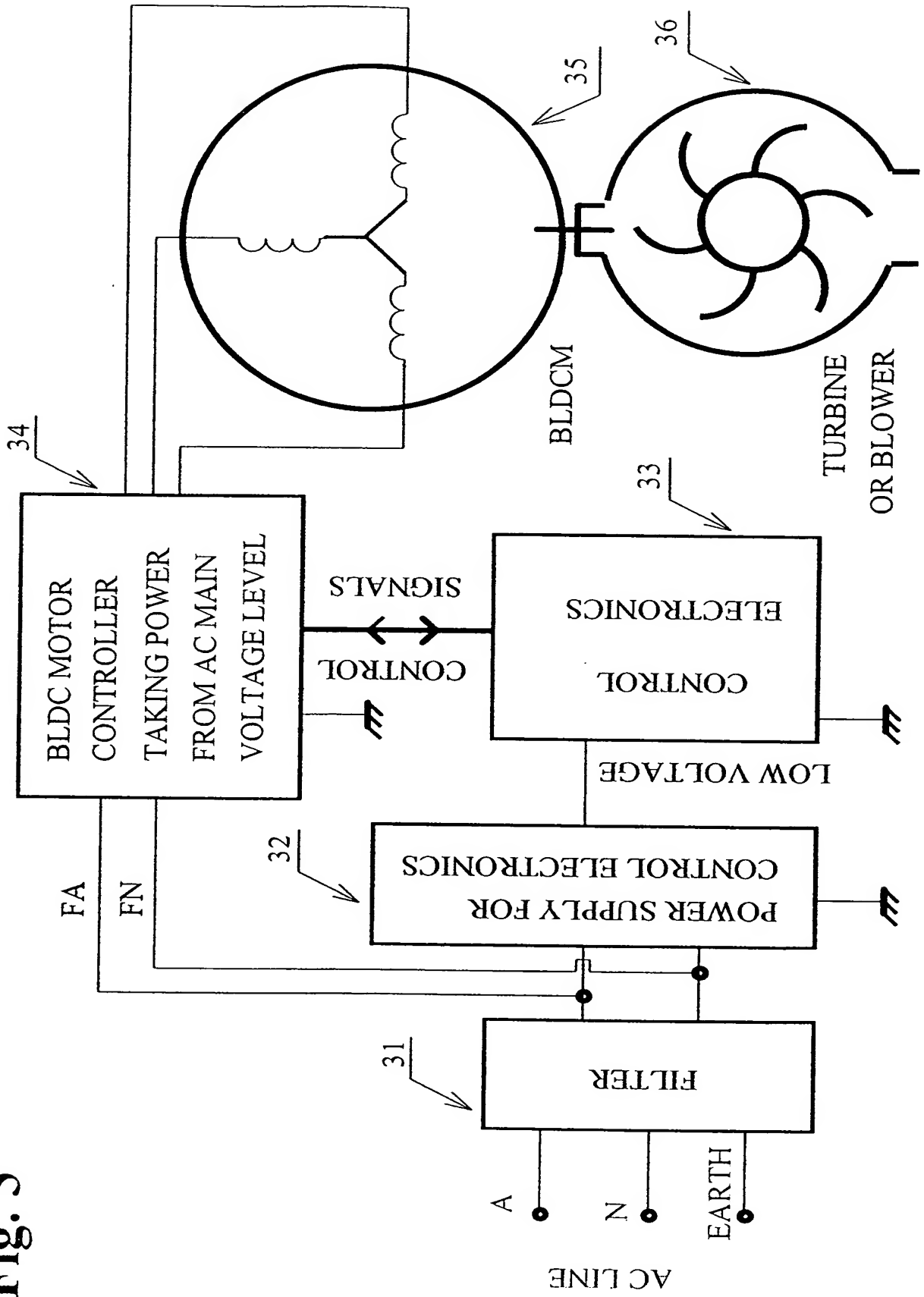


Fig. 3



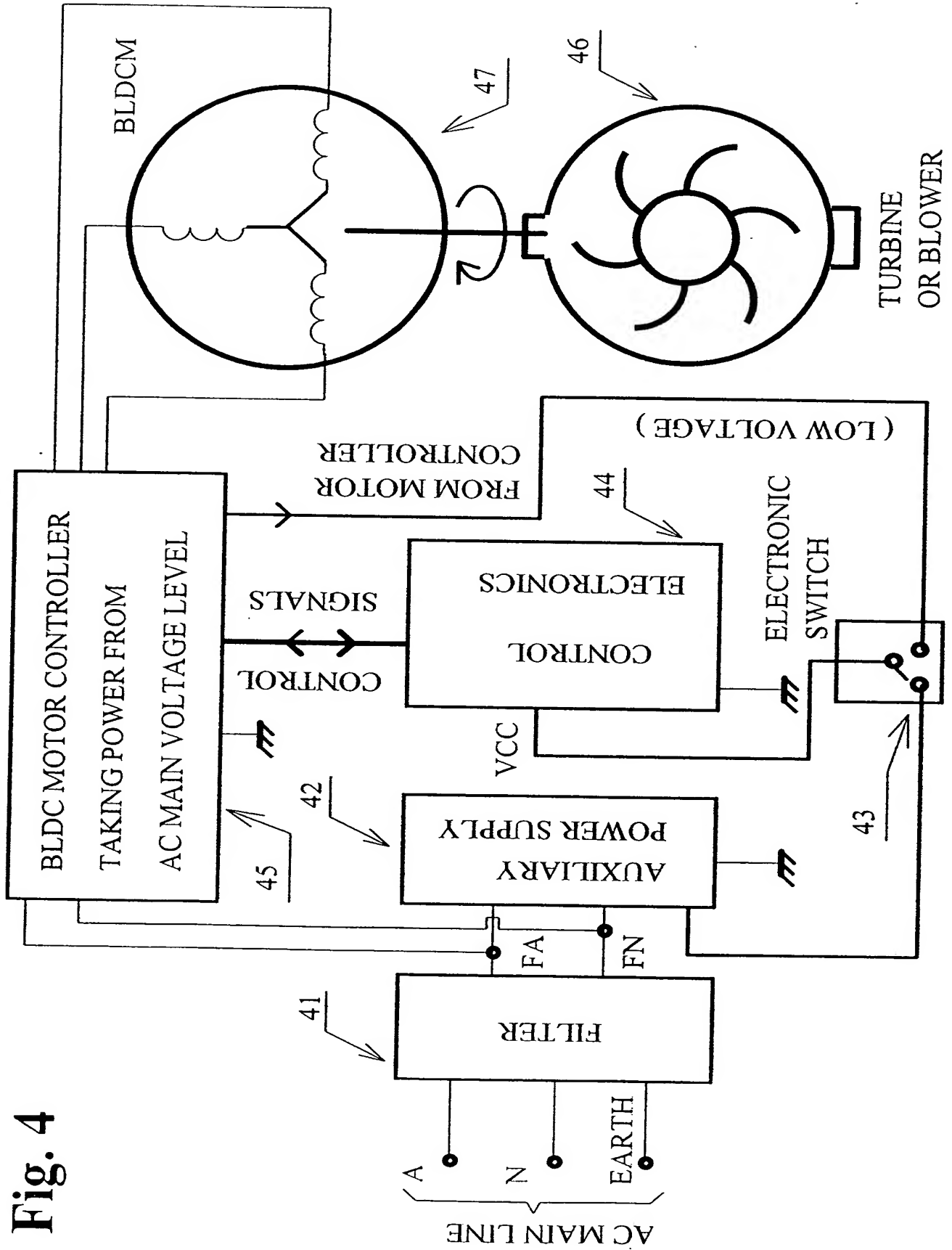


Fig. 5

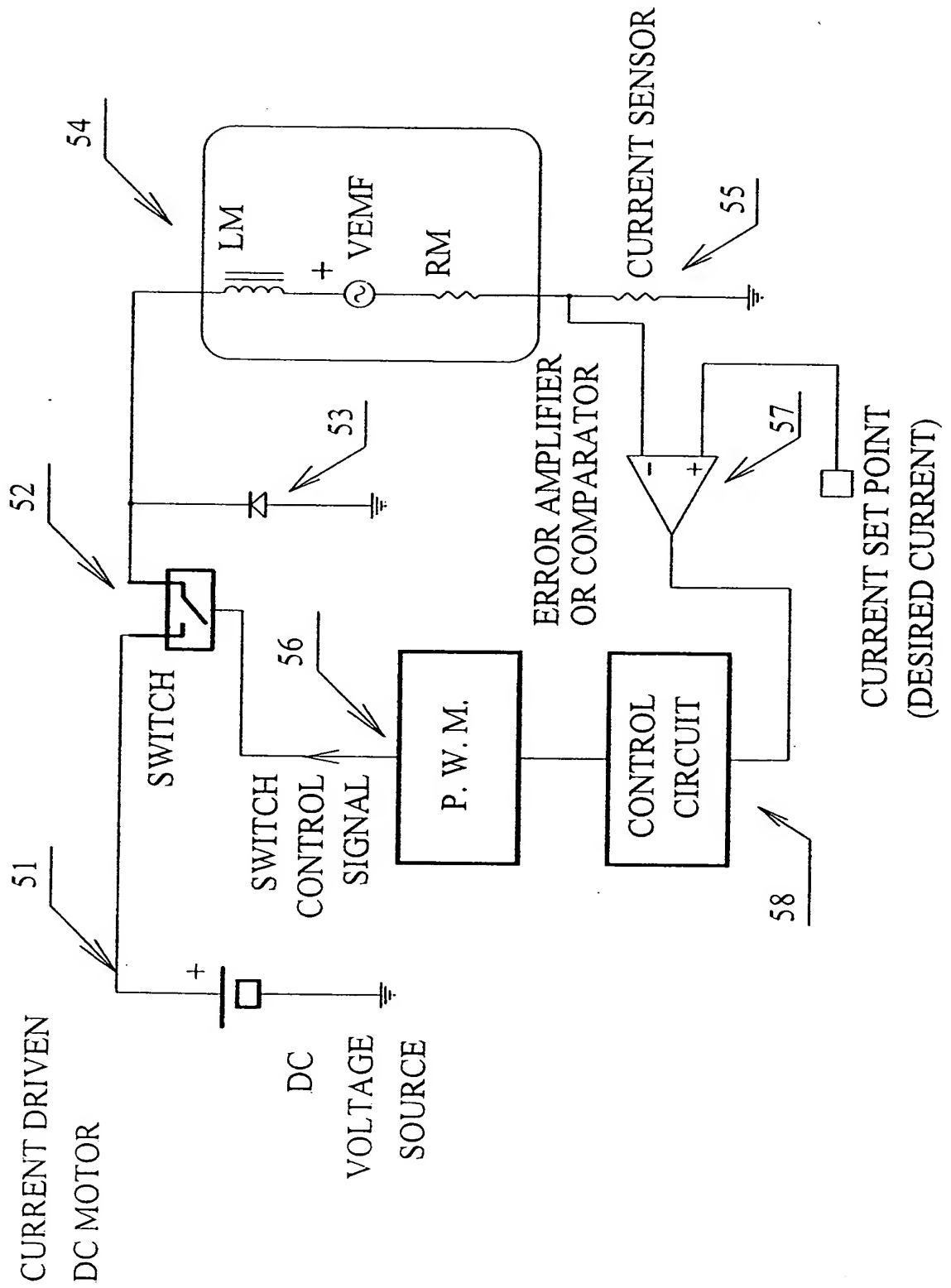


Fig. 6

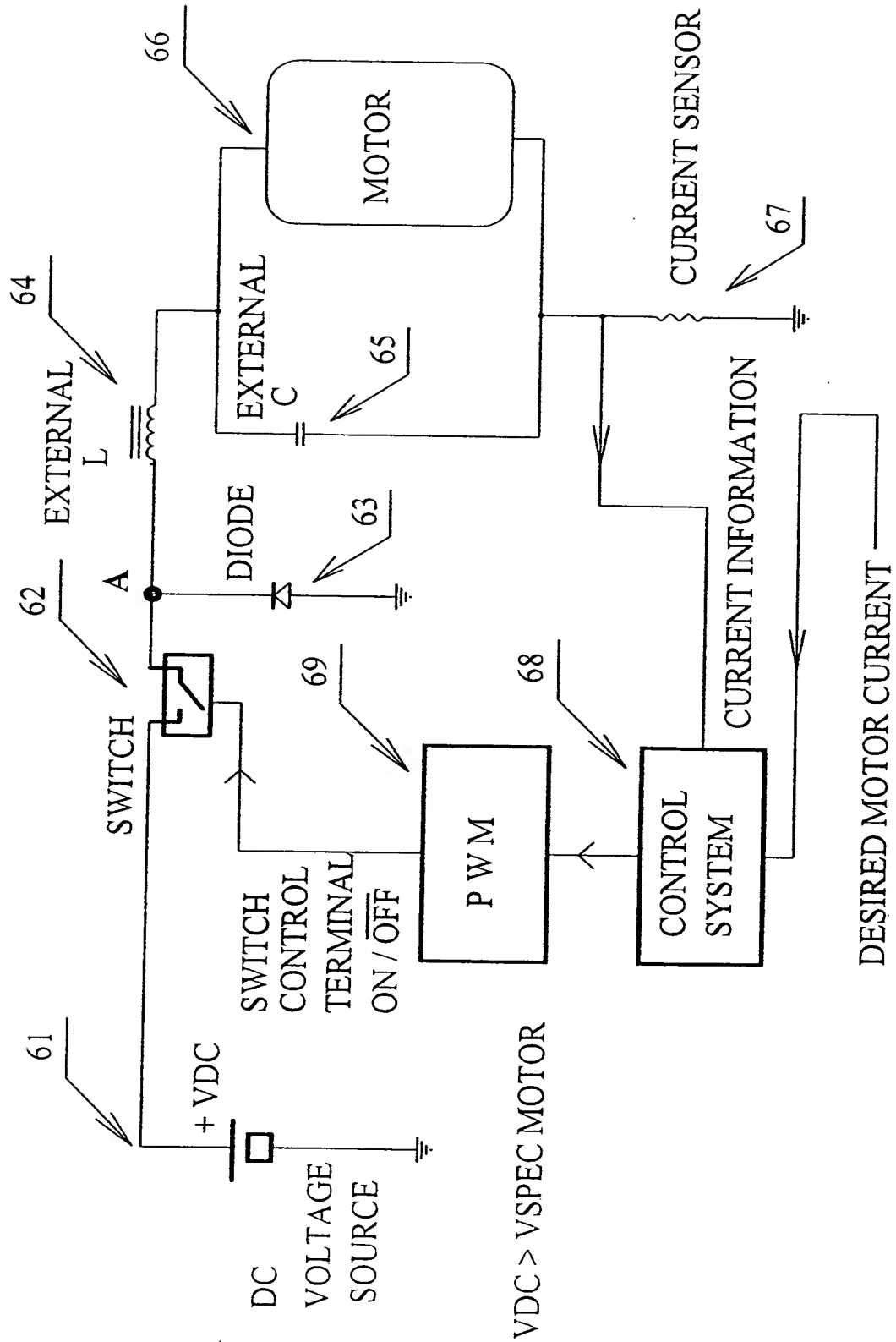
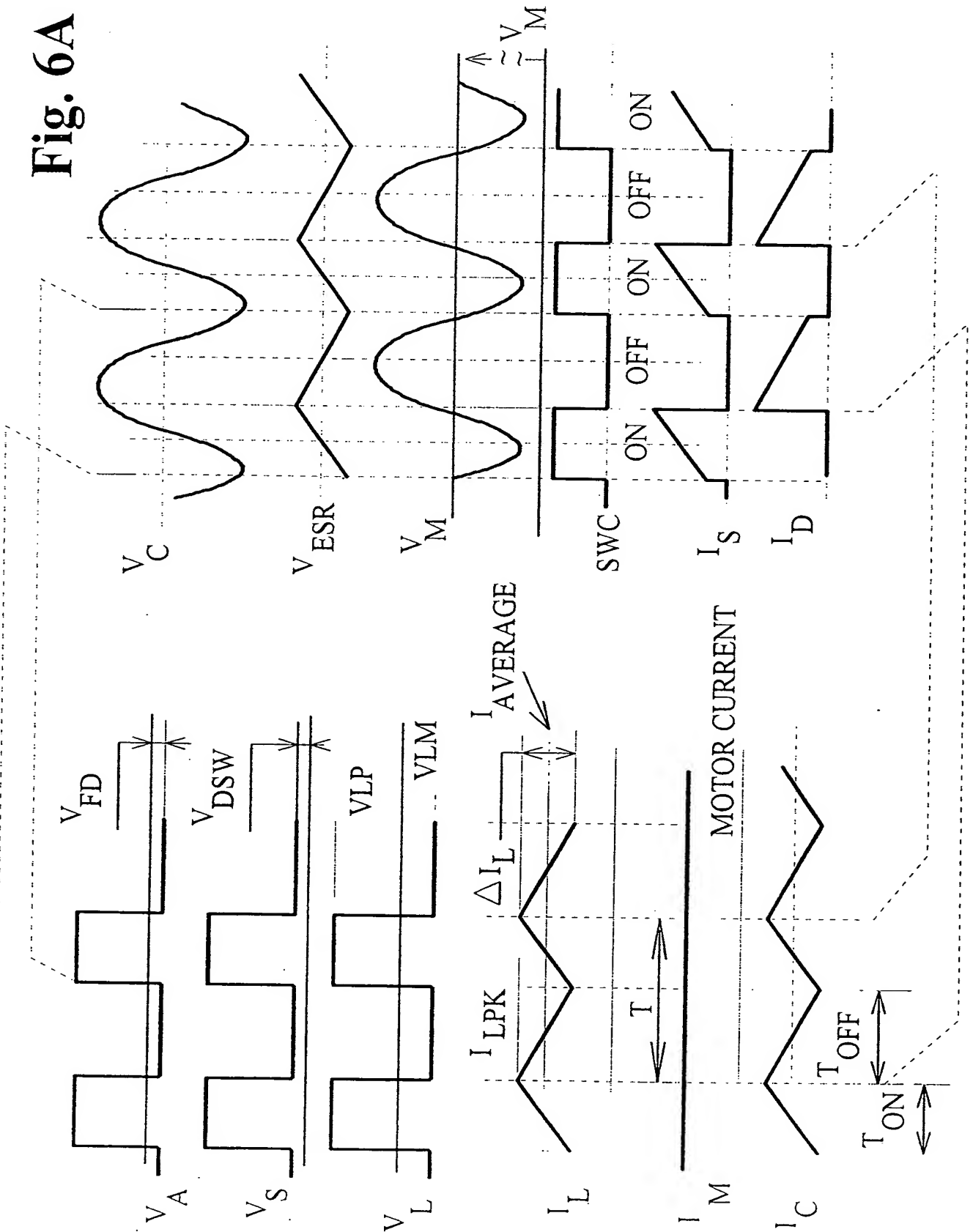


Fig. 6A



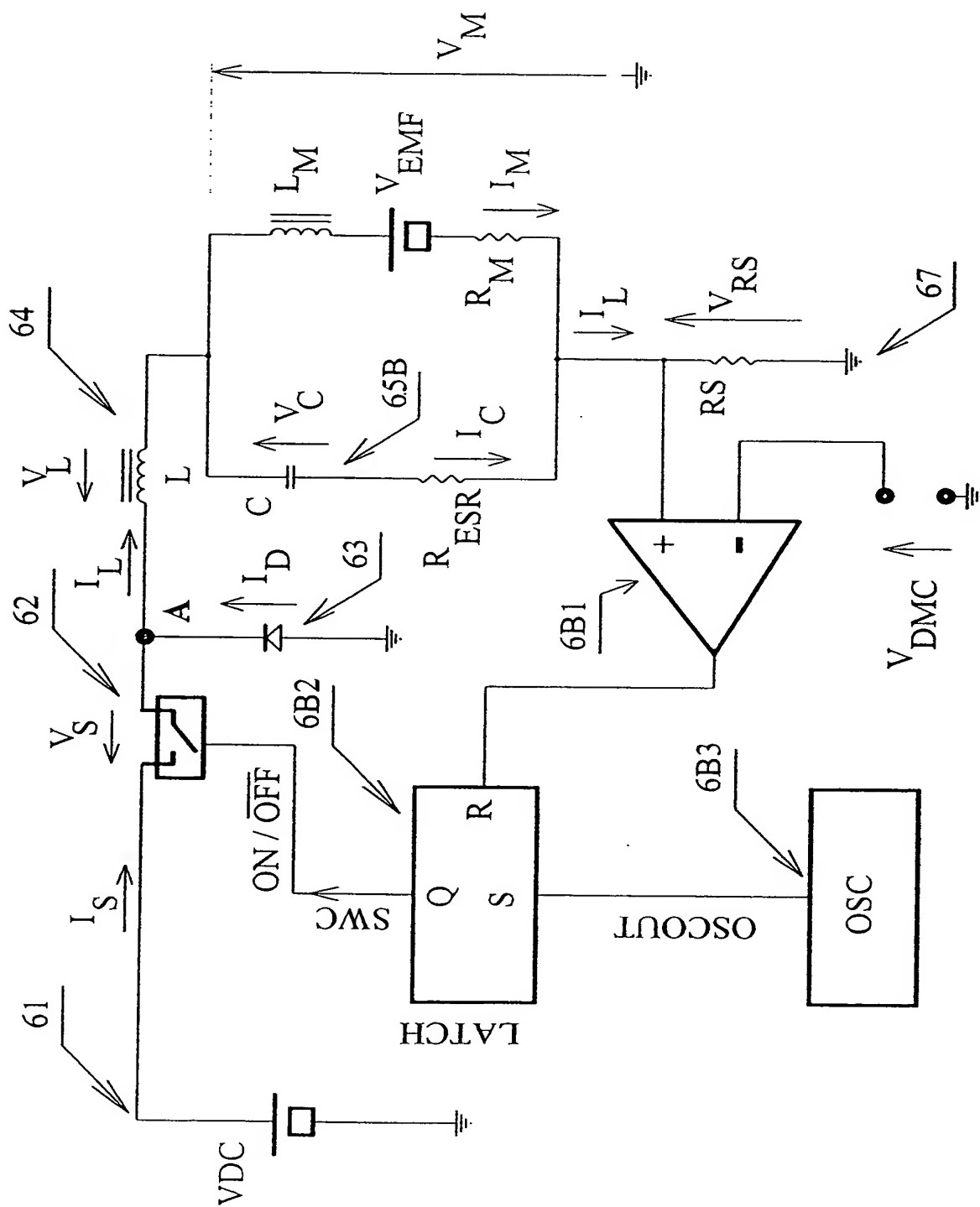
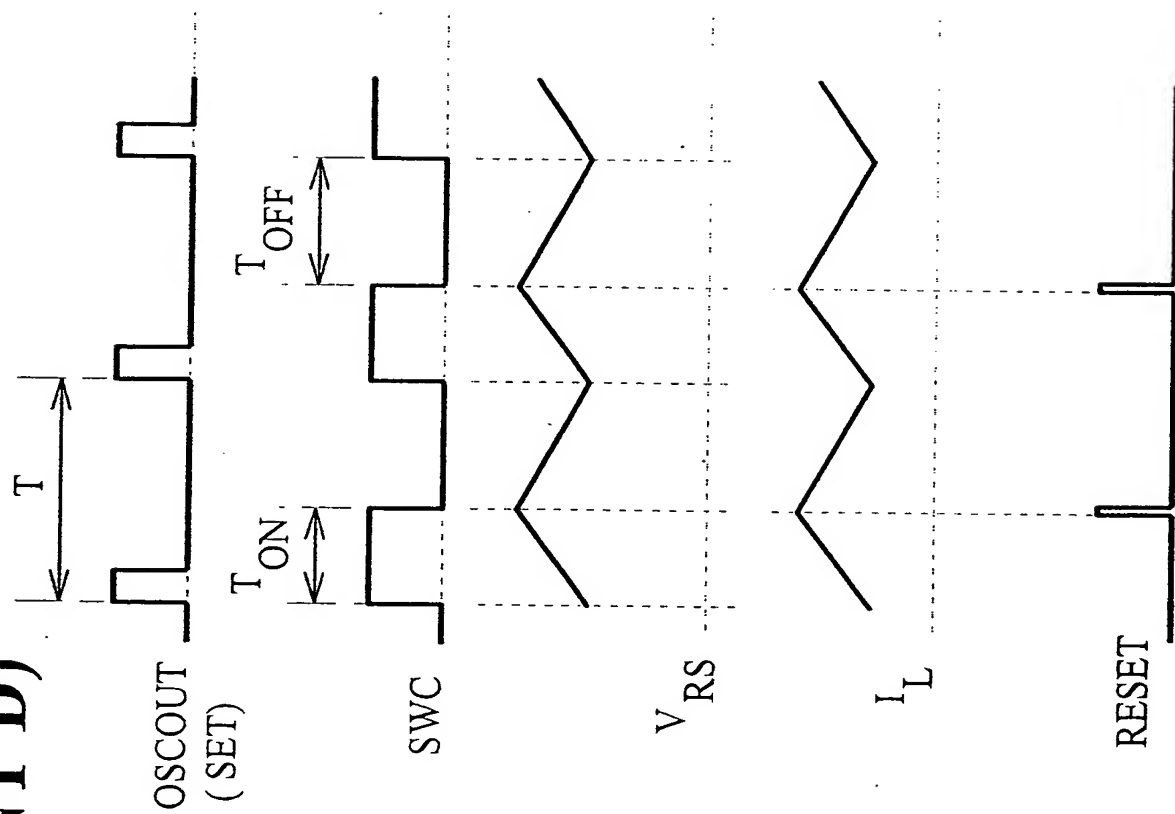


Fig. 6B (CONT'D)



- 1) $V_S = V_{DC} - V_A$
- 2) $V_L = V_A - V_M$
- 3) $V_M \cong I_M \cdot R_M + V_{emf}$
- 4) $V_{emf} = K_v \cdot \omega_M$
- 5) $I_S = I_L$
- 6) $I_L = I_C + I_M$
- 7) $I_L = V_{RS} / R_S$
- 8) $V_M = V_C + I_C \cdot R_{ESR}$
- 9) $T = T_{ON} + T_{OFF}$
- 10) $I_L = I_{AVERAGE} + I_L(t)$
- 11) $I_{LPK} = I_{AVERAGE} + (\Delta I_L / 2)$
- 12) $I_{LMIN} = I_{AVERAGE} - (\Delta I_L / 2)$
- 13) $I_M = I_{AVERAGE}$
- 14) $I_C = I_L(t)$
- 15)
$$I_L(t) = \frac{1}{L} \int V_L(t) dt$$
- 16)
$$I_L = \frac{V_L}{L} t = \frac{V_A - V_M}{L} t$$
- 17)
$$I_L = \frac{V_{DC} - V_S - V_M}{L} t$$

FIG. 6C-1

$$18) \quad \Delta I_L = \frac{V_{DC} - V_S - V_M}{L} T_{ON}$$

$$19) \quad |\Delta I_L| = \frac{V_M + V_{FD}}{L} T_{OFF}$$

$$20) \quad T_{ON} \frac{V_{DC} - V_S - V_M}{L} = \frac{V_M + V_{FD}}{L} T_{OFF}$$

$$21) \quad T_{ON} (V_{DC} - V_M) \cong V_M T_{OFF}$$

$$22) \quad V_M \cong V_{DC} \frac{T_{ON}}{T_{ON} + T_{OFF}} = V_{DC} \frac{T_{ON}}{T}$$

$$23) \quad \Delta Q = \frac{1}{2} \frac{T}{2} \frac{\Delta I_L}{2}$$

$$24) \quad \Delta V_{CC} = \frac{\Delta Q}{C} = \frac{\Delta I_L}{f \cdot 8 \cdot C}$$

$$25) \quad \Delta V_C = \Delta V_{CC} + \Delta I_L R_{ESR}$$

$$26) \quad \Delta V_C \ll V_M$$

FIG. 6C-2

Fig. 6C-2 (CONT'D)

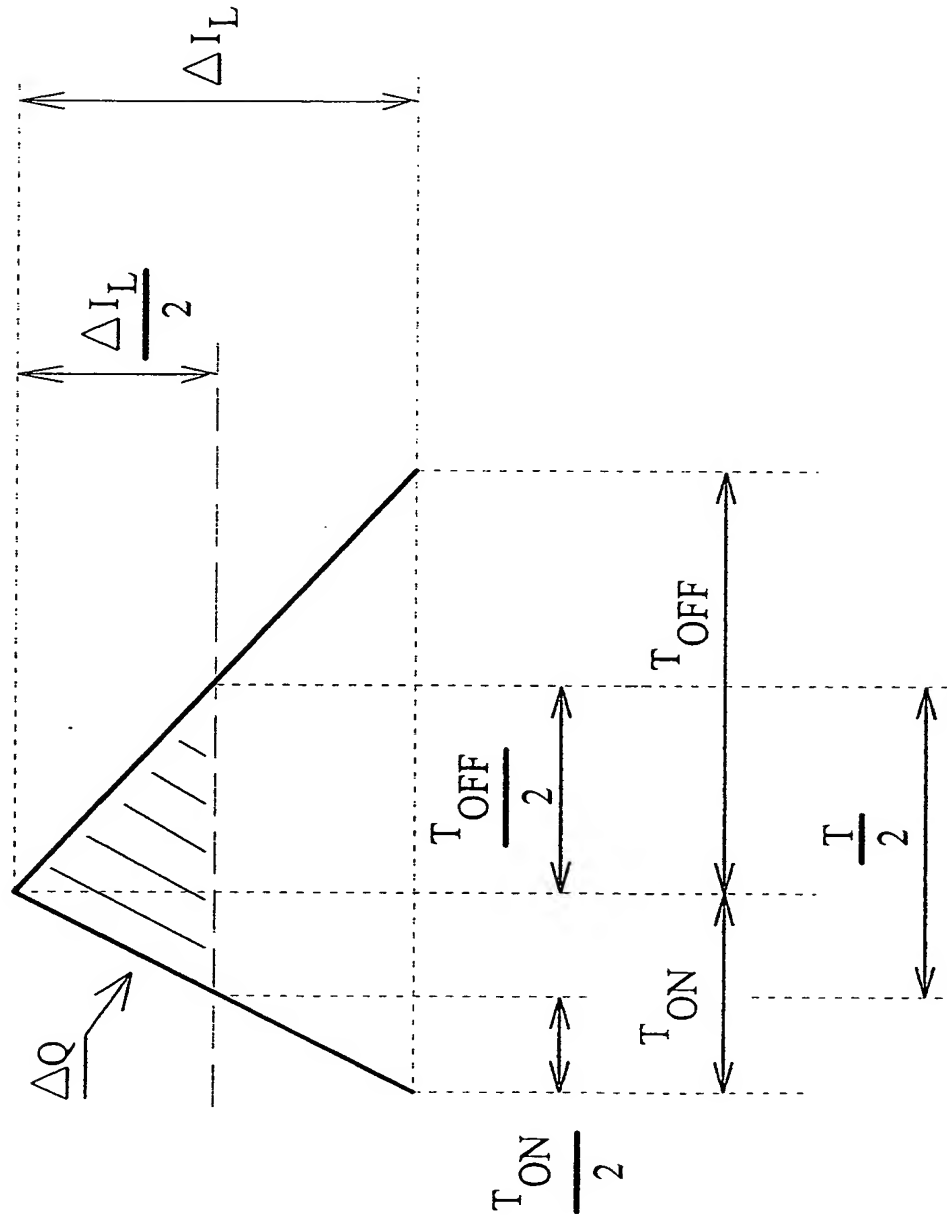


Fig. 7A

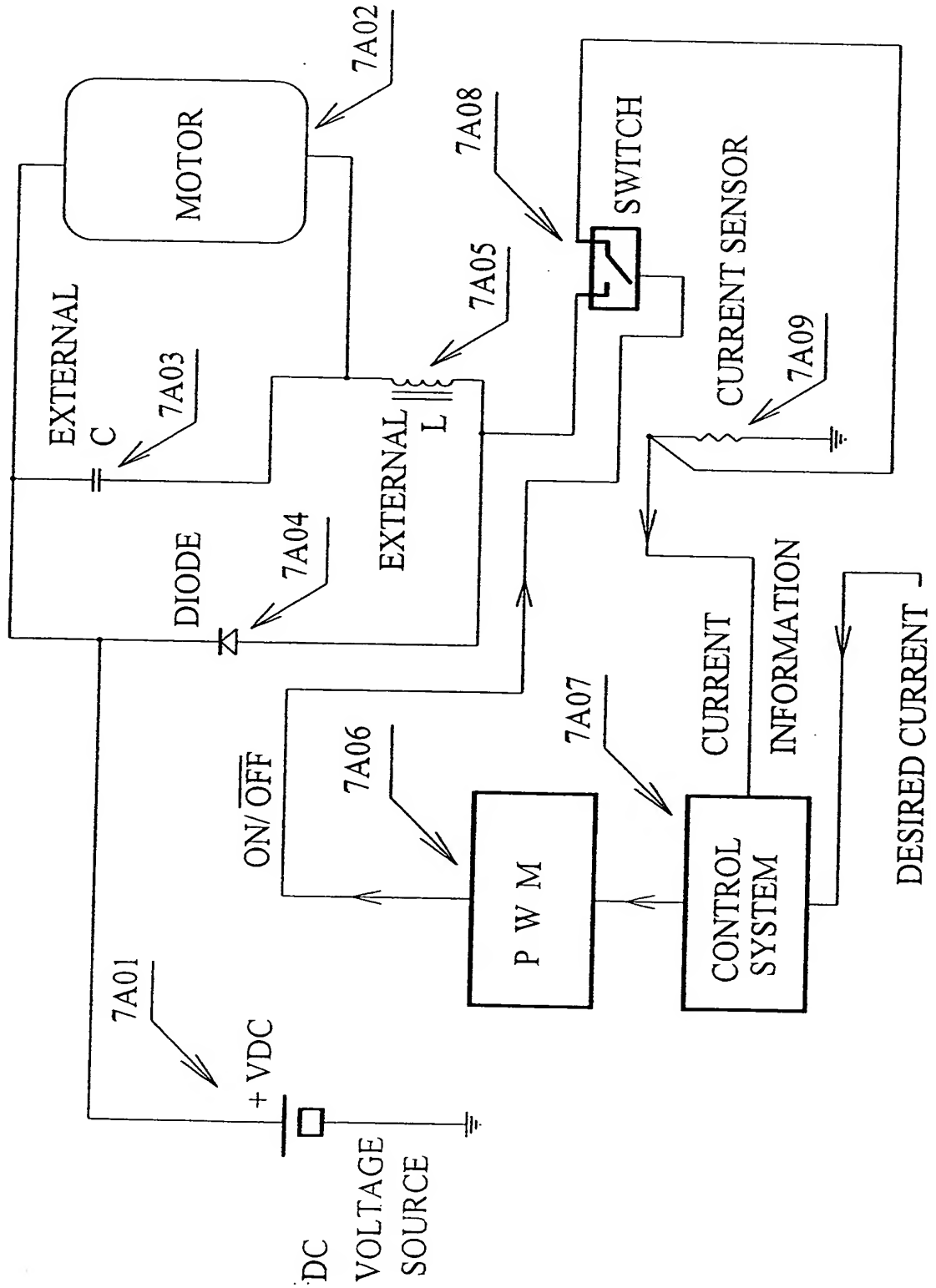
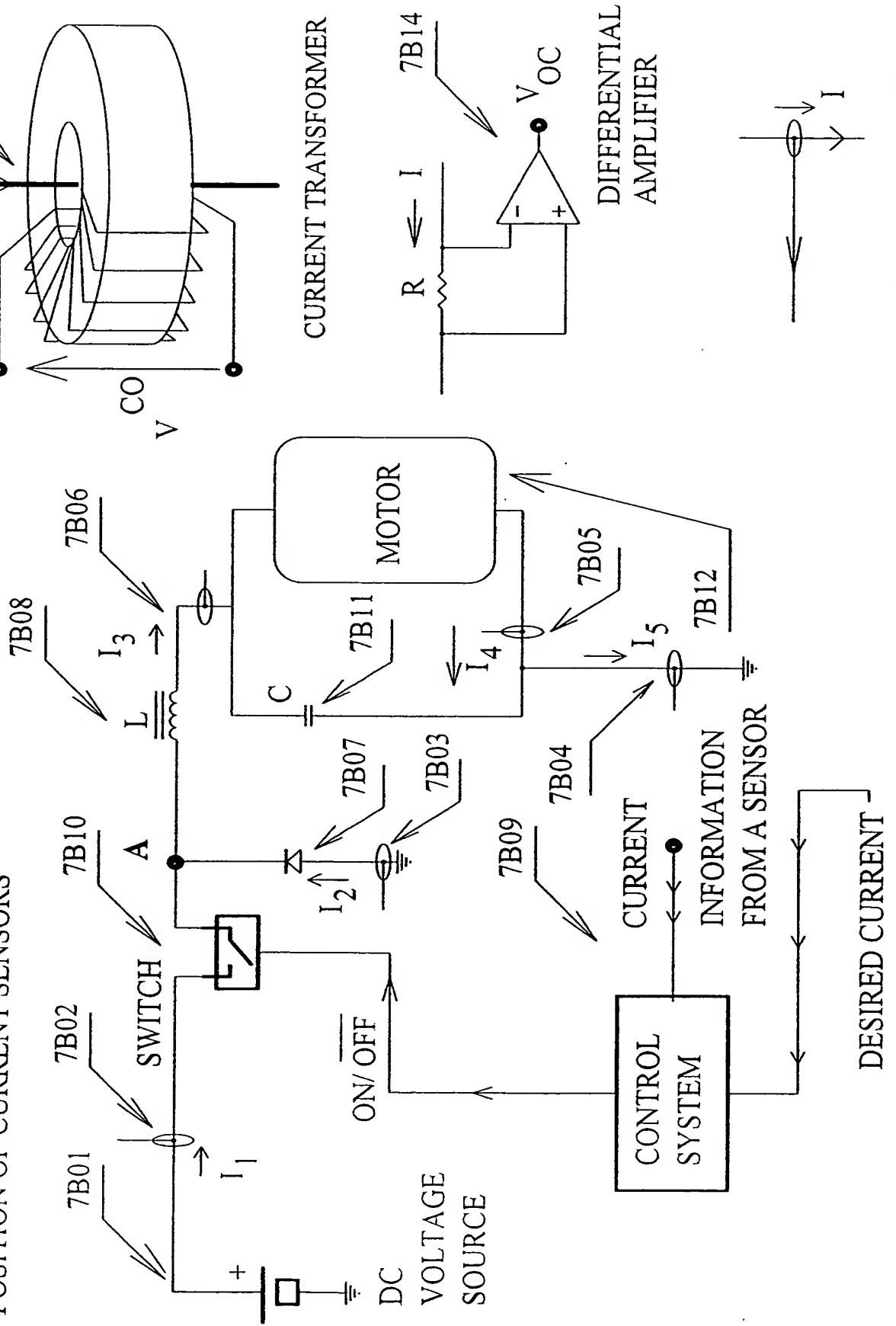


Fig. 7B

POSITION OF CURRENT SENSORS



CURRENT SENSOR SYMBOL

Fig. 7C

WITH SYNCHRONOUS RECTIFICATION

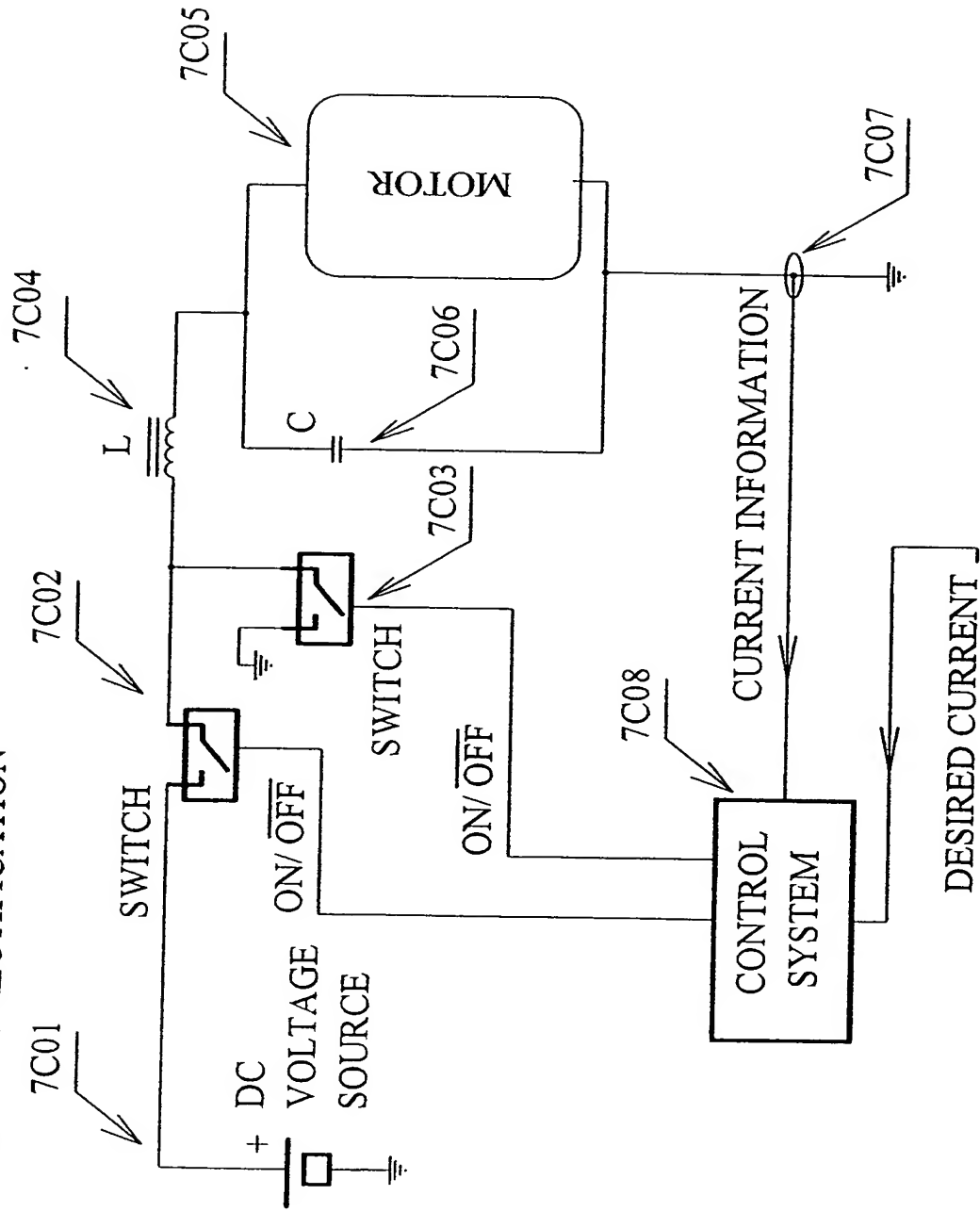


Fig. 7D

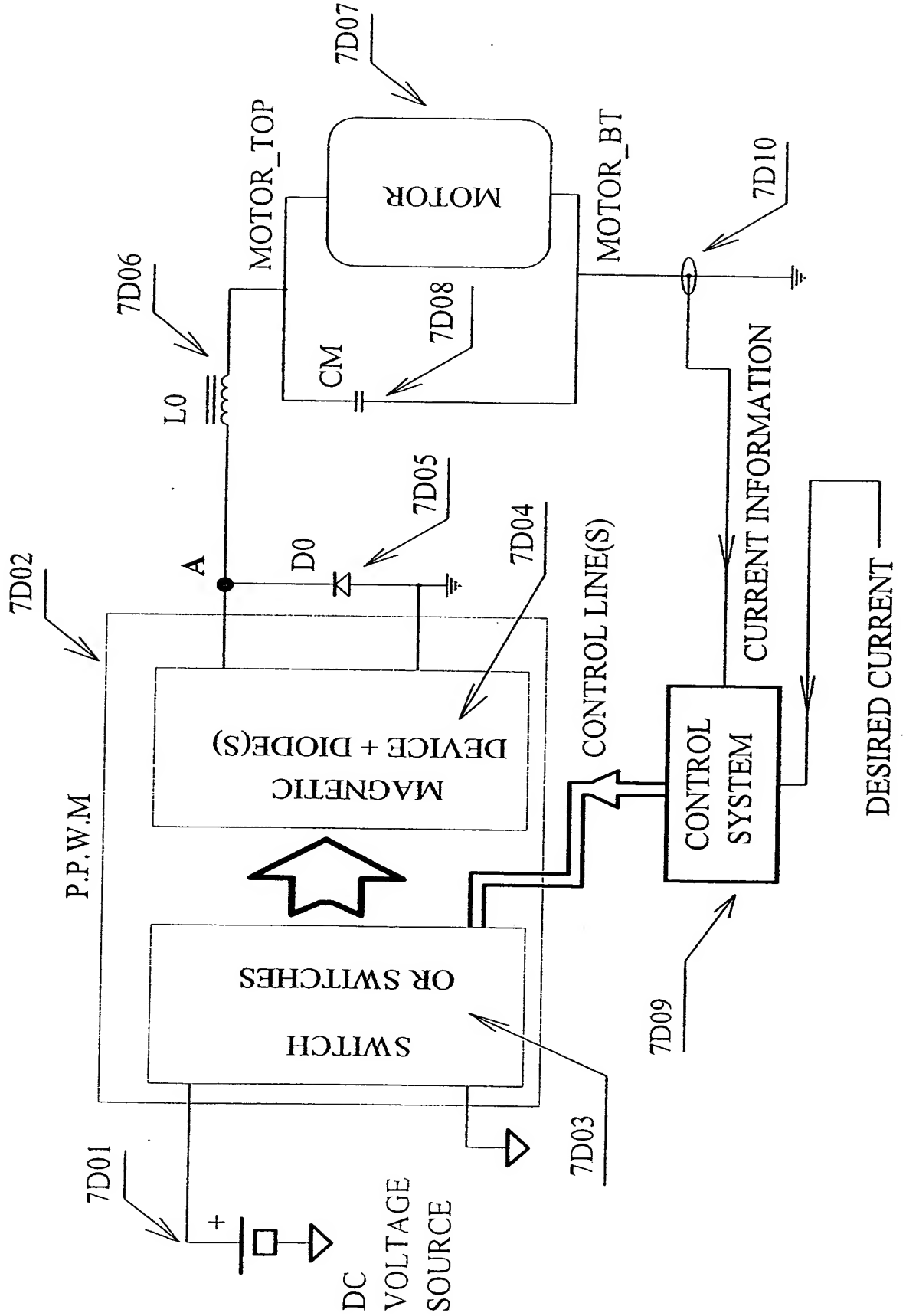


Fig. 7E

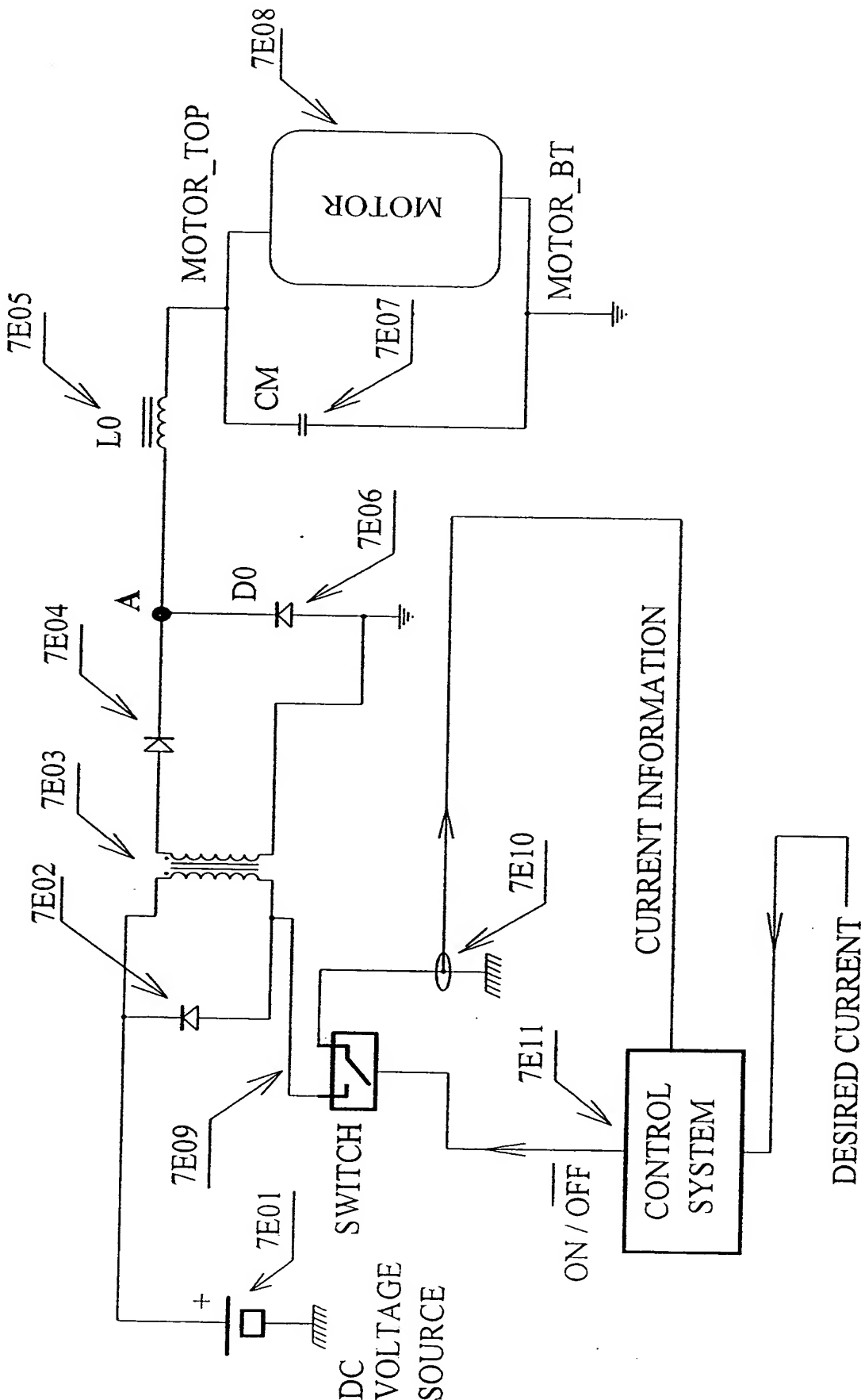


Fig. 7F

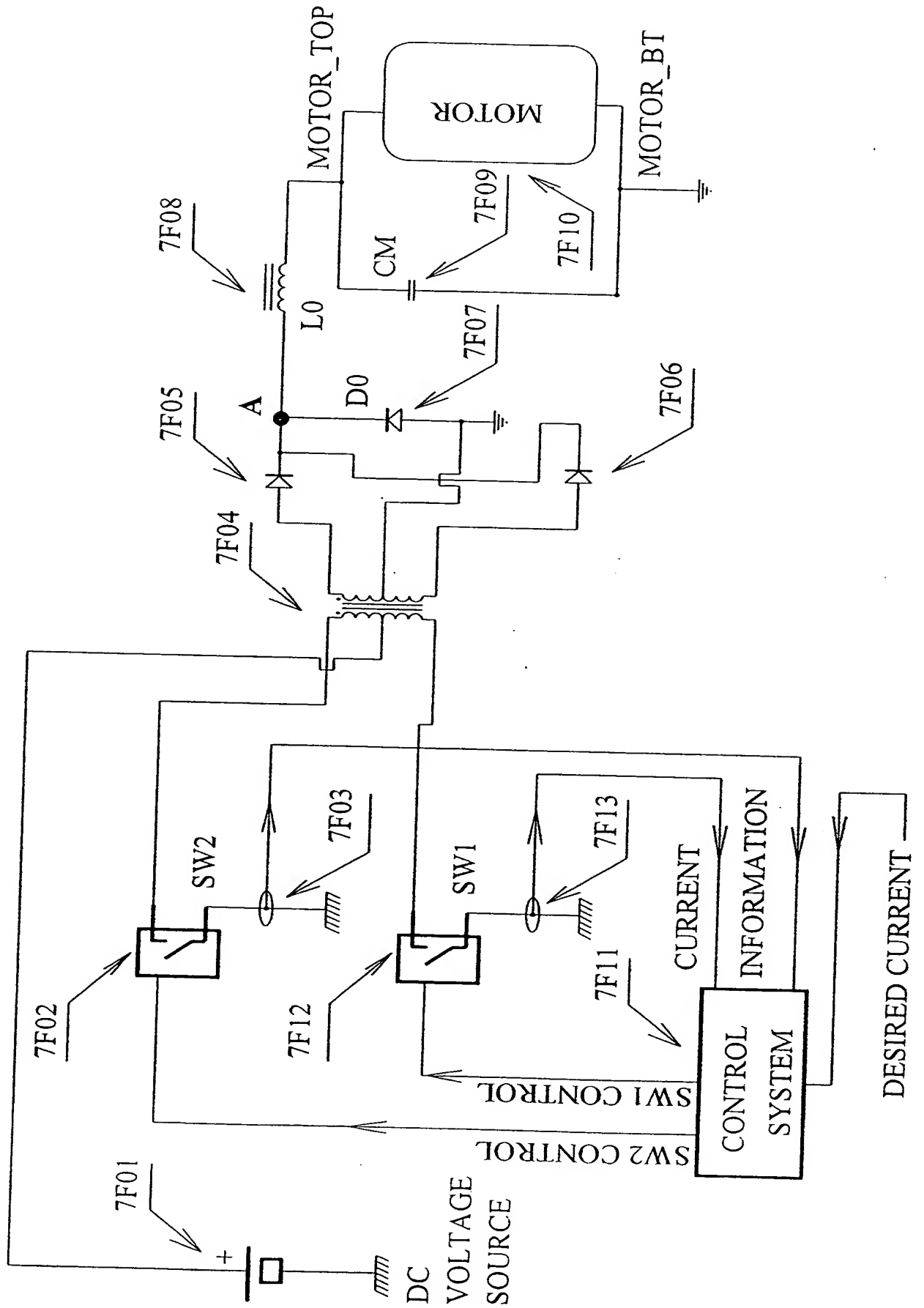


Fig. 7G

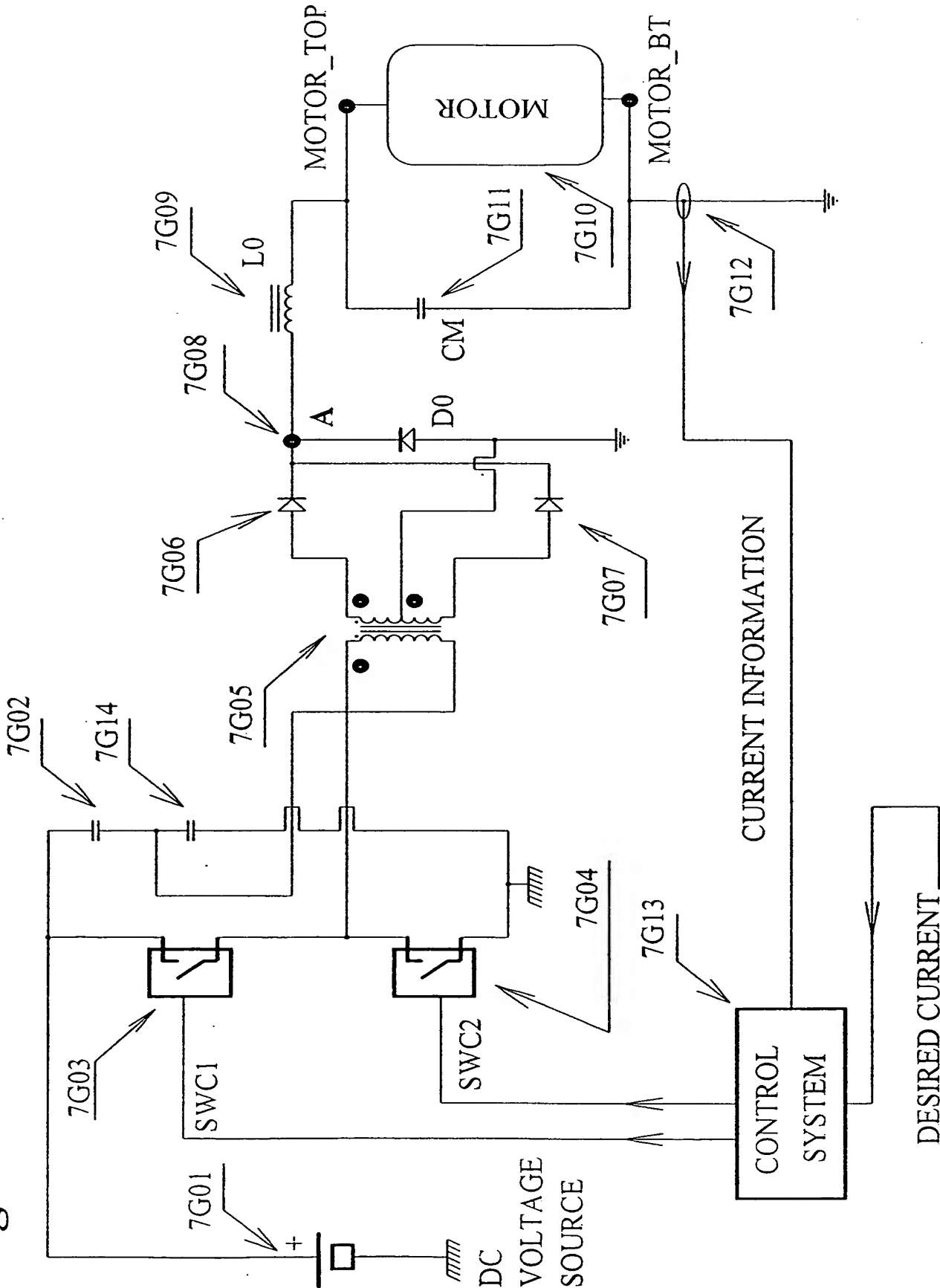
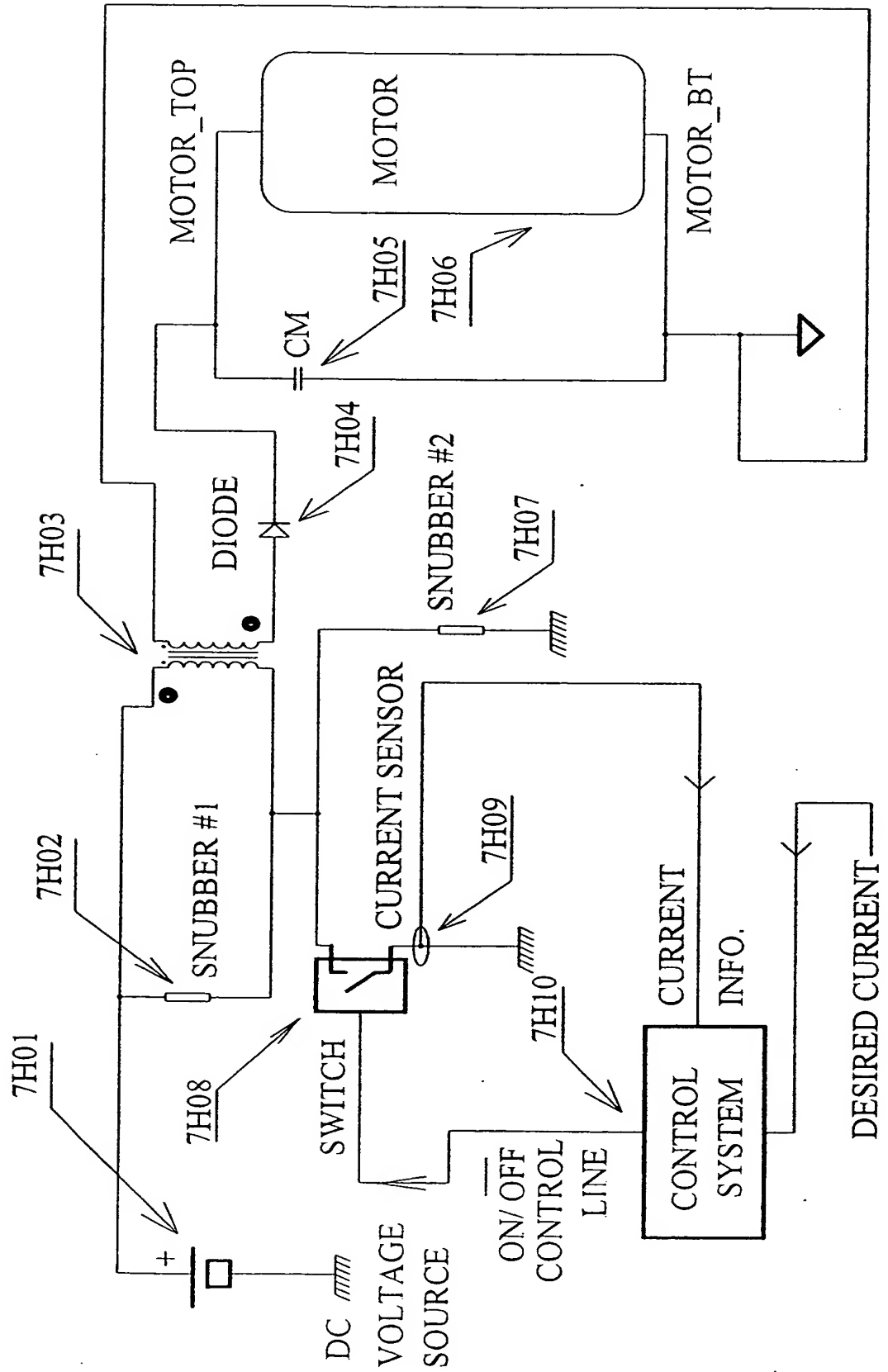


Fig. 7H



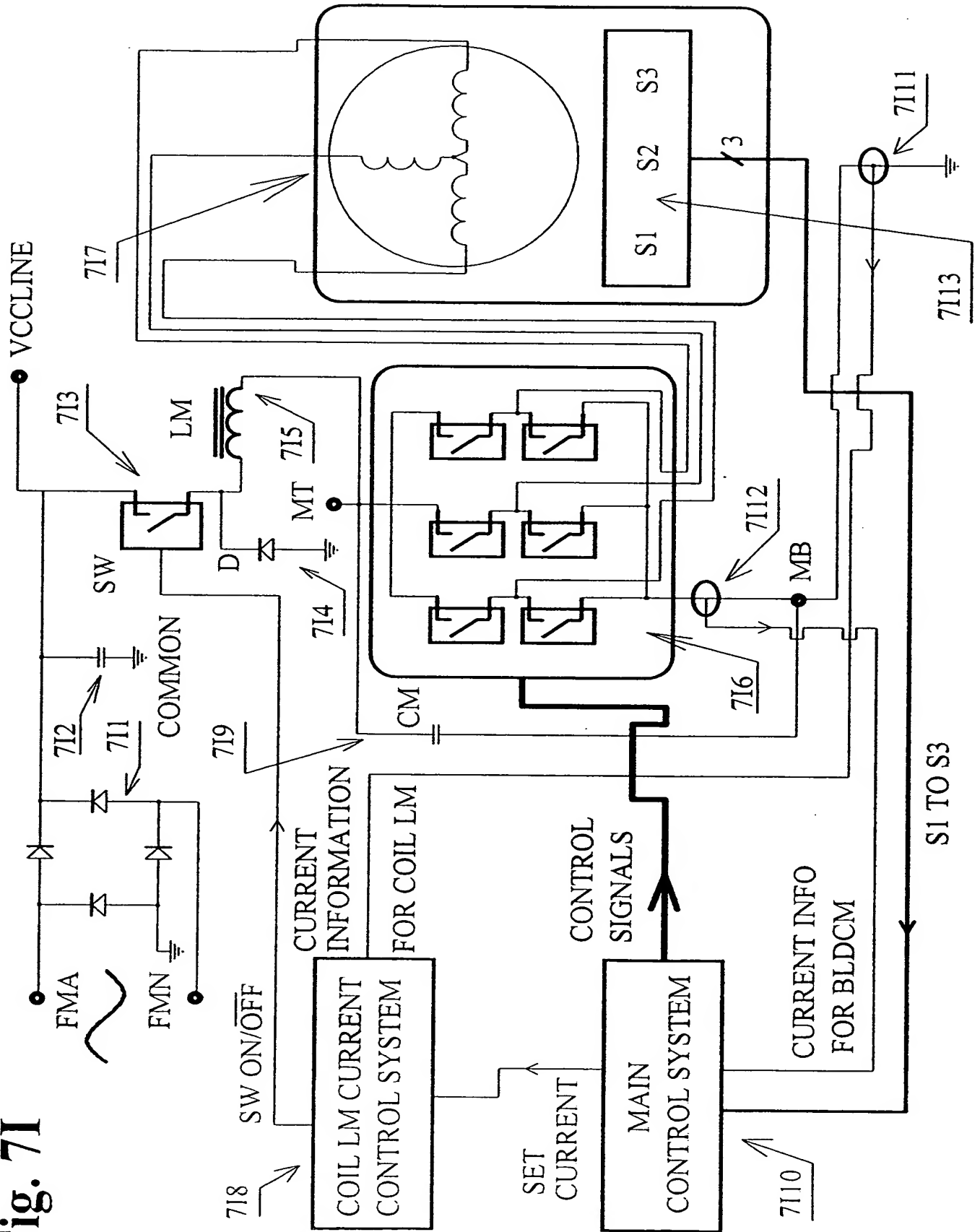


Fig. 7J

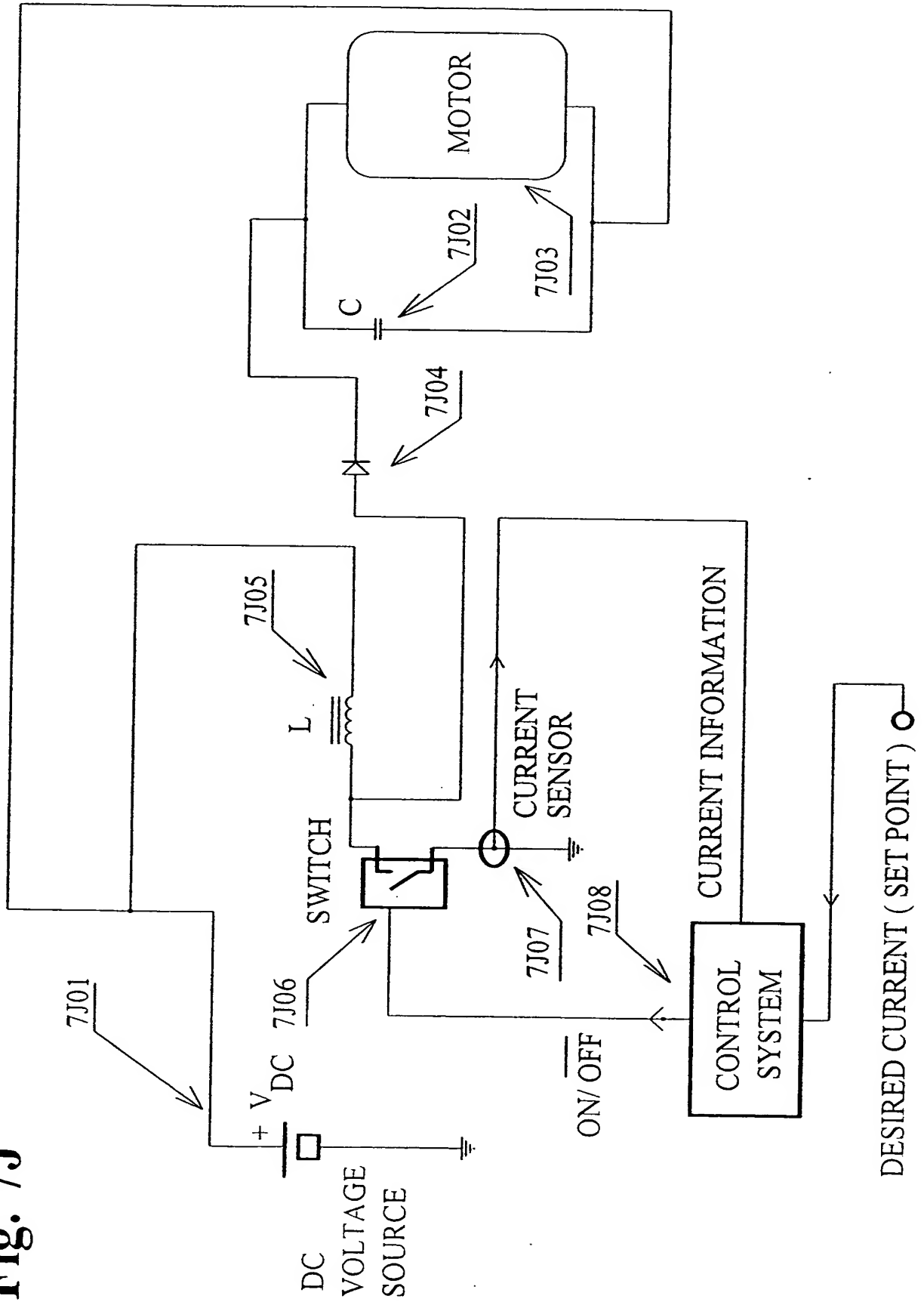


Fig. 7K

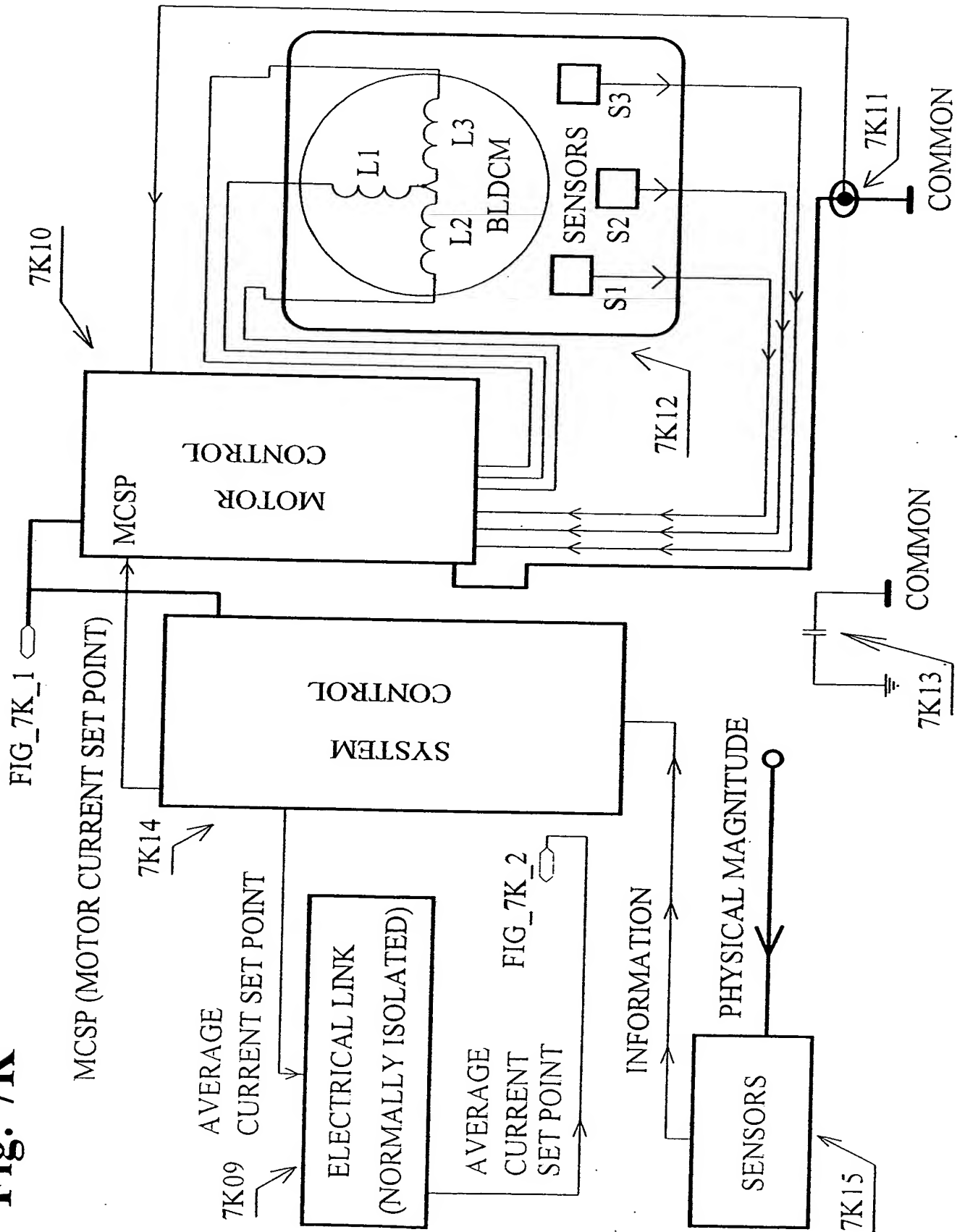


Fig. 7K (CONT'D)

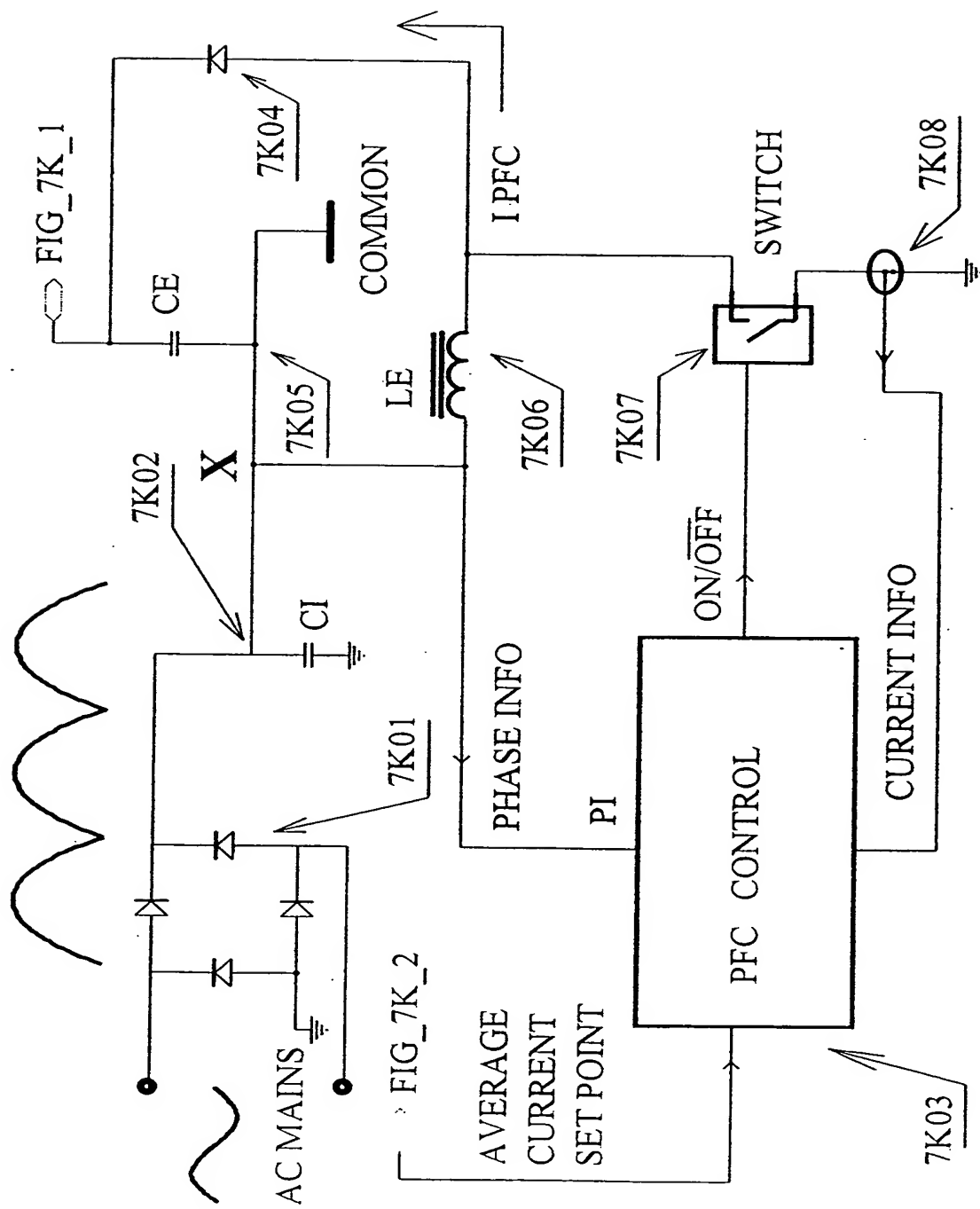


Fig. 7L

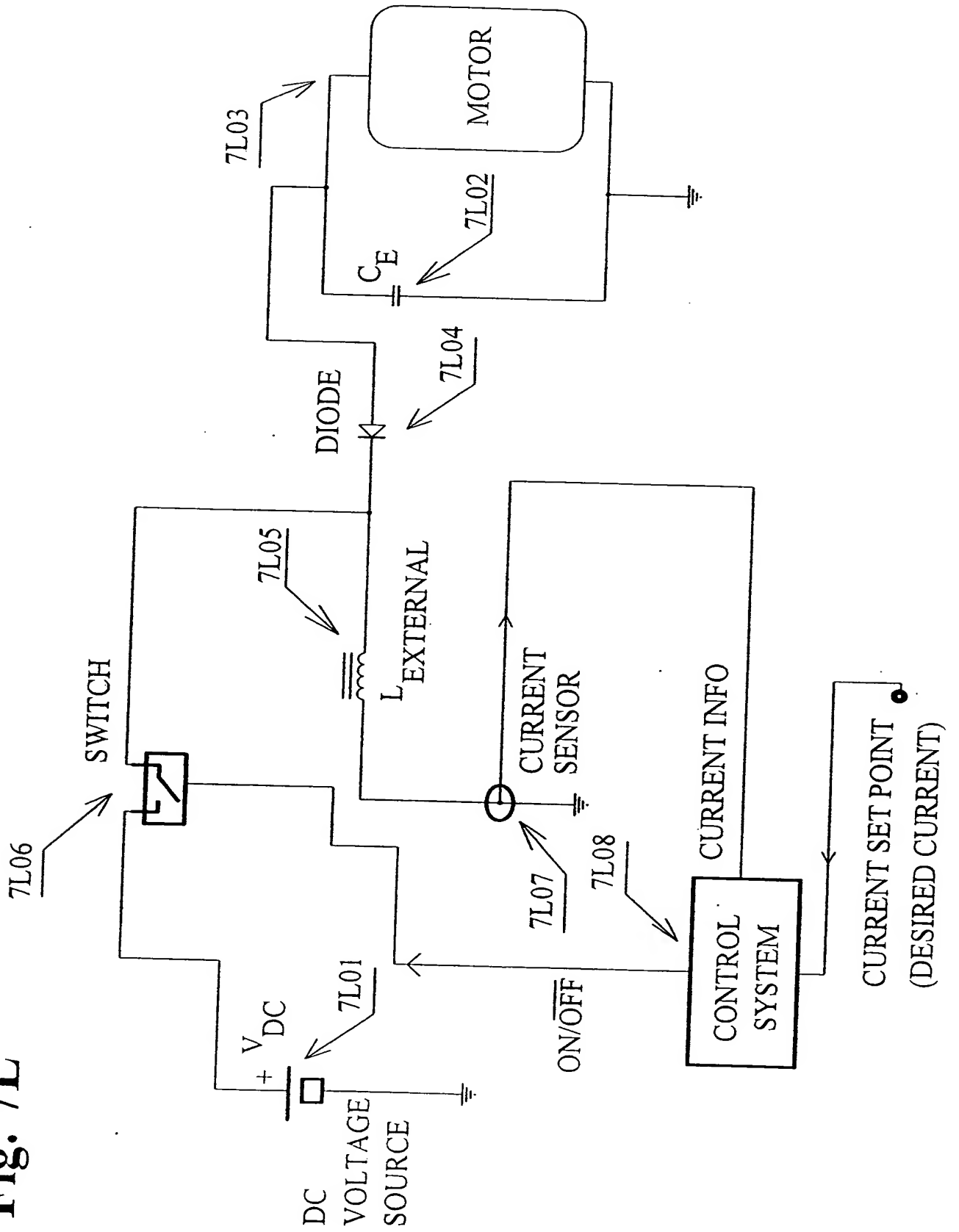


Fig. 8A

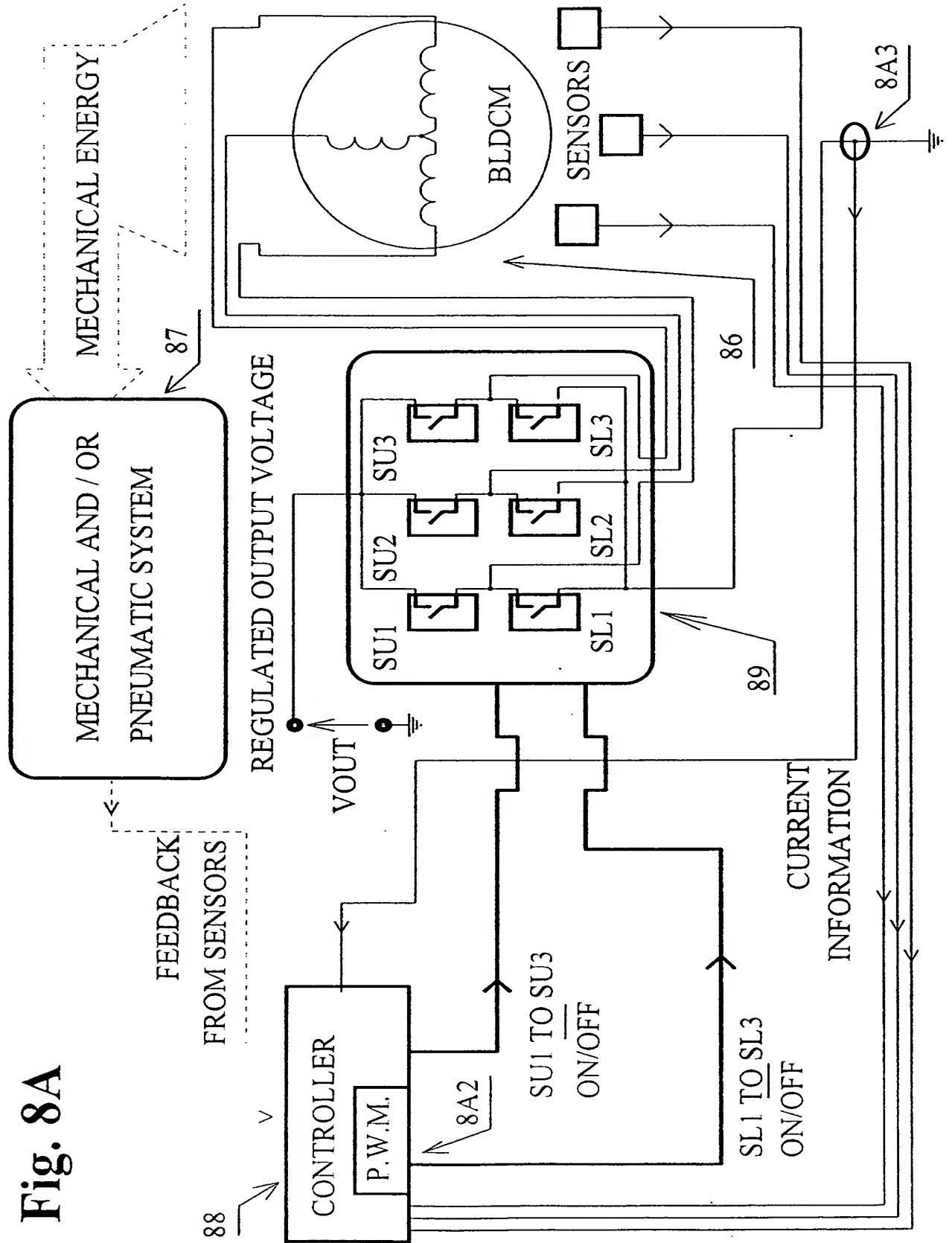


Fig. 8A (CONT'D)

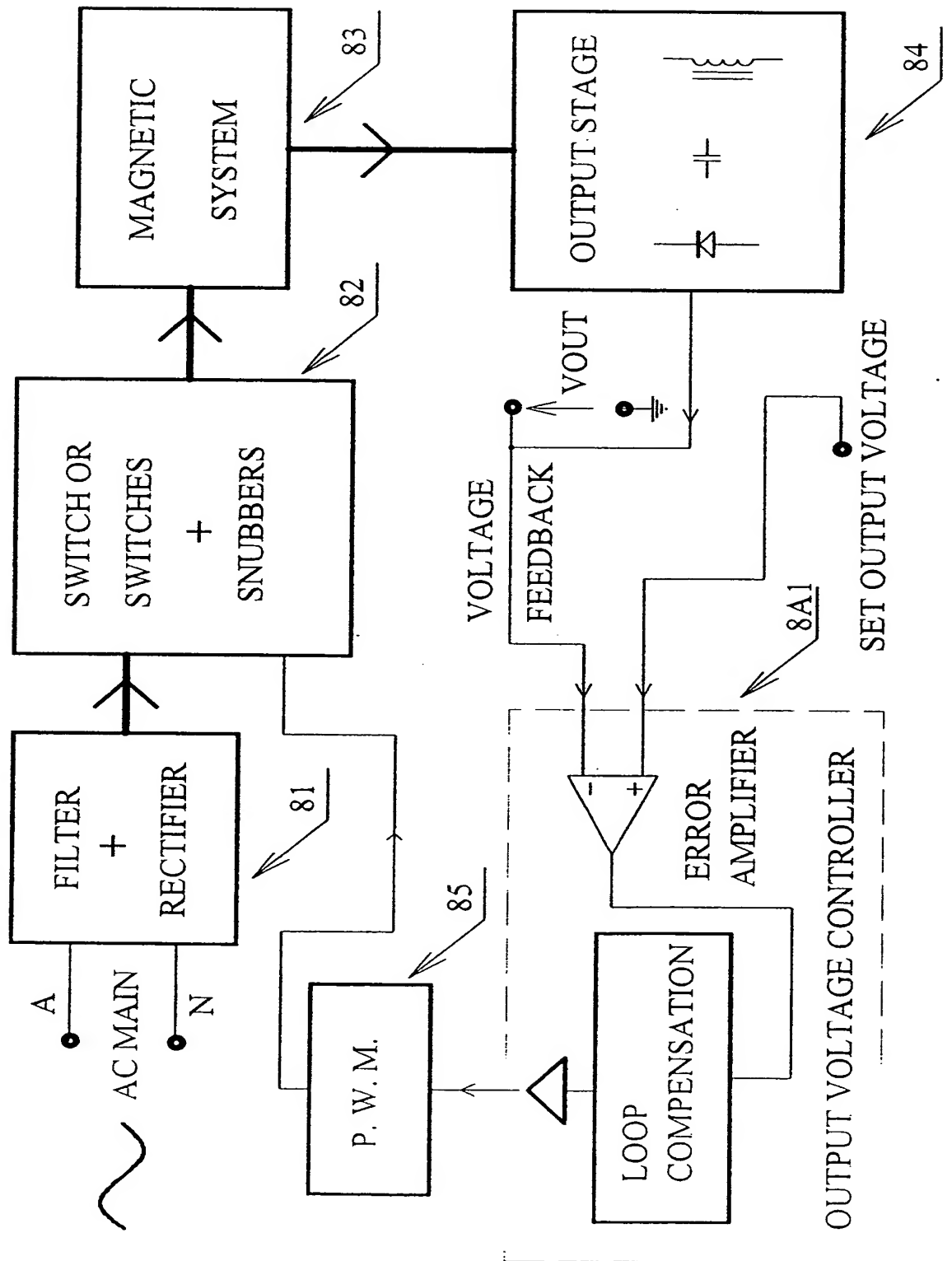


Fig. 8B

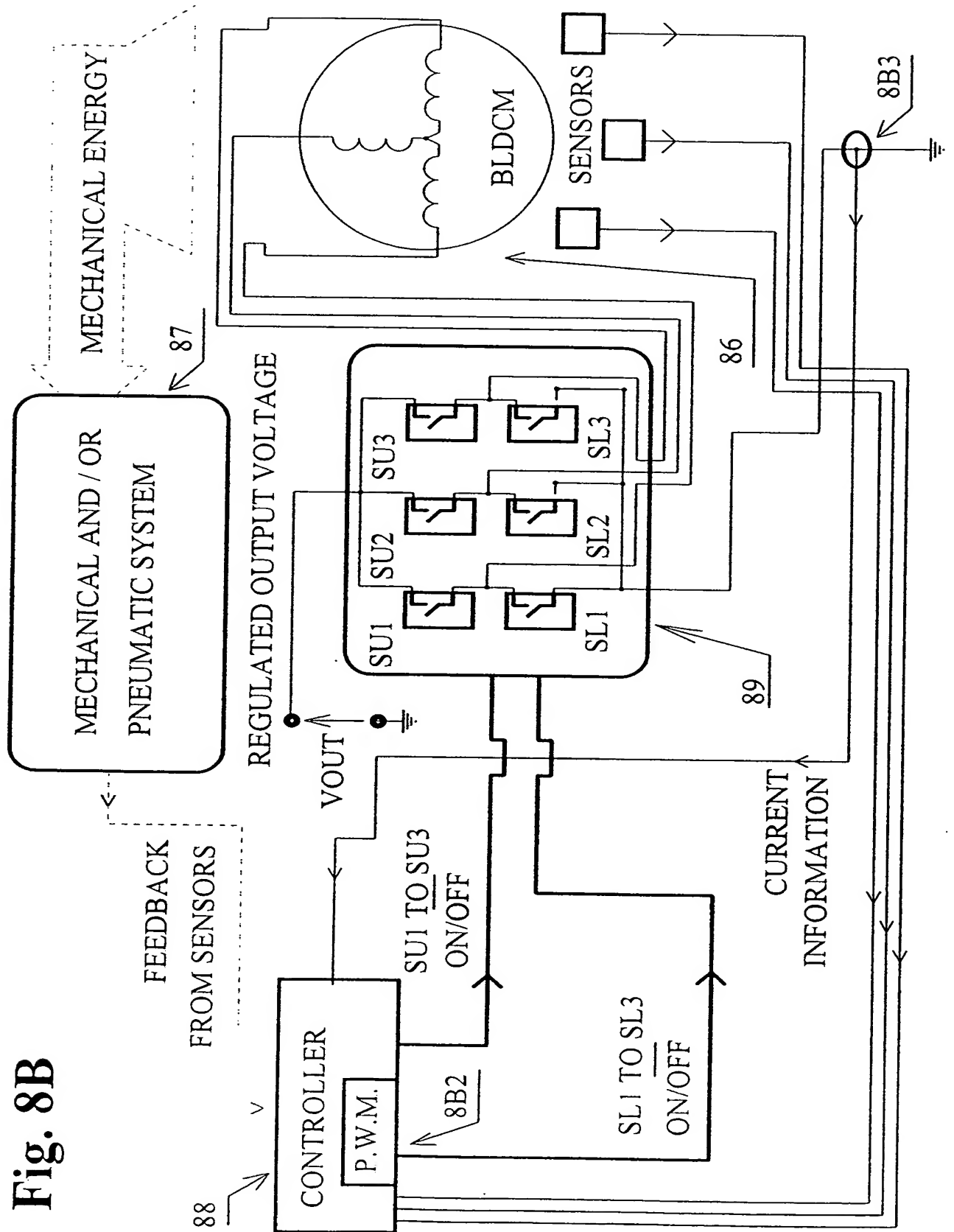


Fig. 8B (CONT'D)

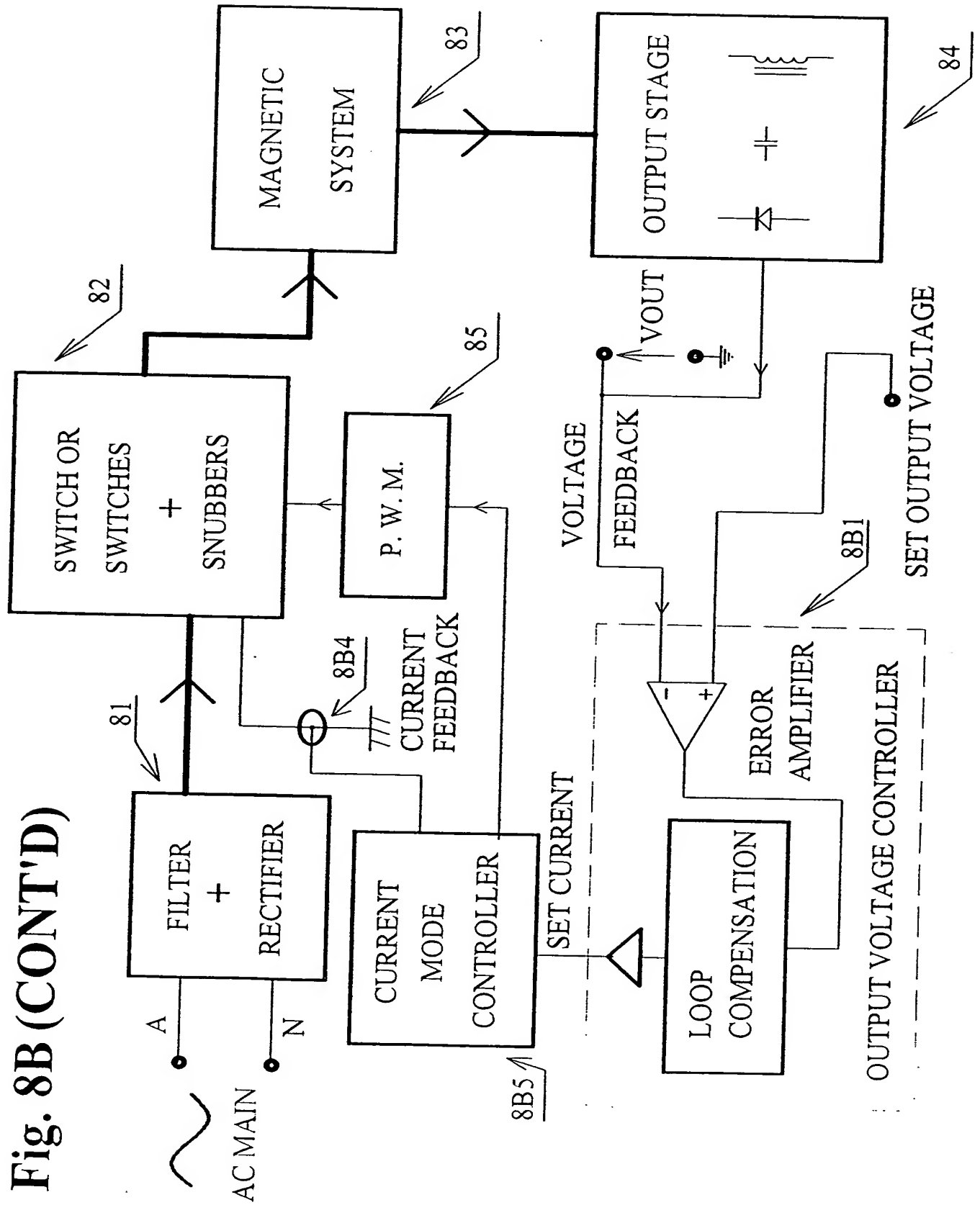


Fig. 8C

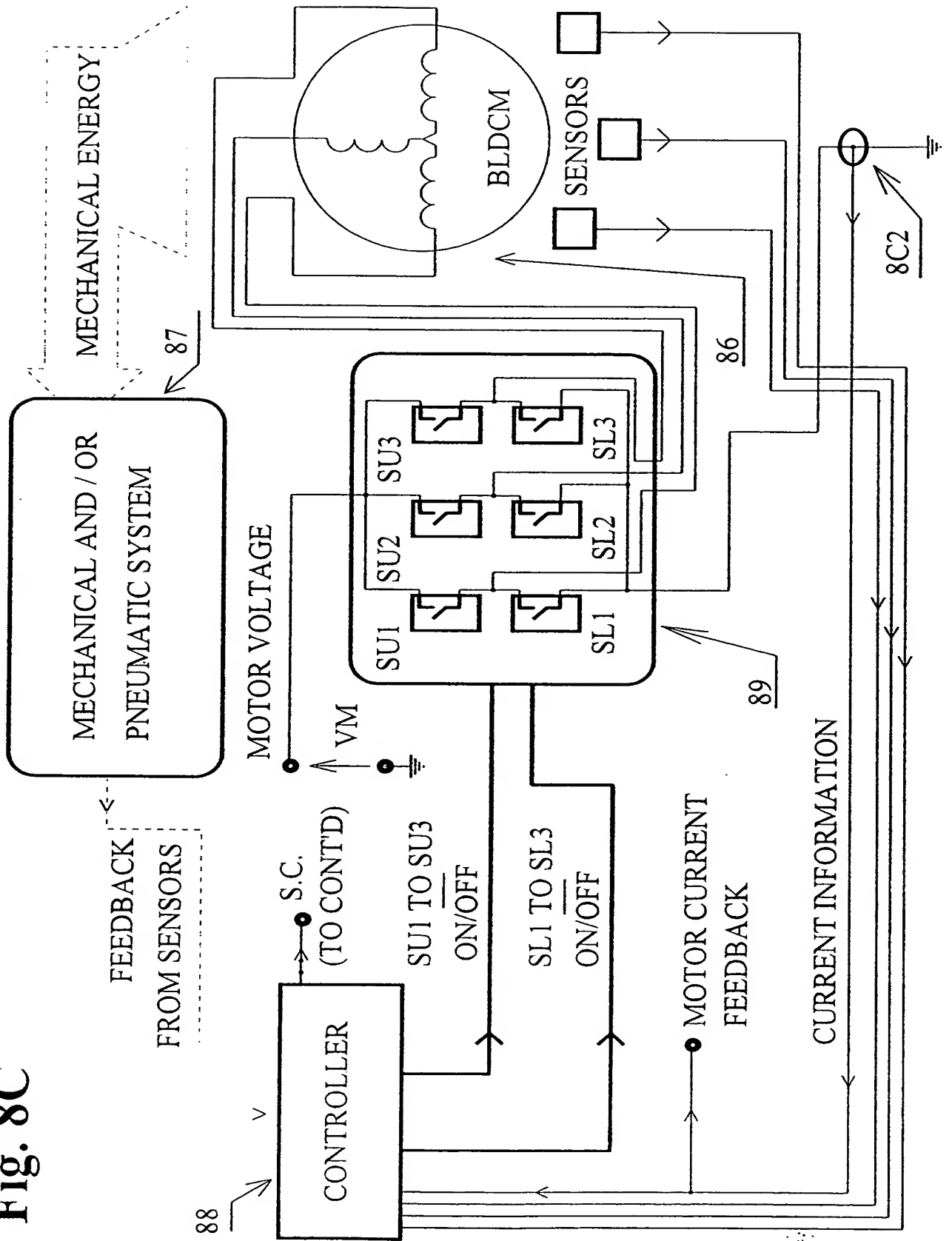


Fig. 8C (CONT'D)

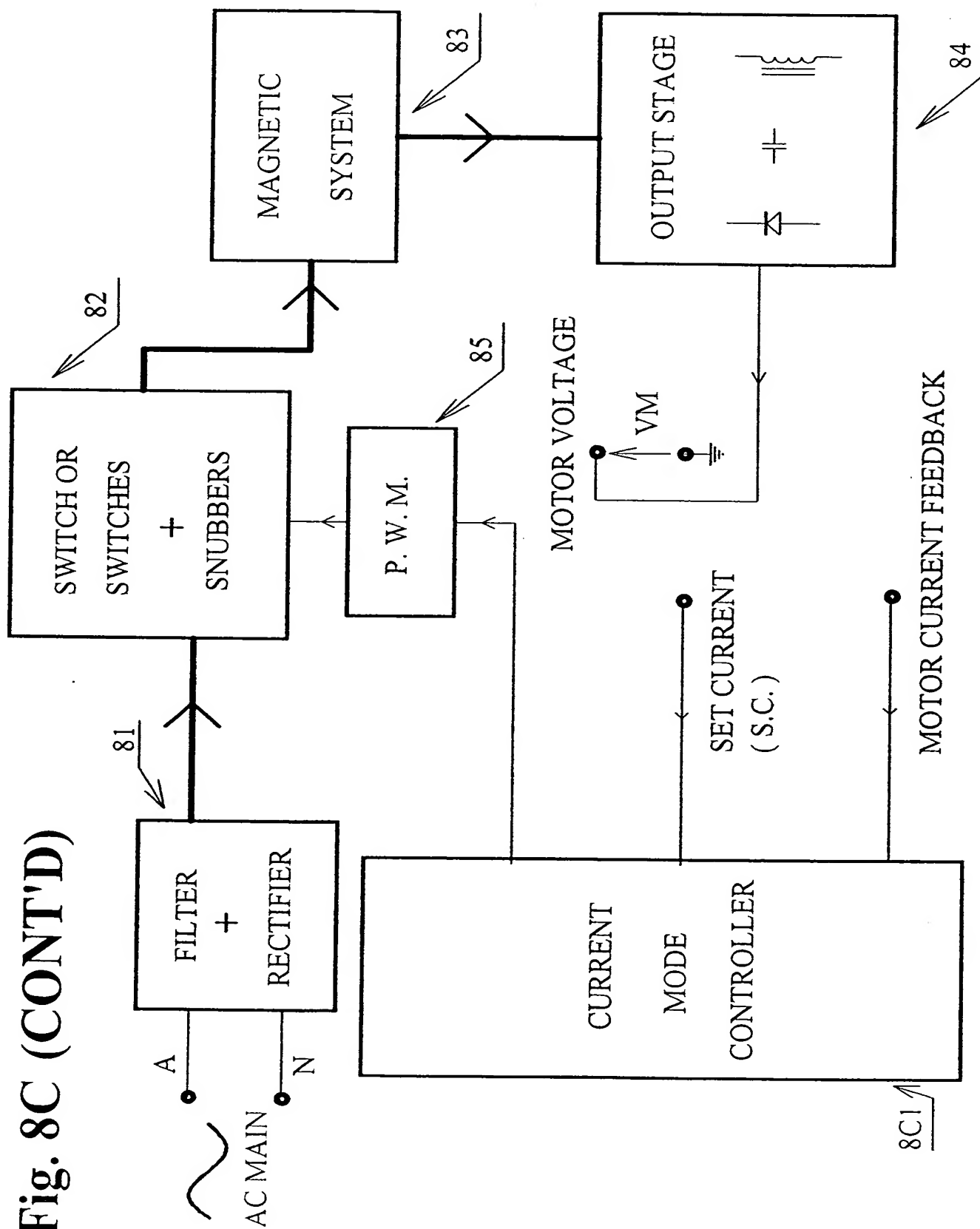


Fig. 9A

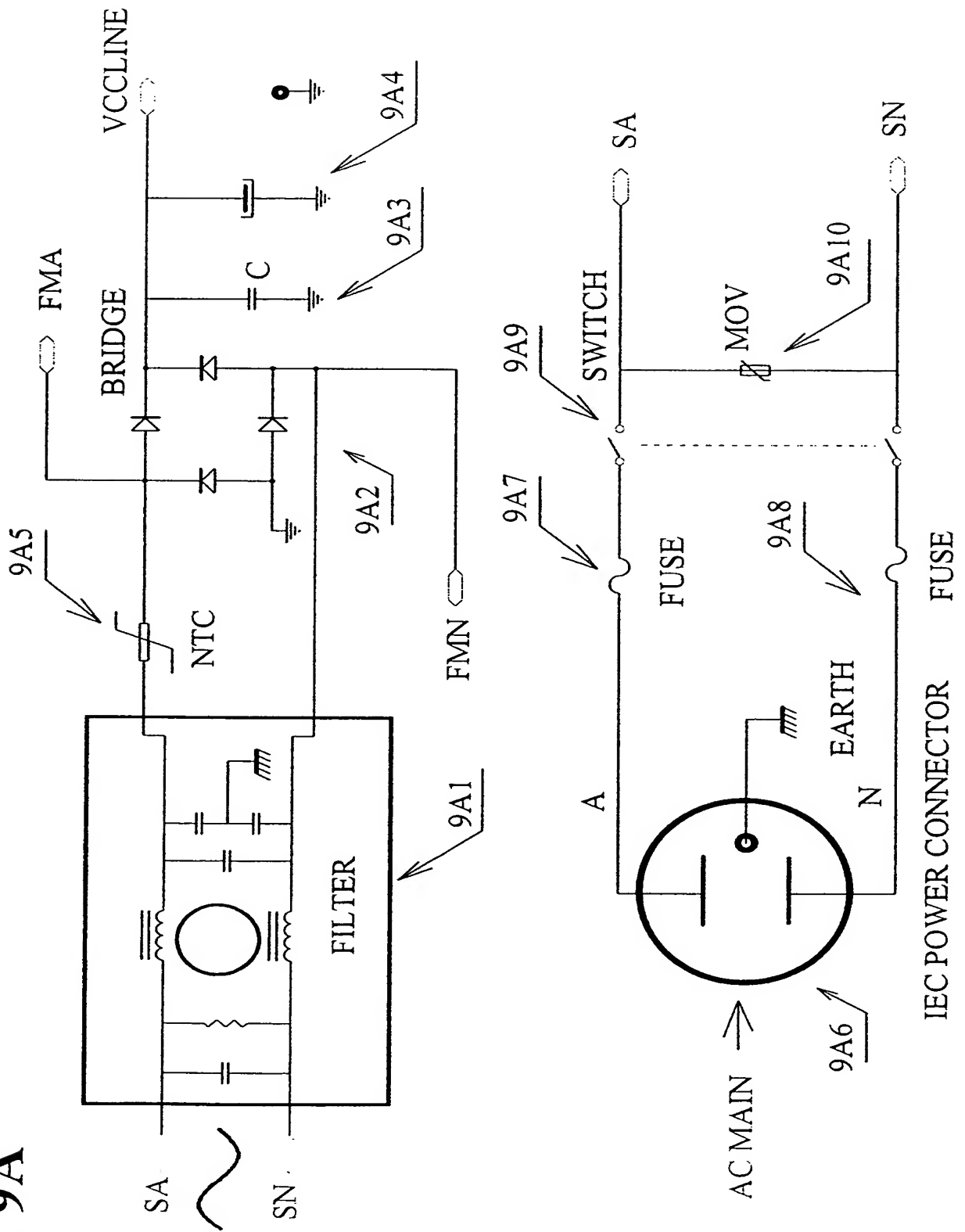


Fig. 9B

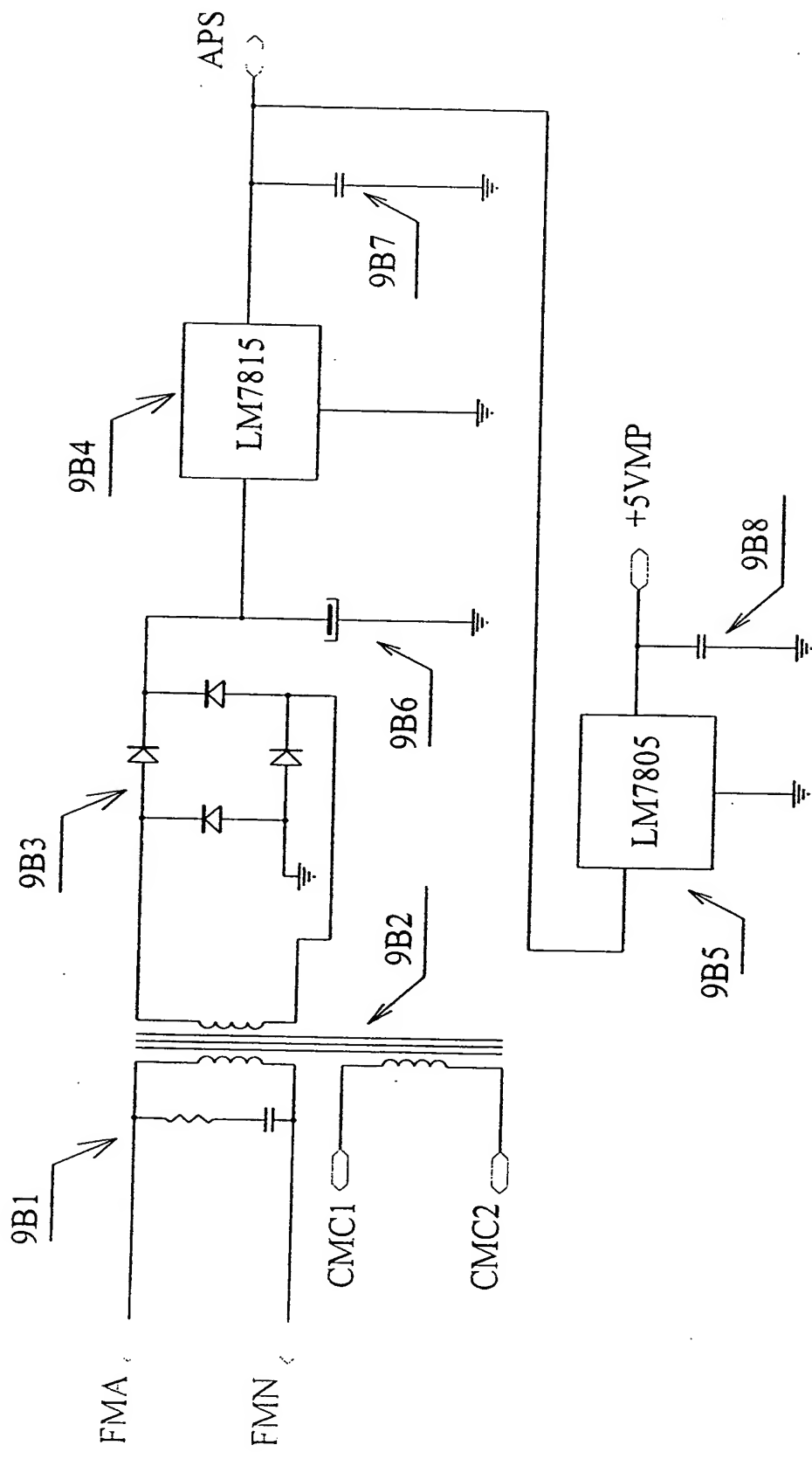


Fig. 9C

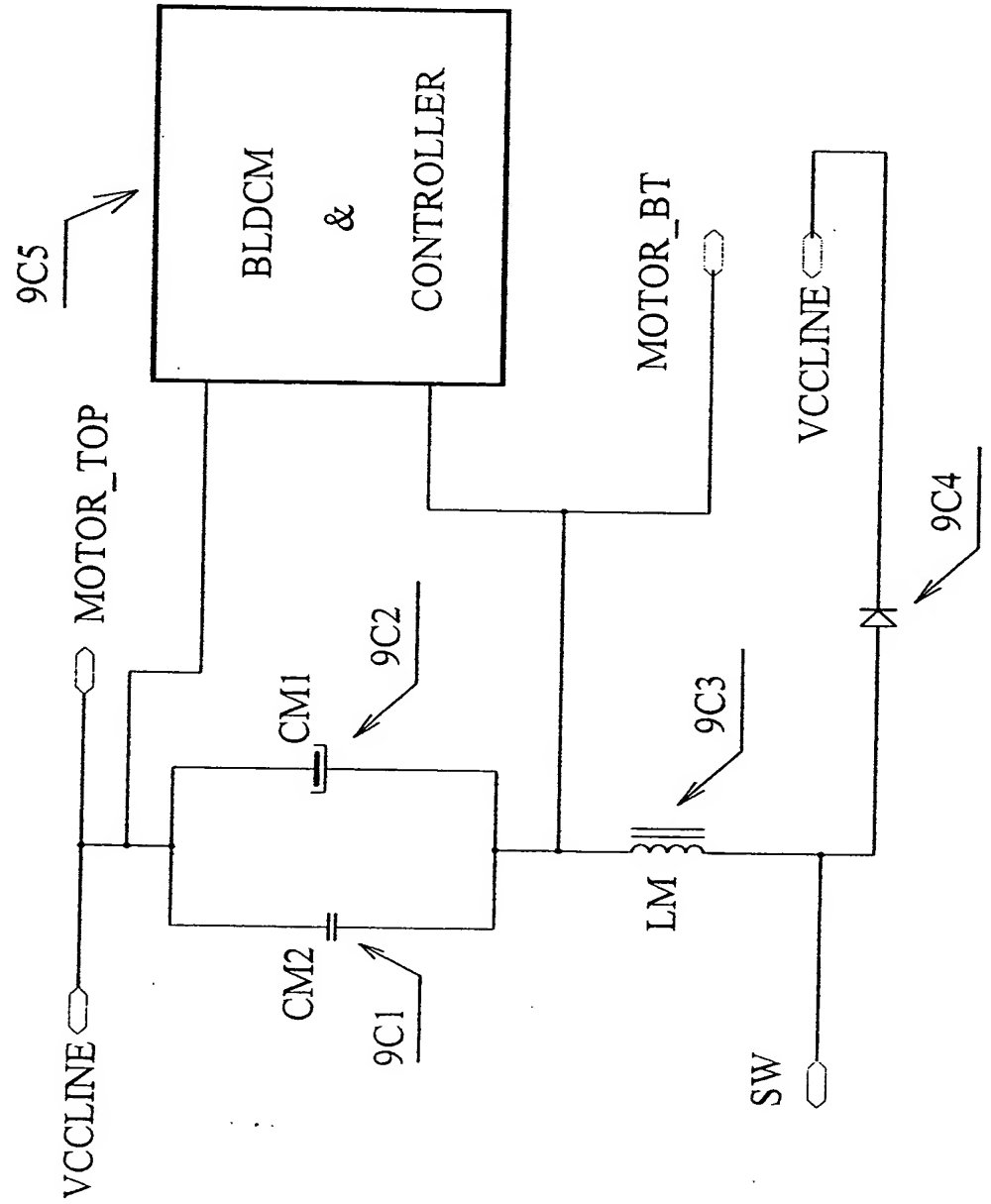
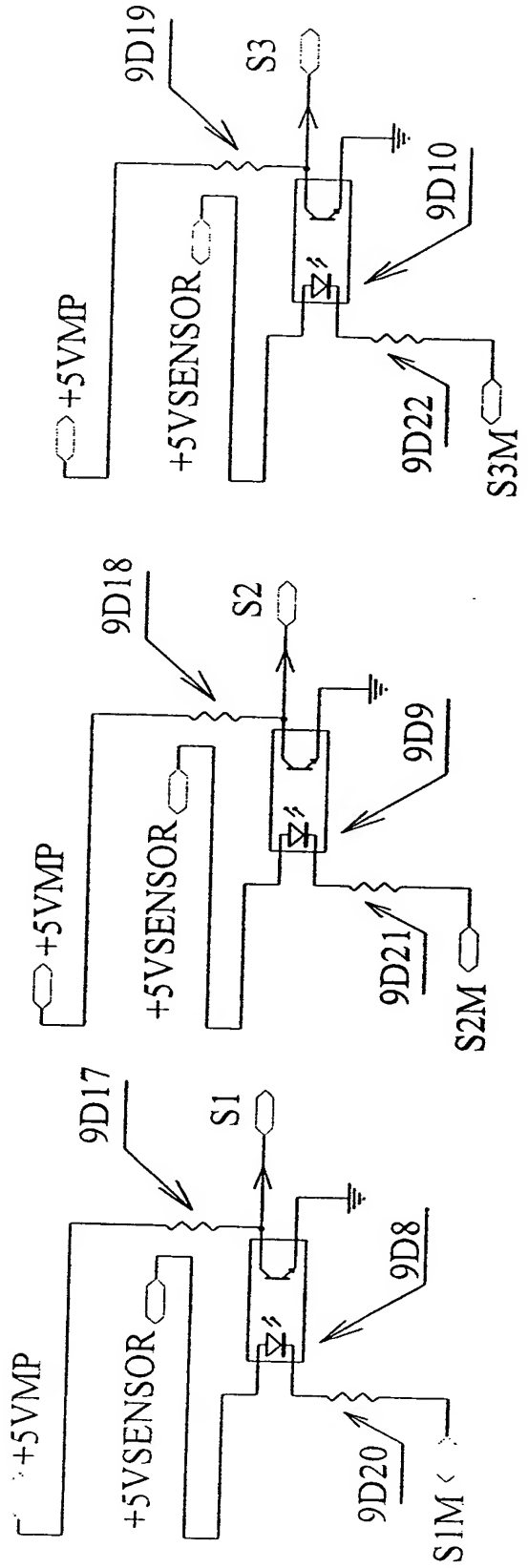
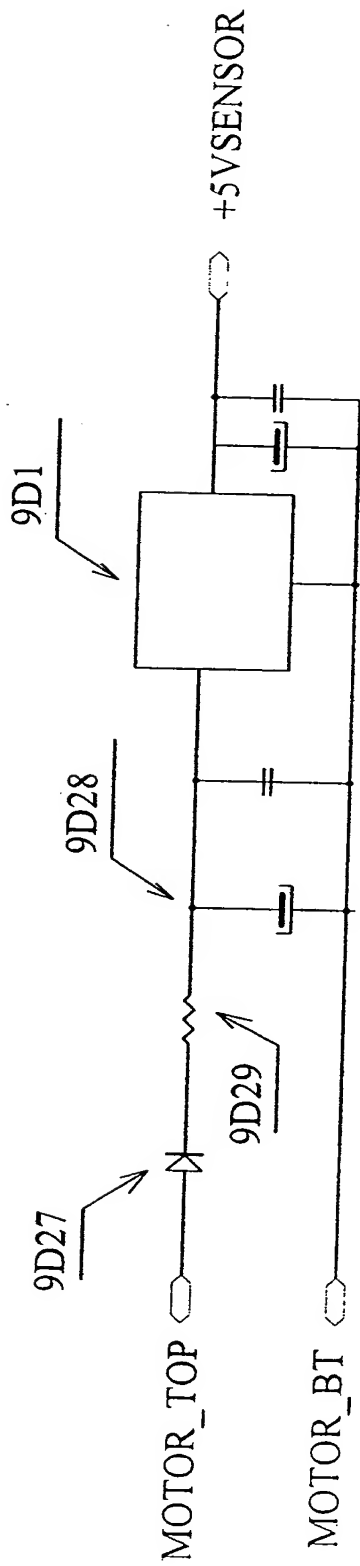


Fig. 9D



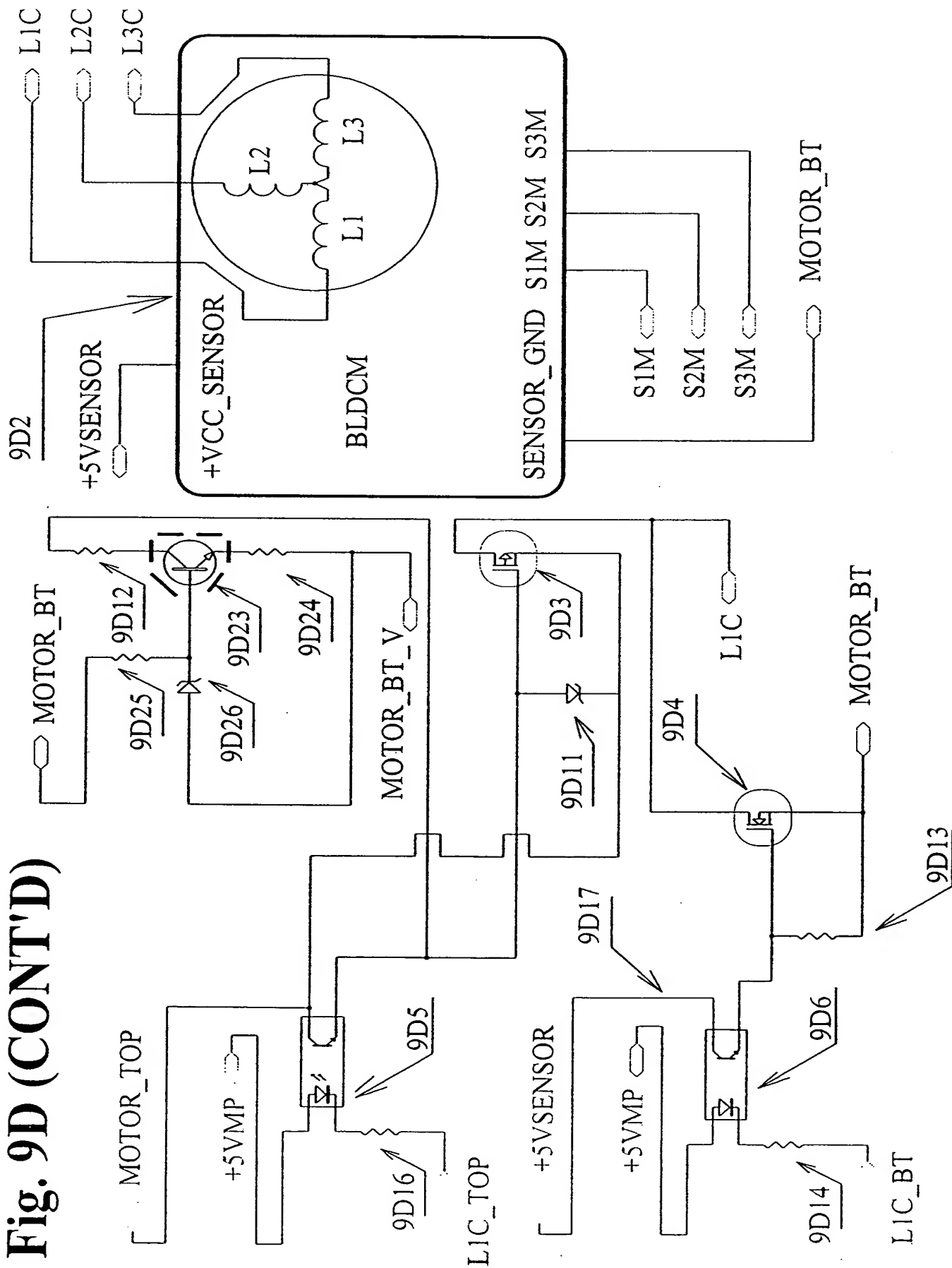


Fig. 9F

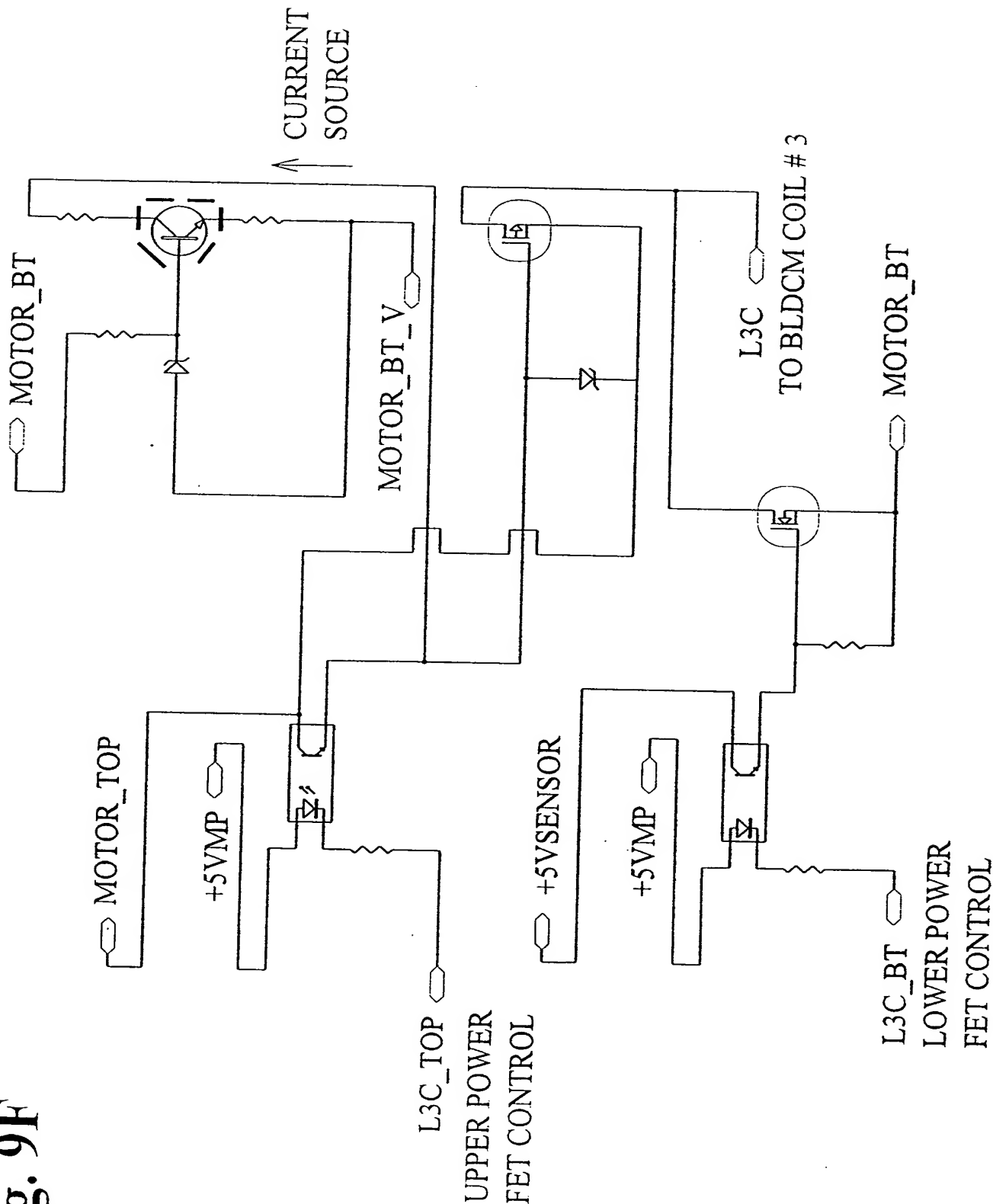


Fig. 9G

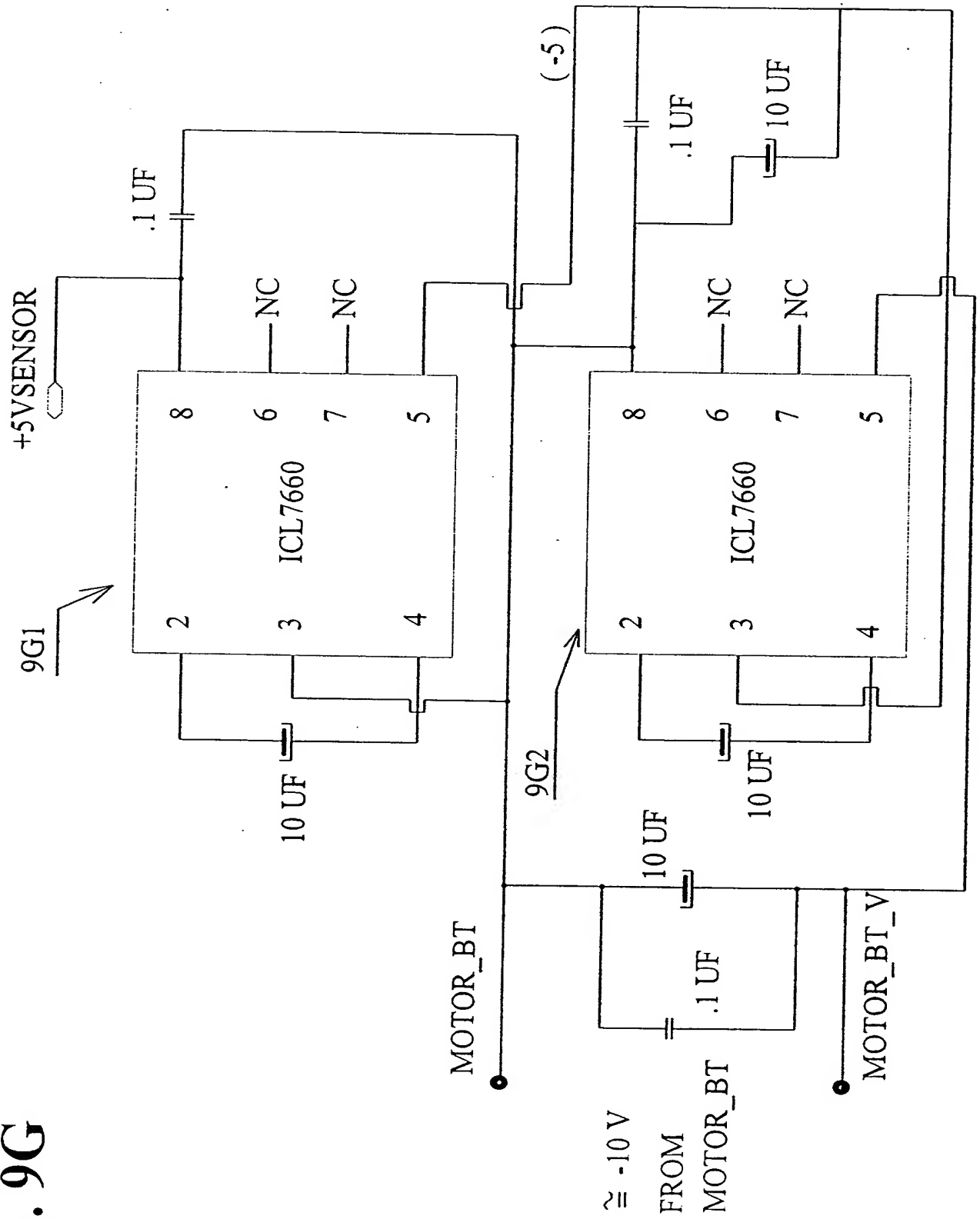


Fig. 9H

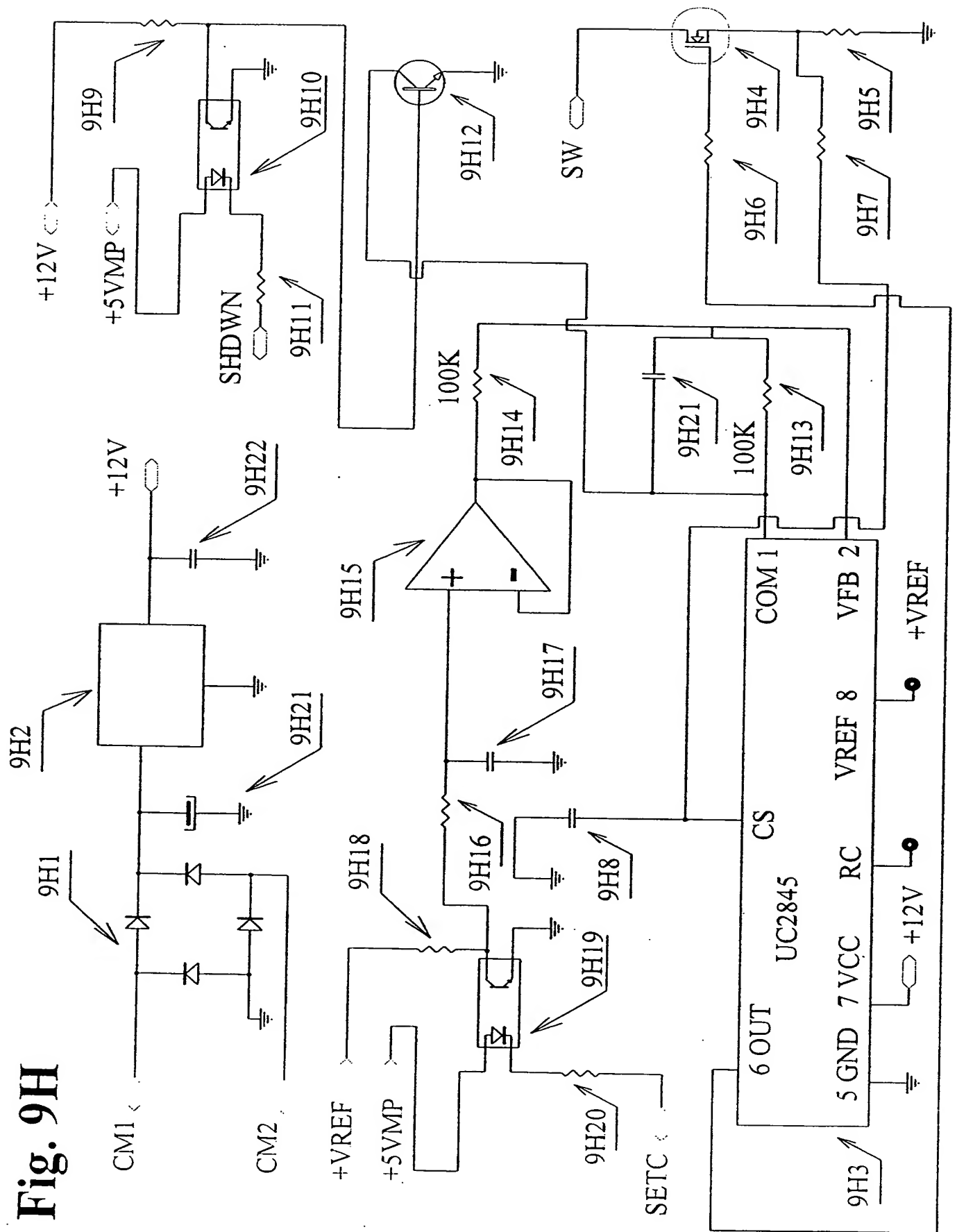


Fig. 9I

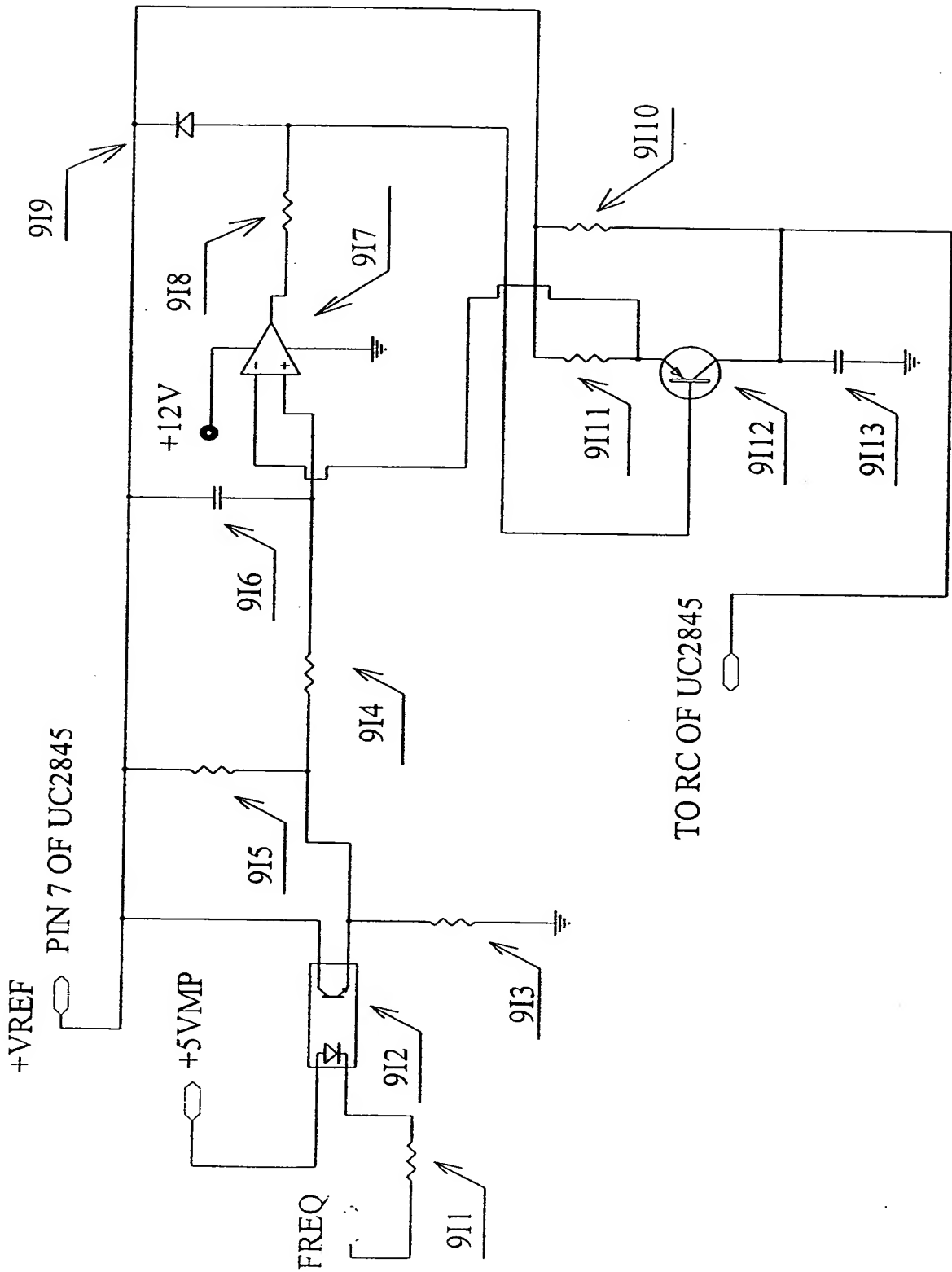
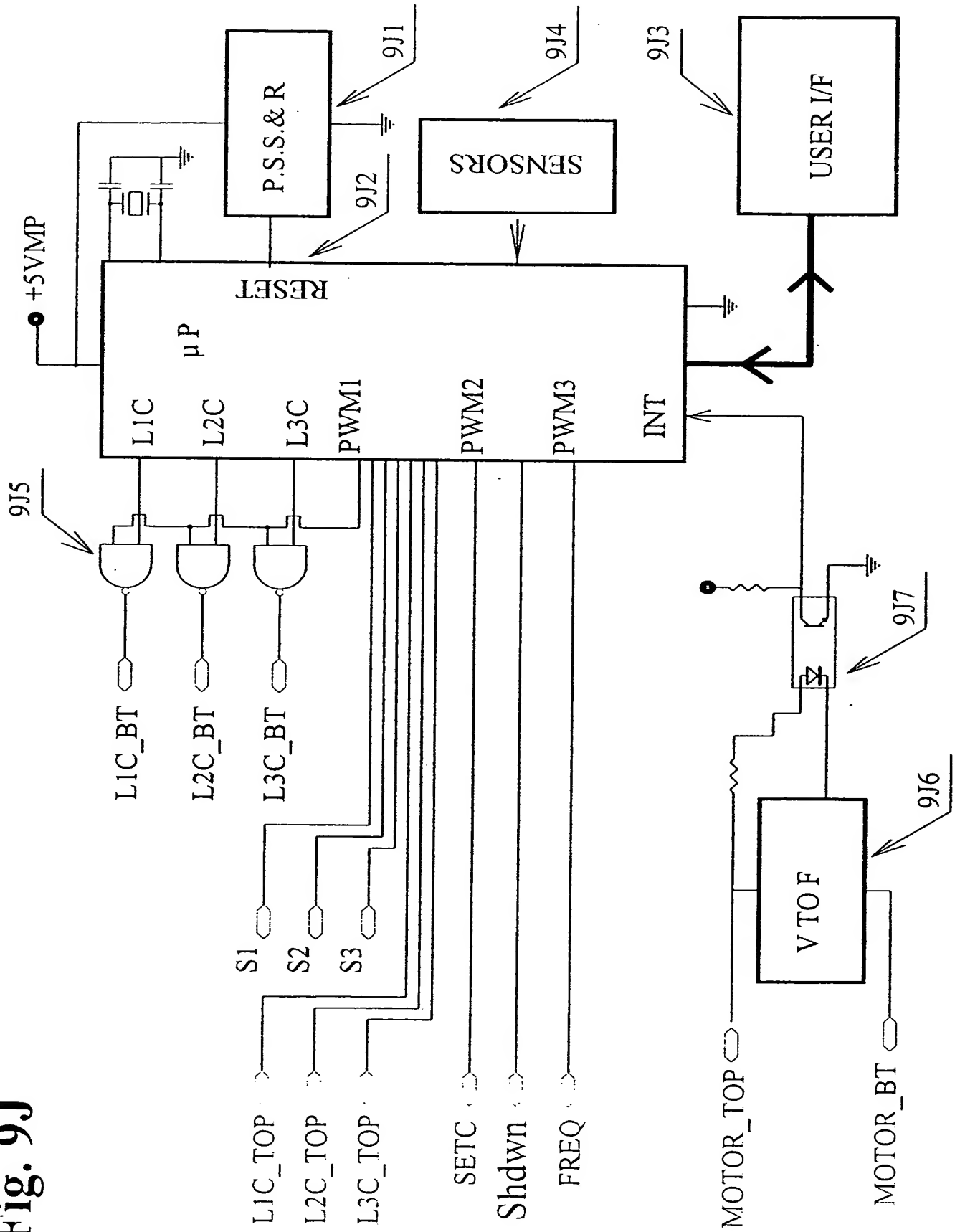
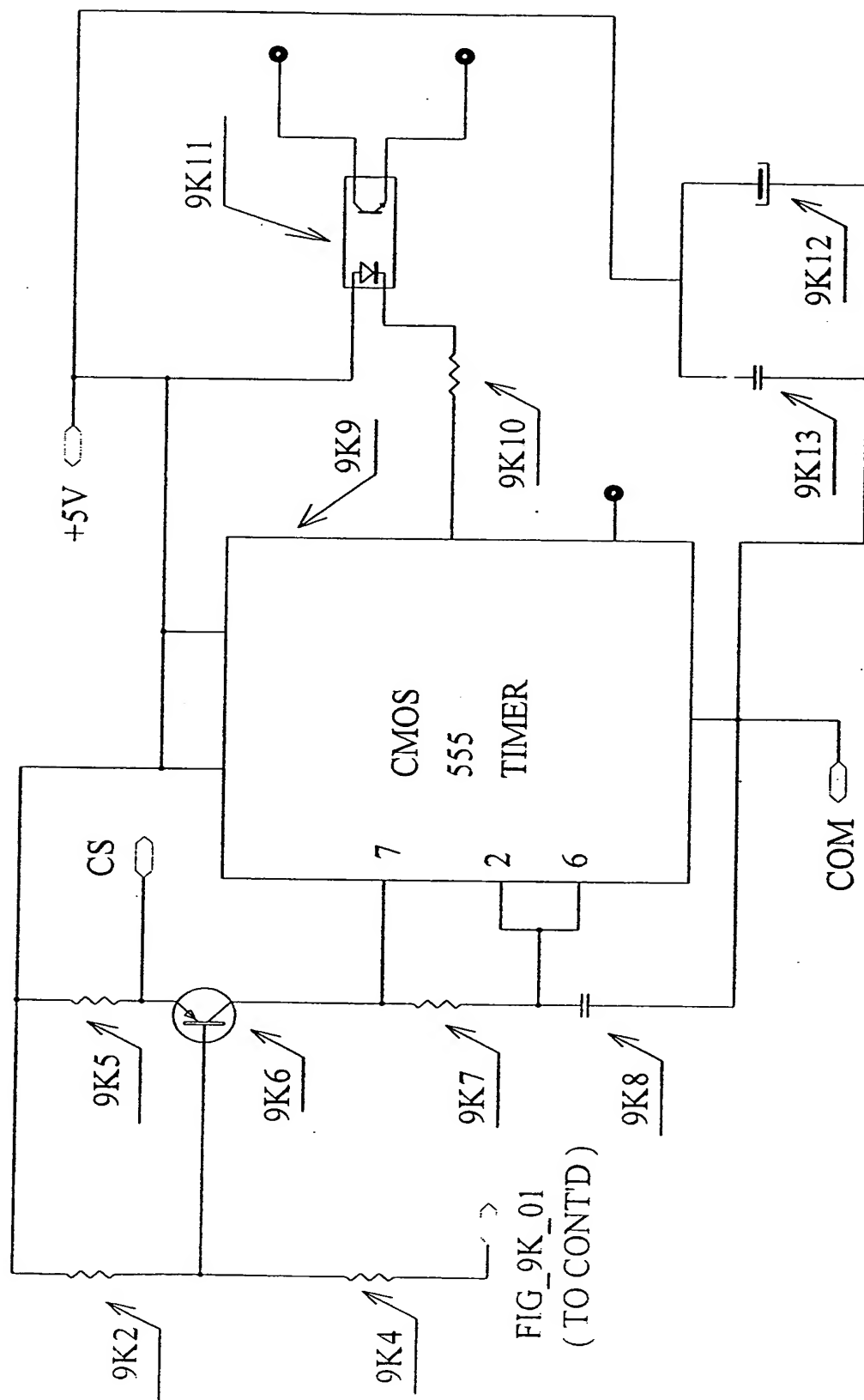


Fig. 9J





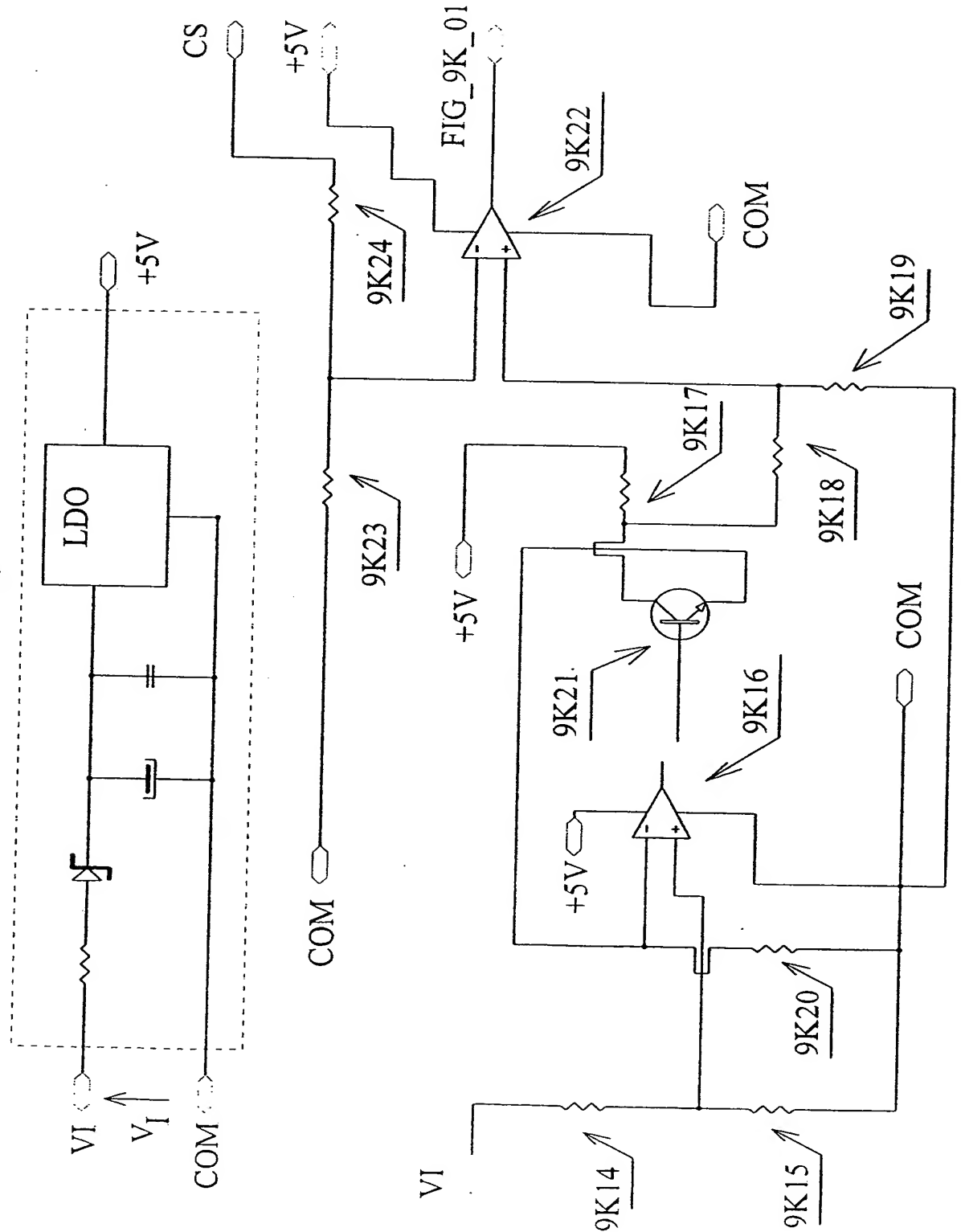


Fig. 9L

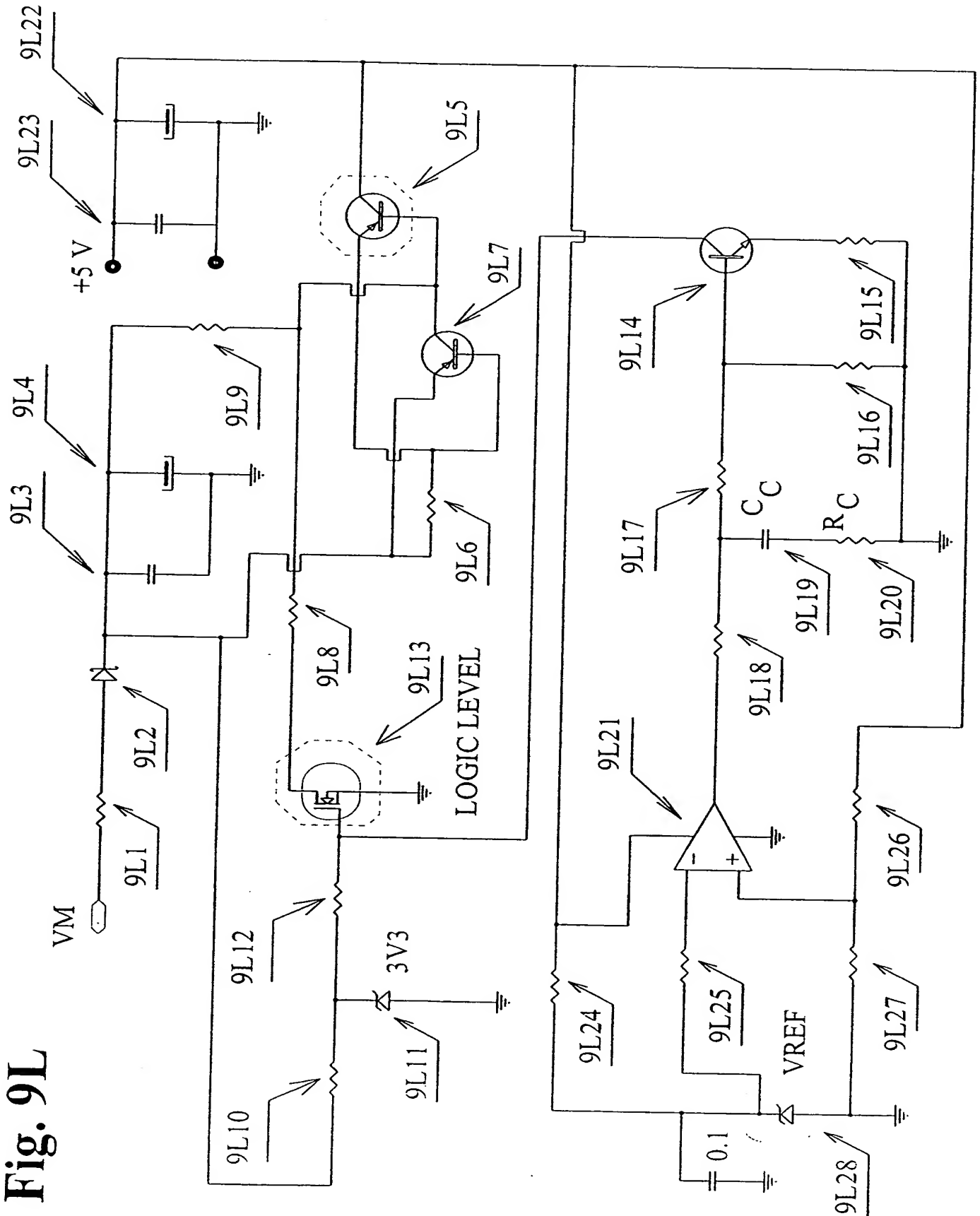
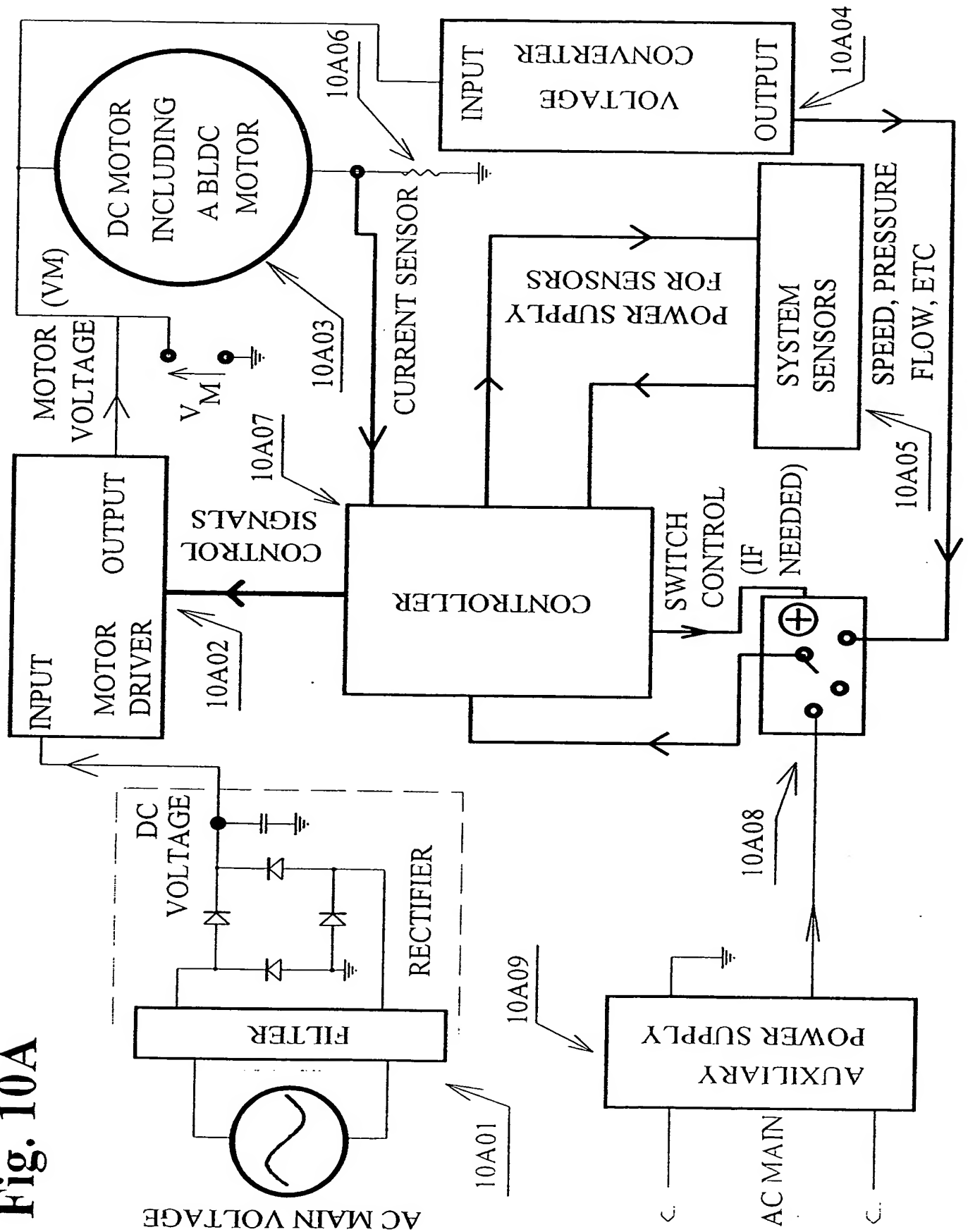


Fig. 10A



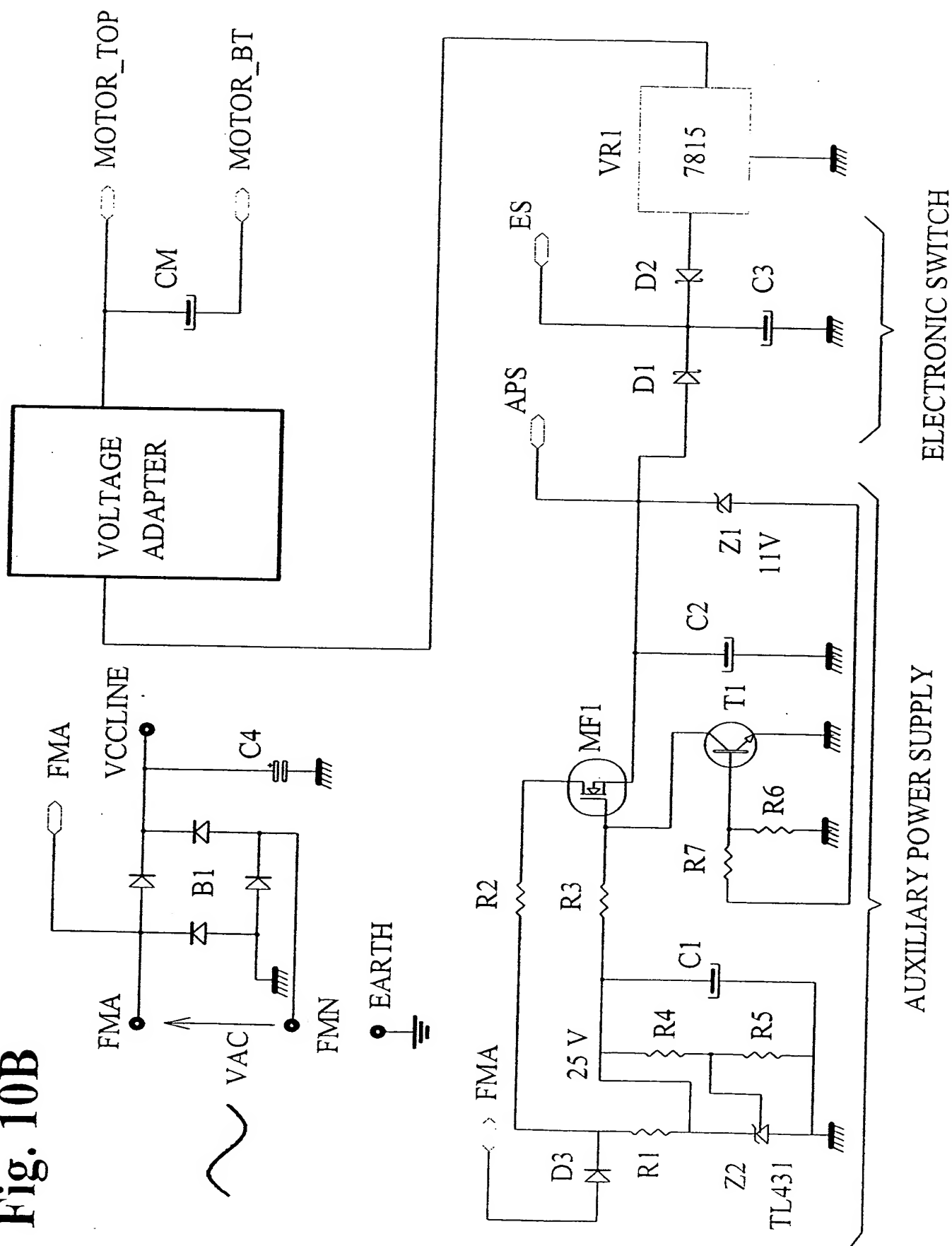
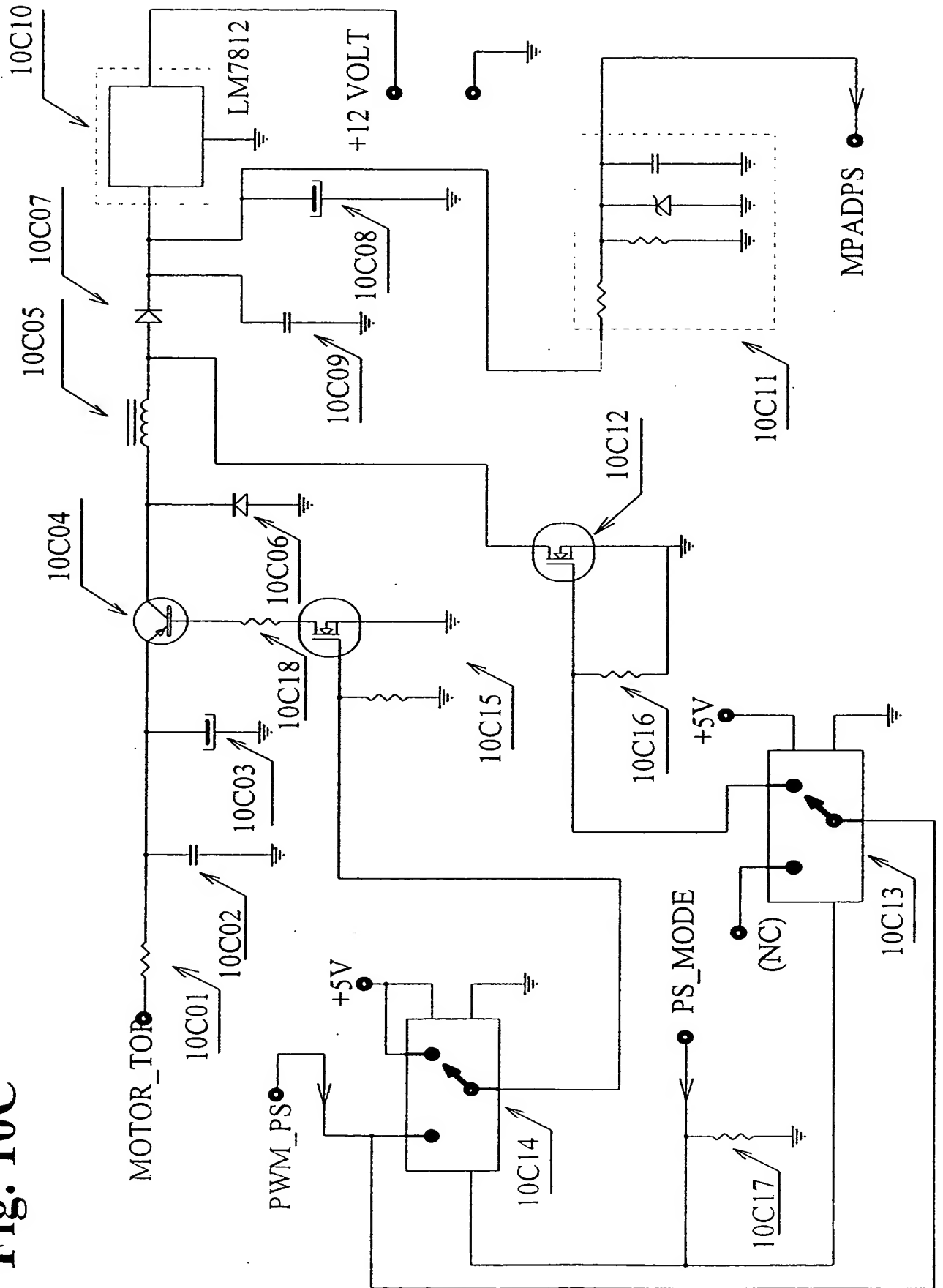


Fig. 10C



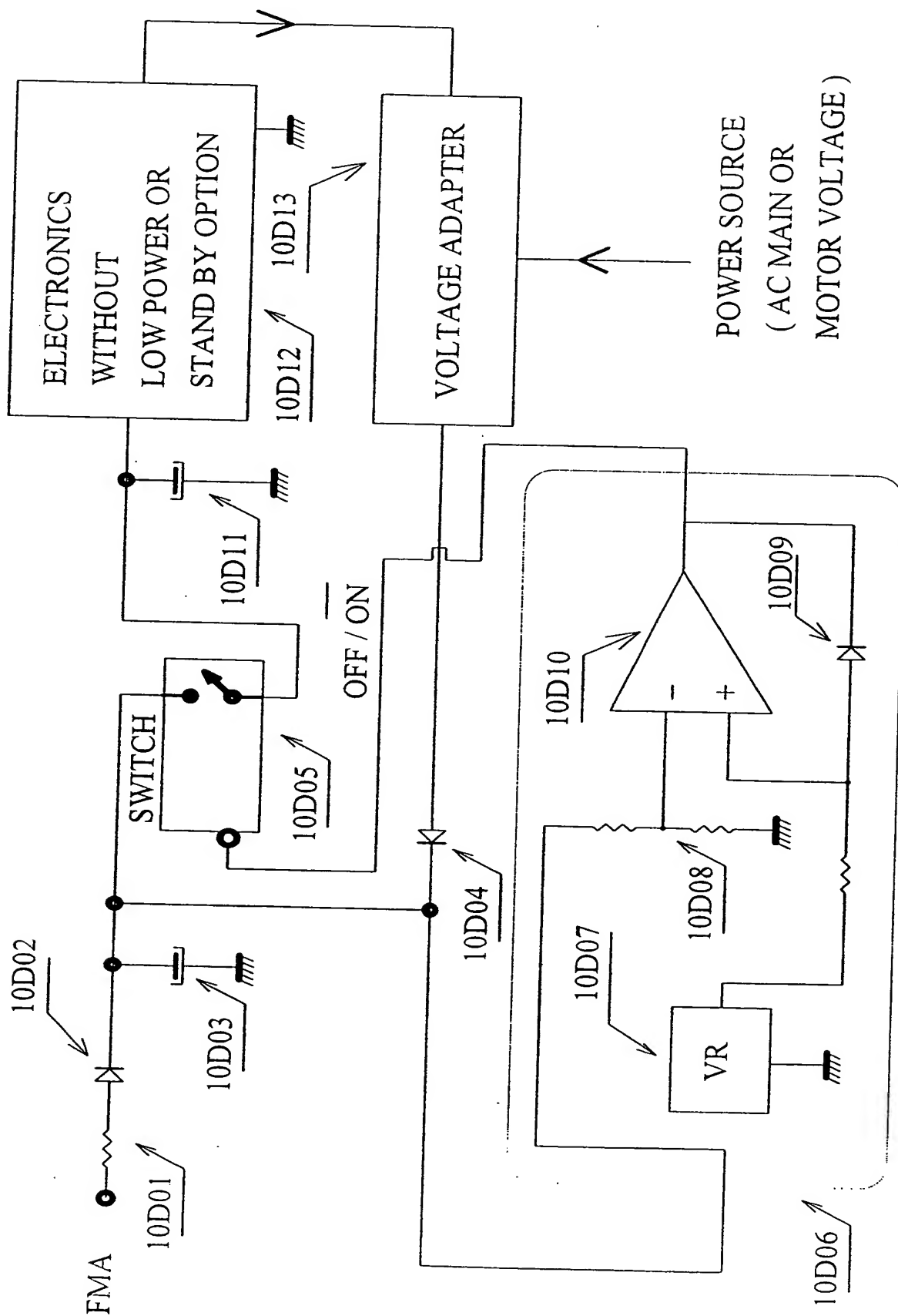


Fig. 10E

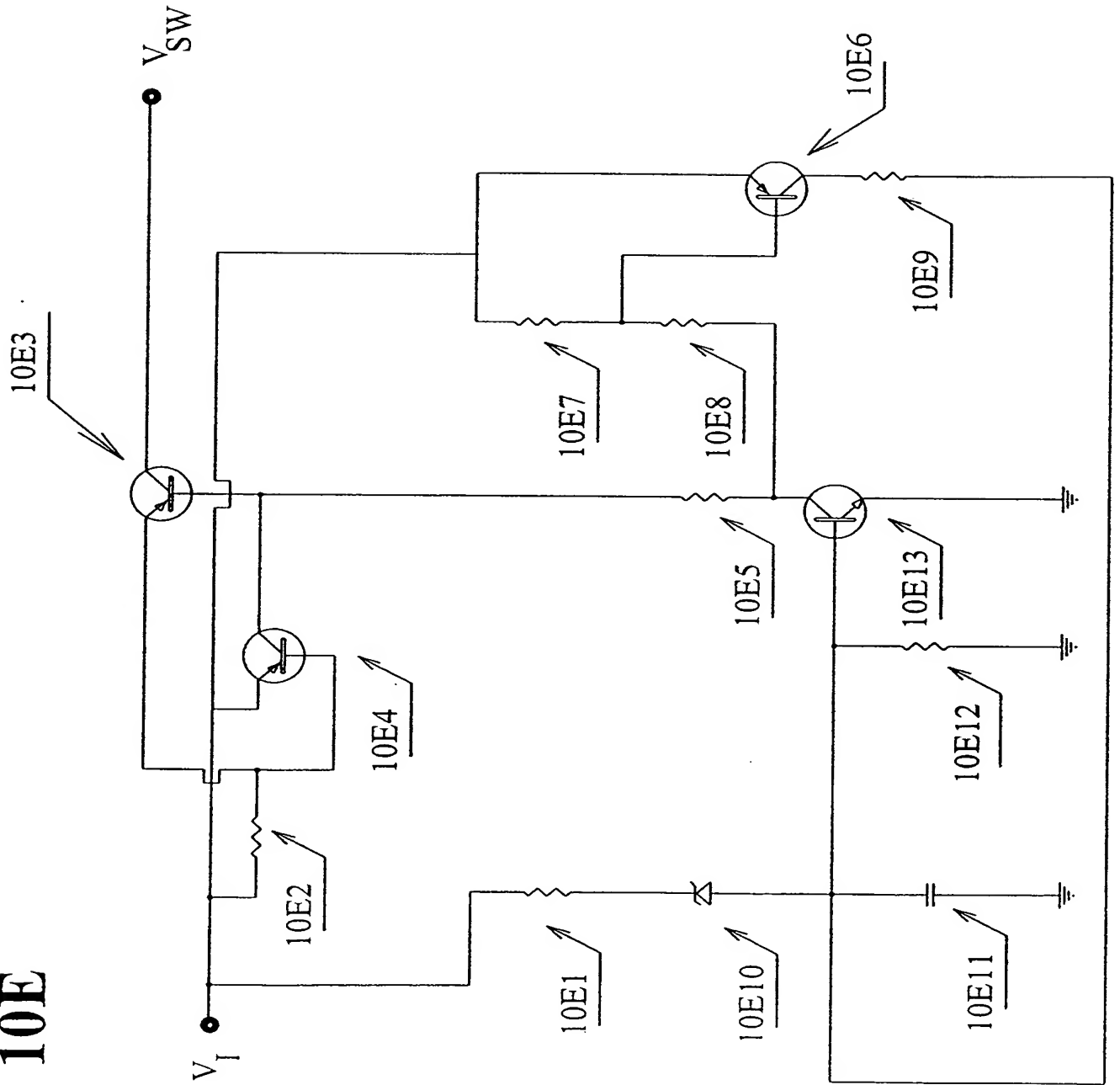


Fig. 11A

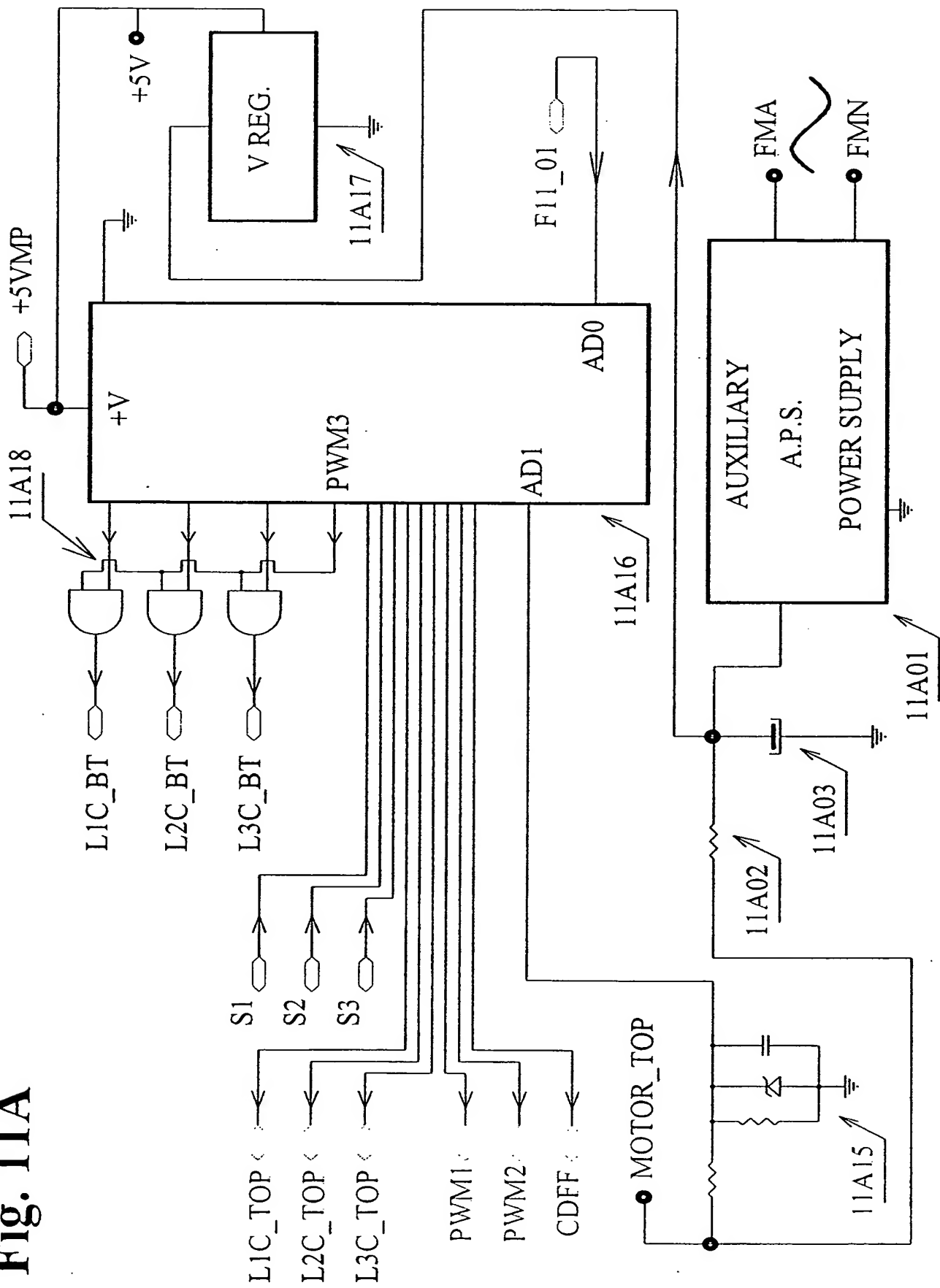
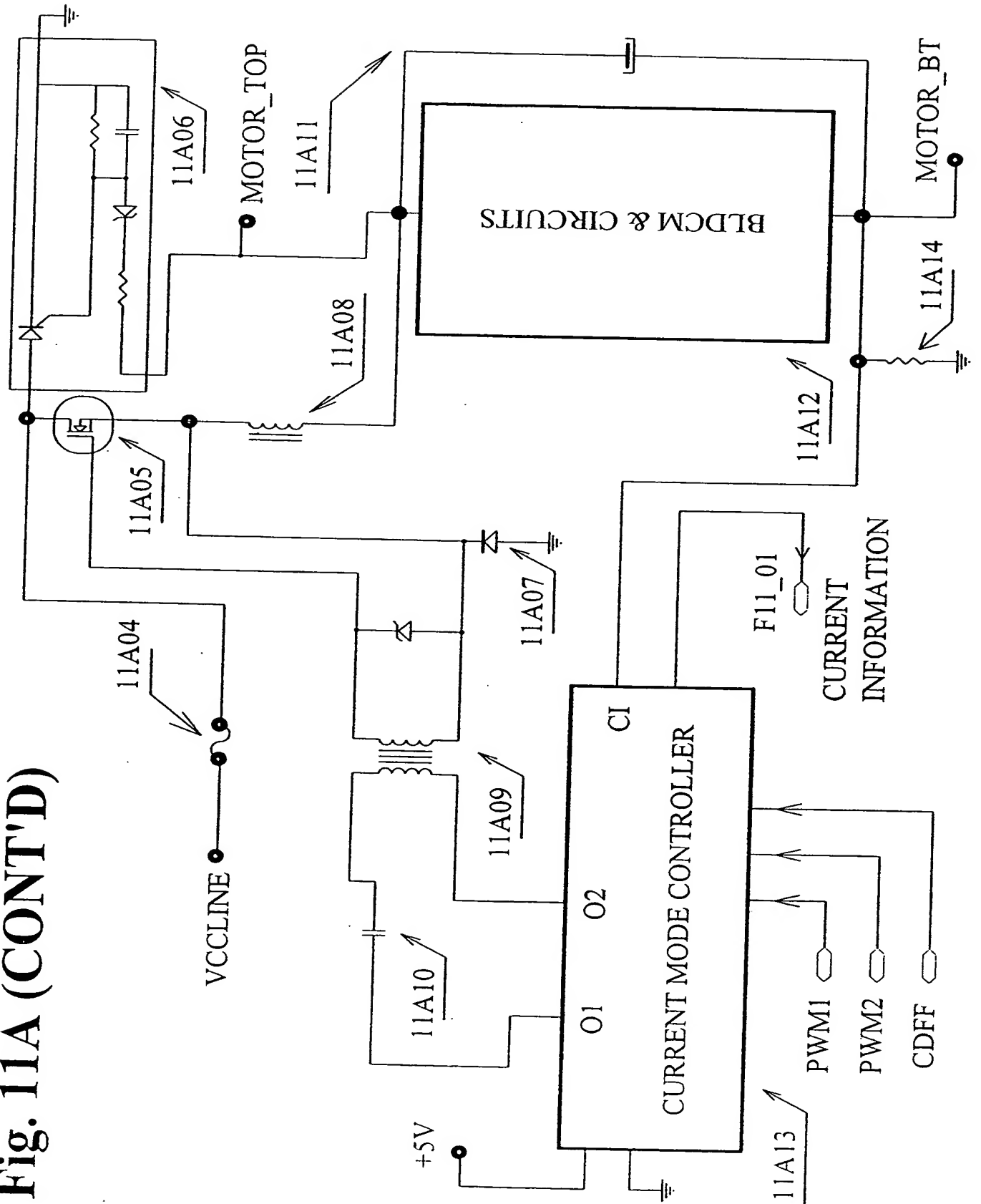
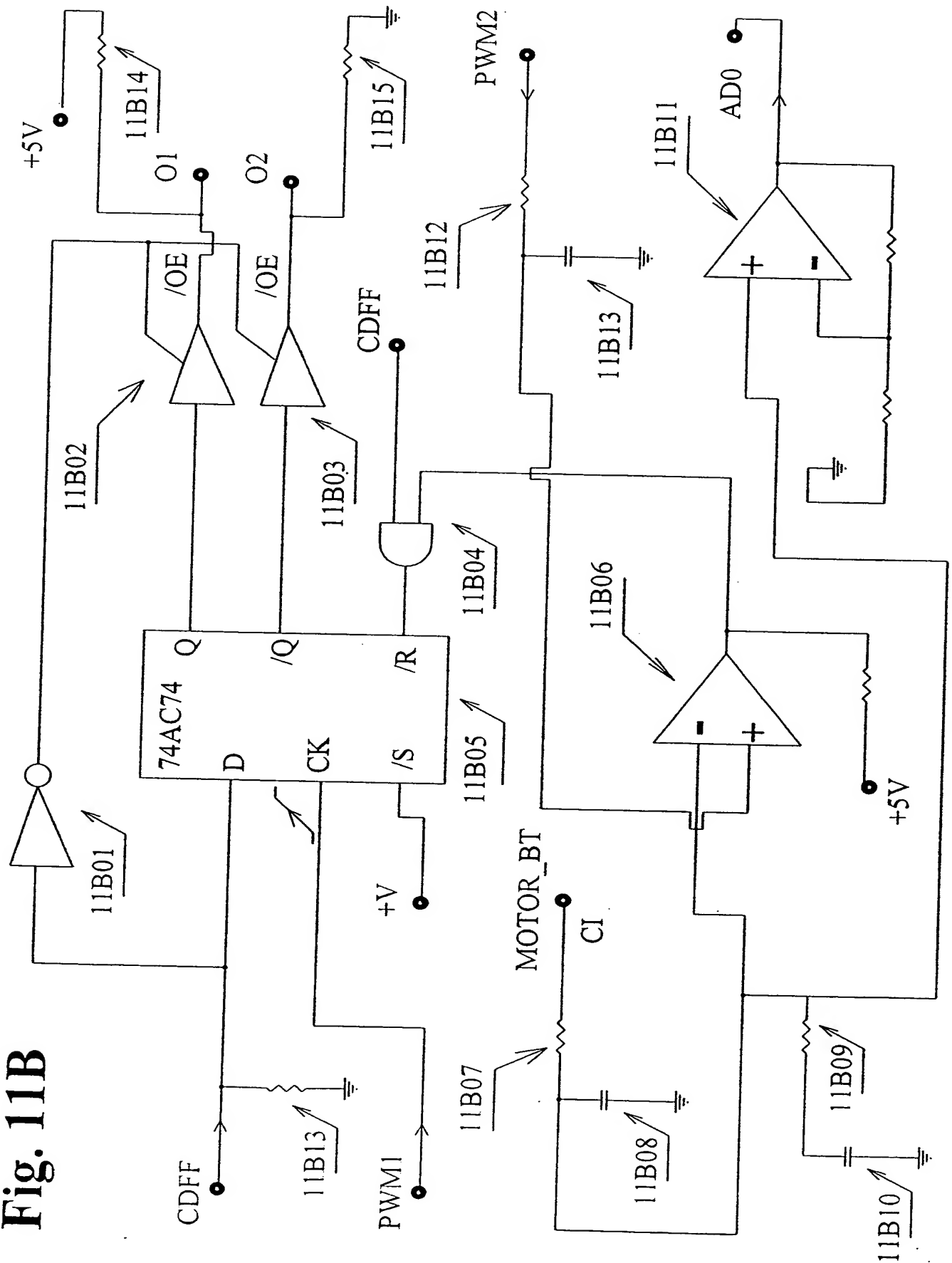


Fig. 11A (CONT'D)





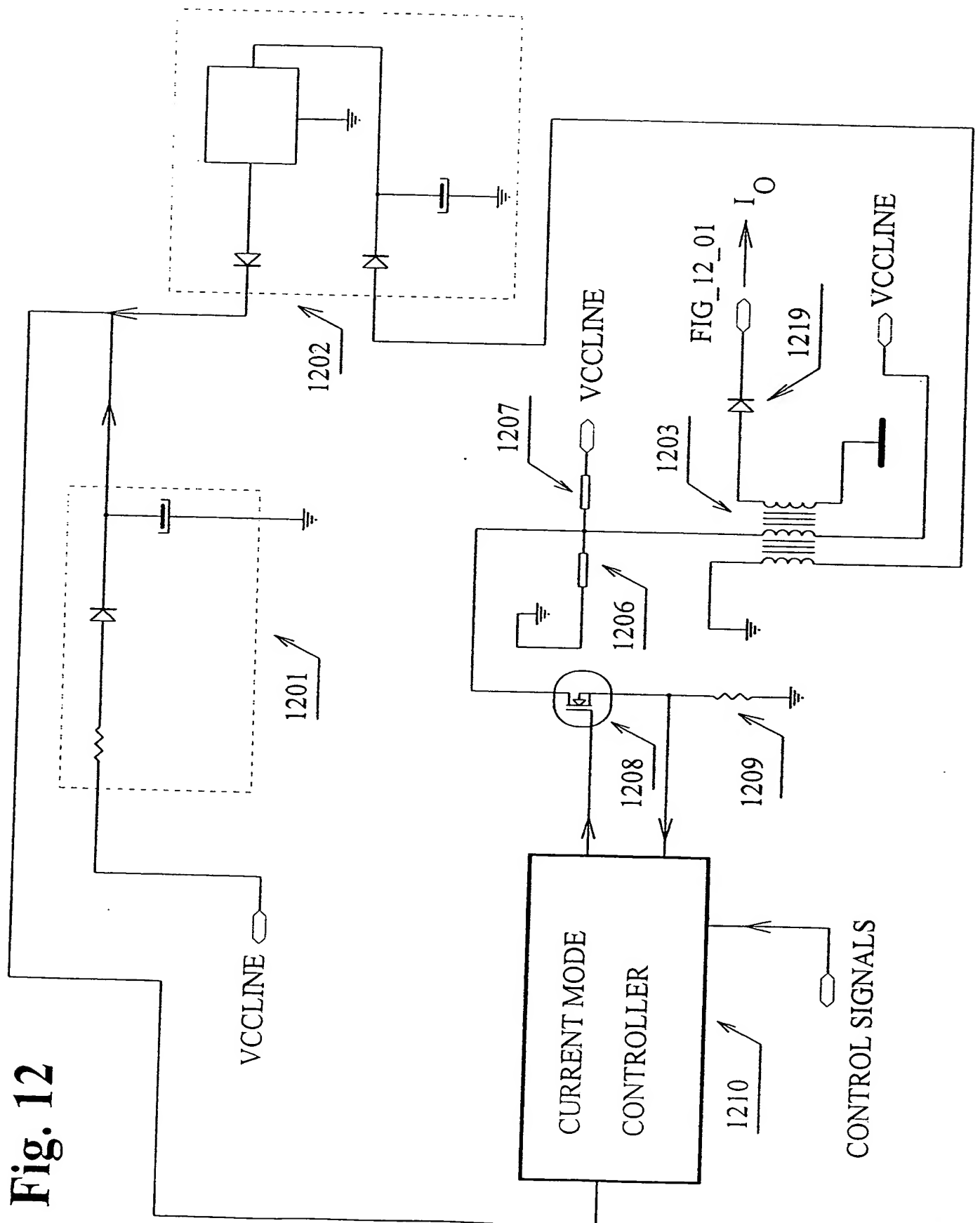


Fig. 12 (CONT'D)

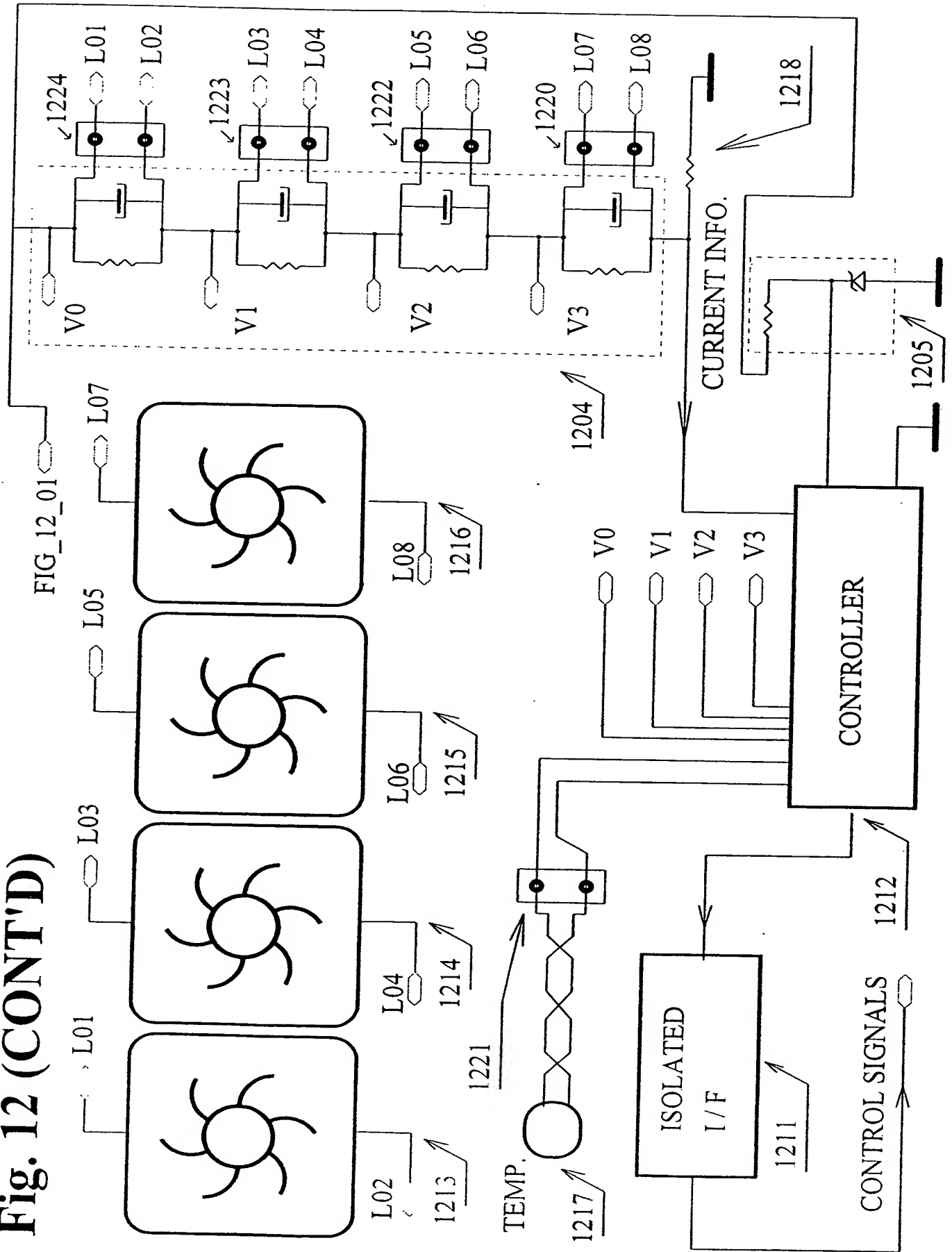


Fig. 13

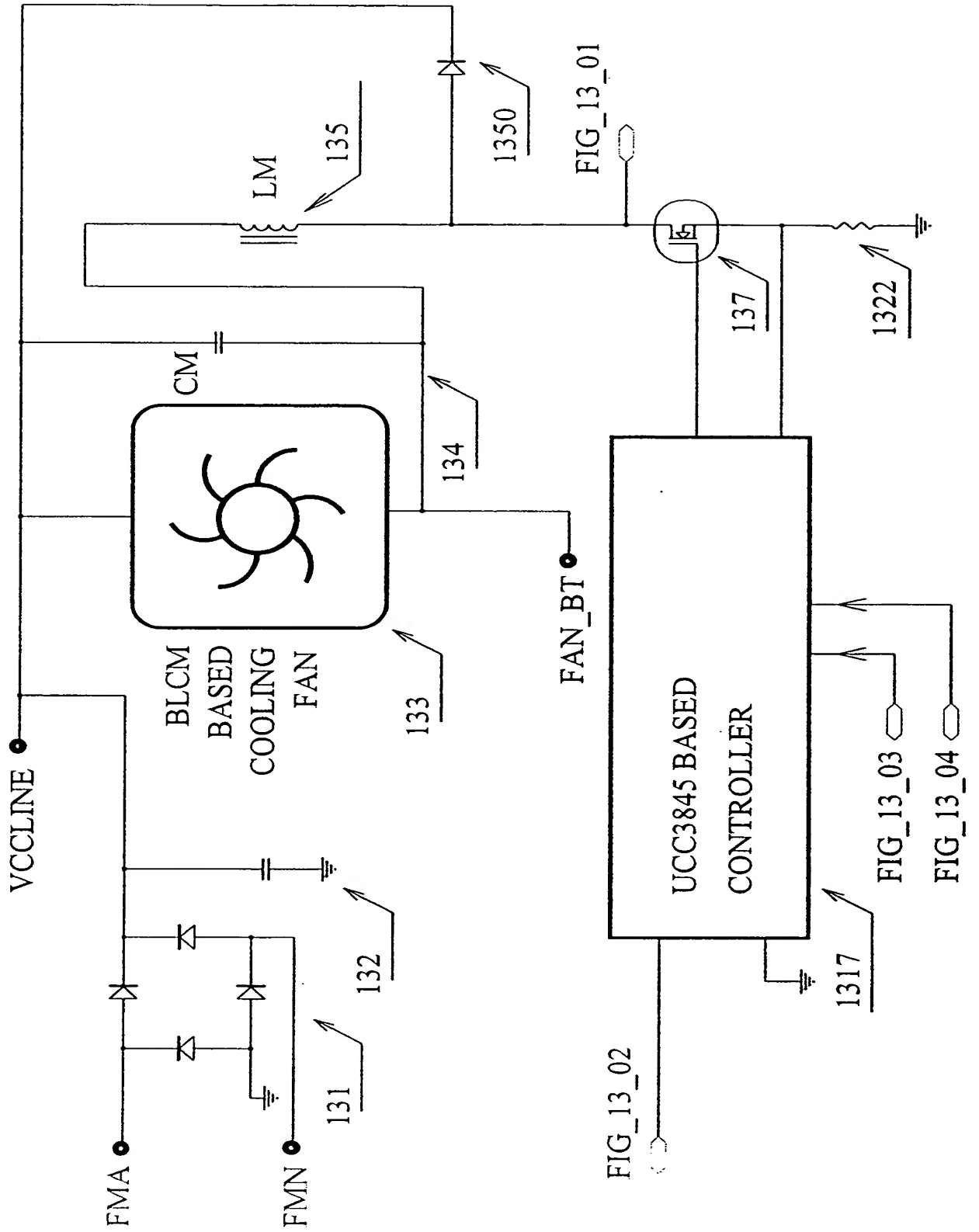


Fig. 13 (CONT'D)

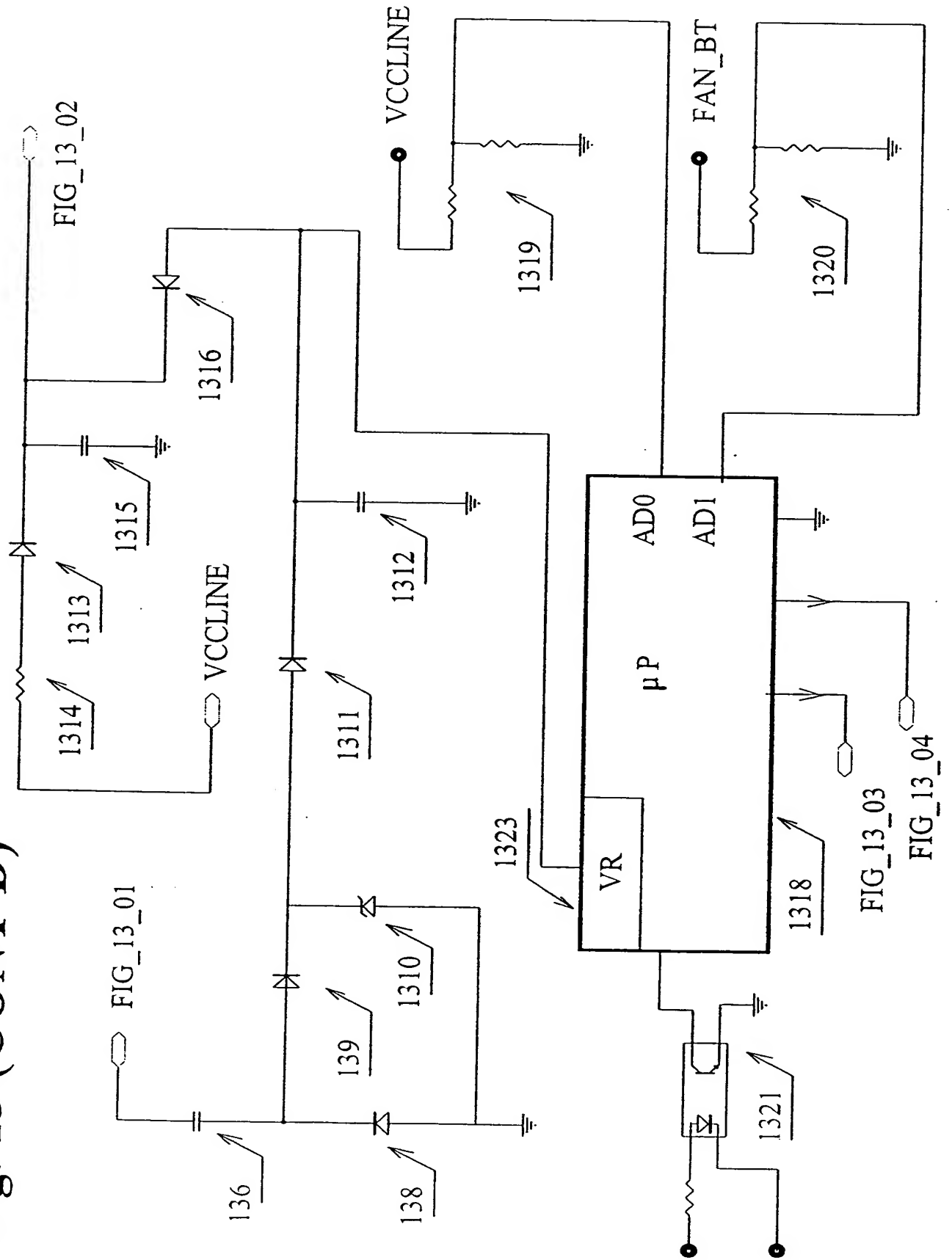


Fig. 14

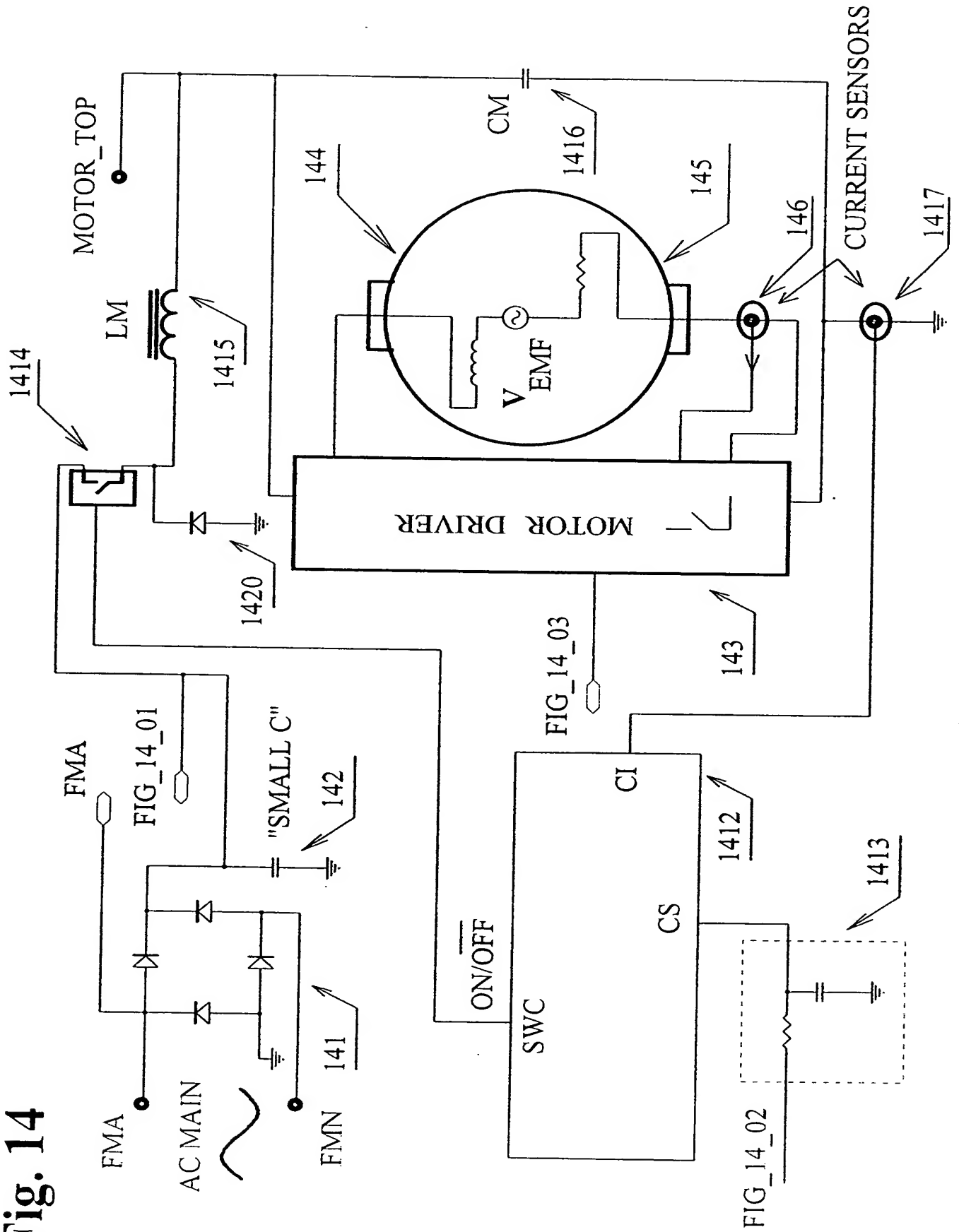
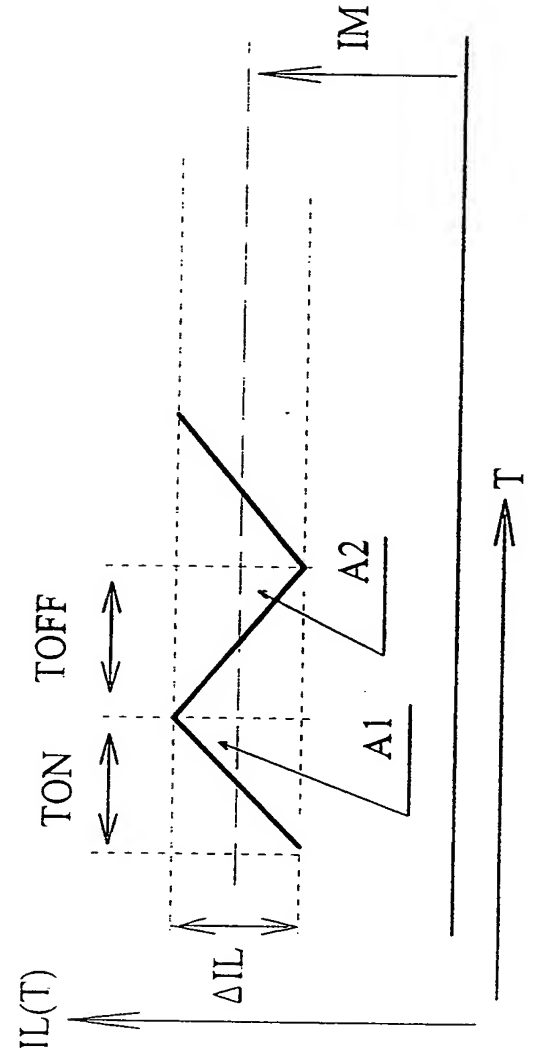
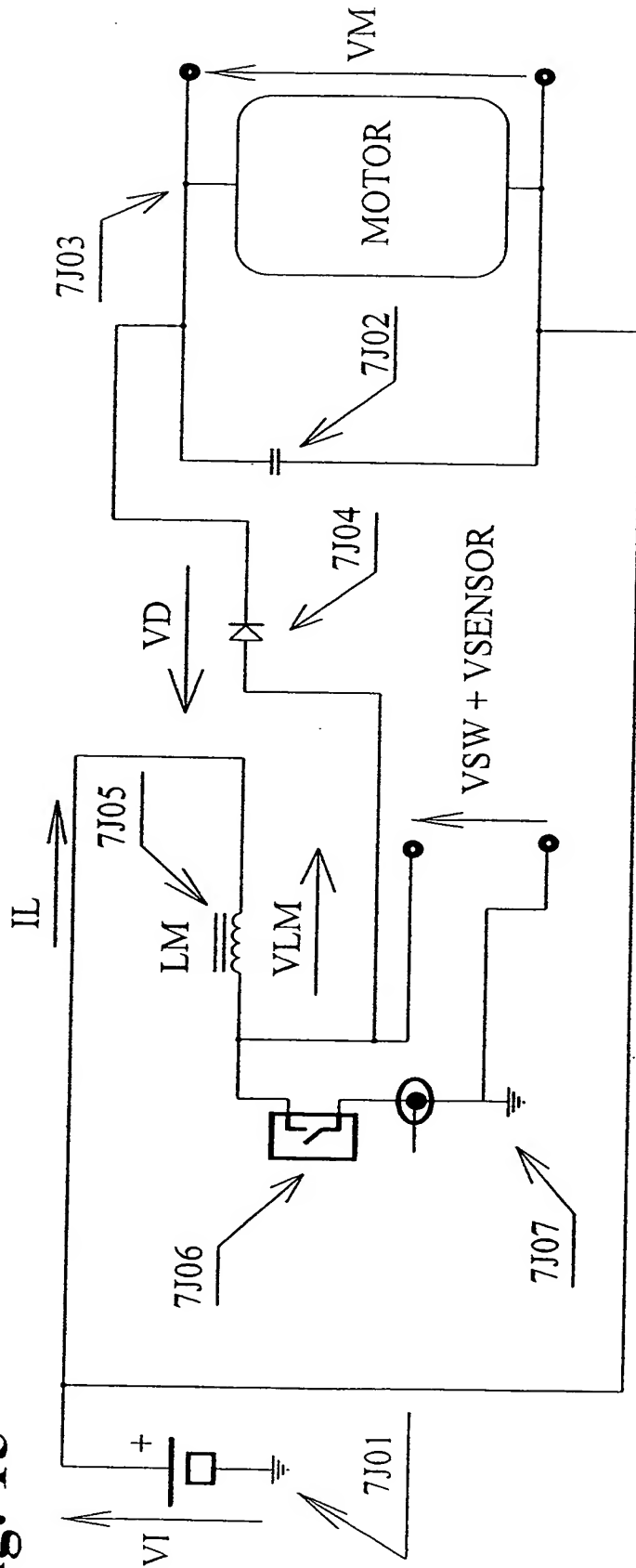




Fig. 15



$$(1501) V_M \cong I_M \cdot R_M + V_{emf}$$

$$(1502) V_{emf} = K_v \cdot \omega_M$$

$$(1503) V_{SW} + V_{SENSOR} \ll V_L$$

$$(1504) V_D \ll V_M$$

$$(1505) \Delta I_L = \frac{V_I}{L_M} T_{ON} = \frac{V_M}{L_M} T_{OFF}$$

$$(1506) \frac{T_{ON}}{T_{OFF}} = \frac{V_M}{V_I} \quad (\text{FOR CONTINUOUS CONDUCTION MODE})$$

Fig. 15 (CONT'D)

Fig. 16

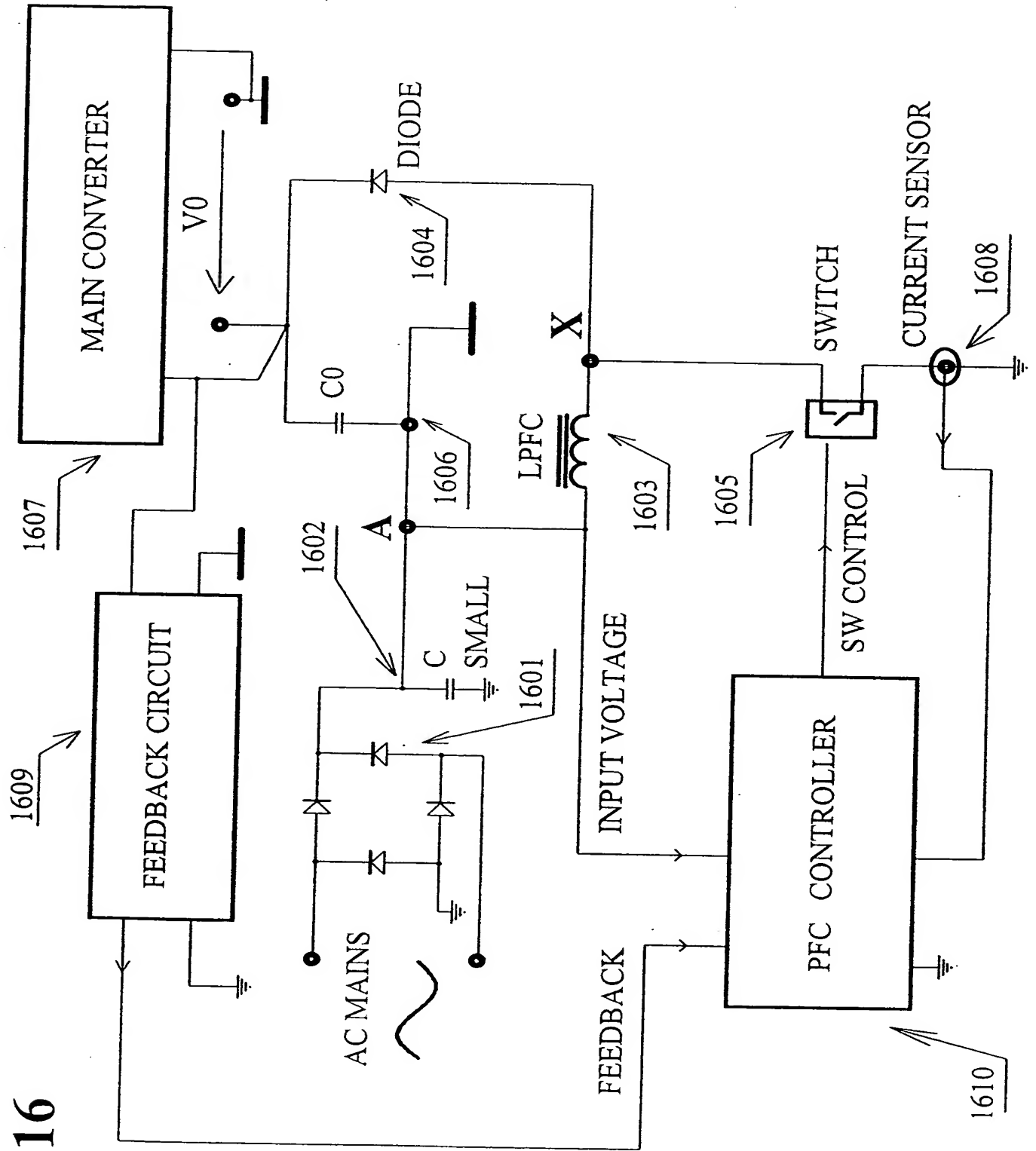


Fig. 17A

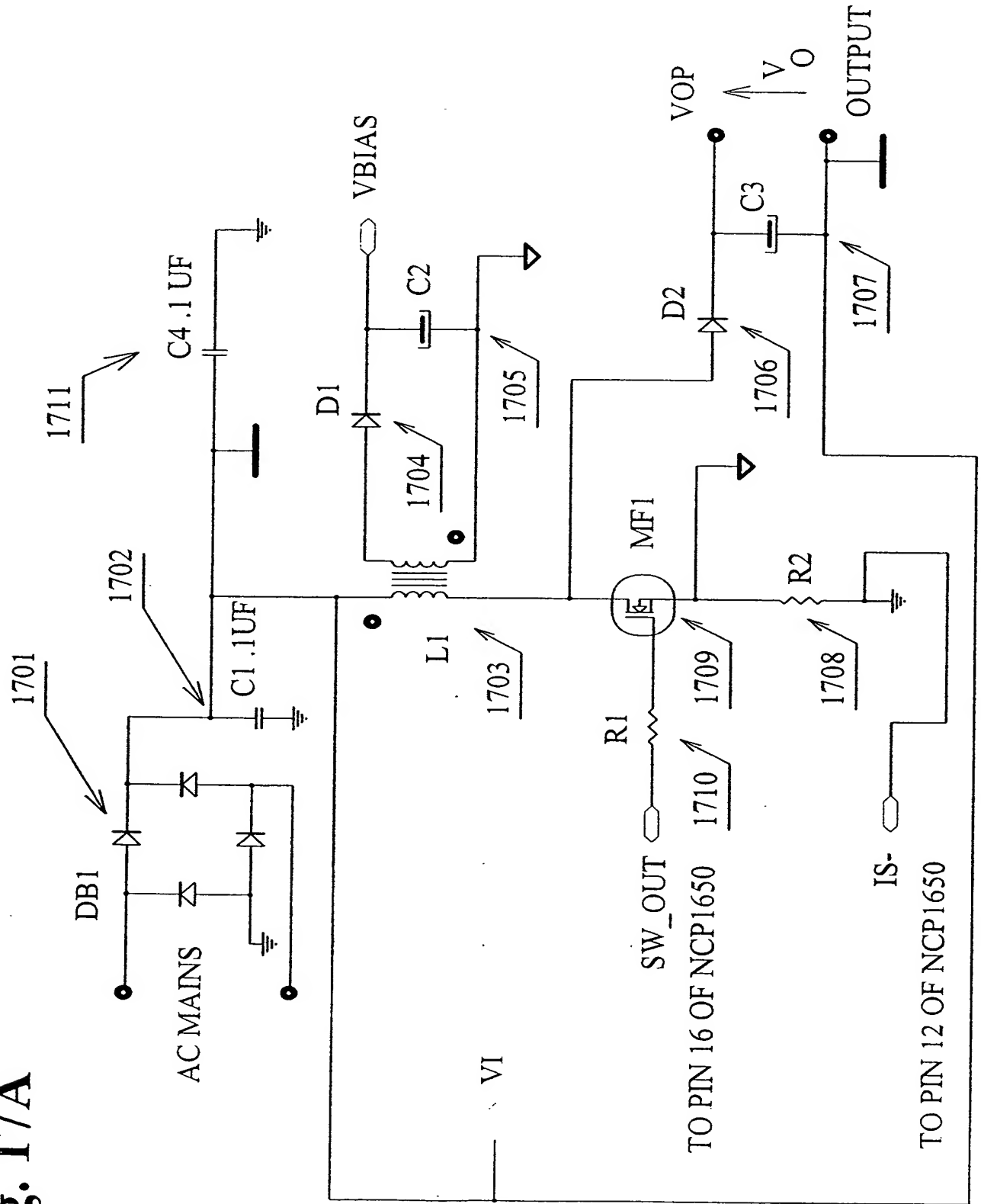


Fig. 17B

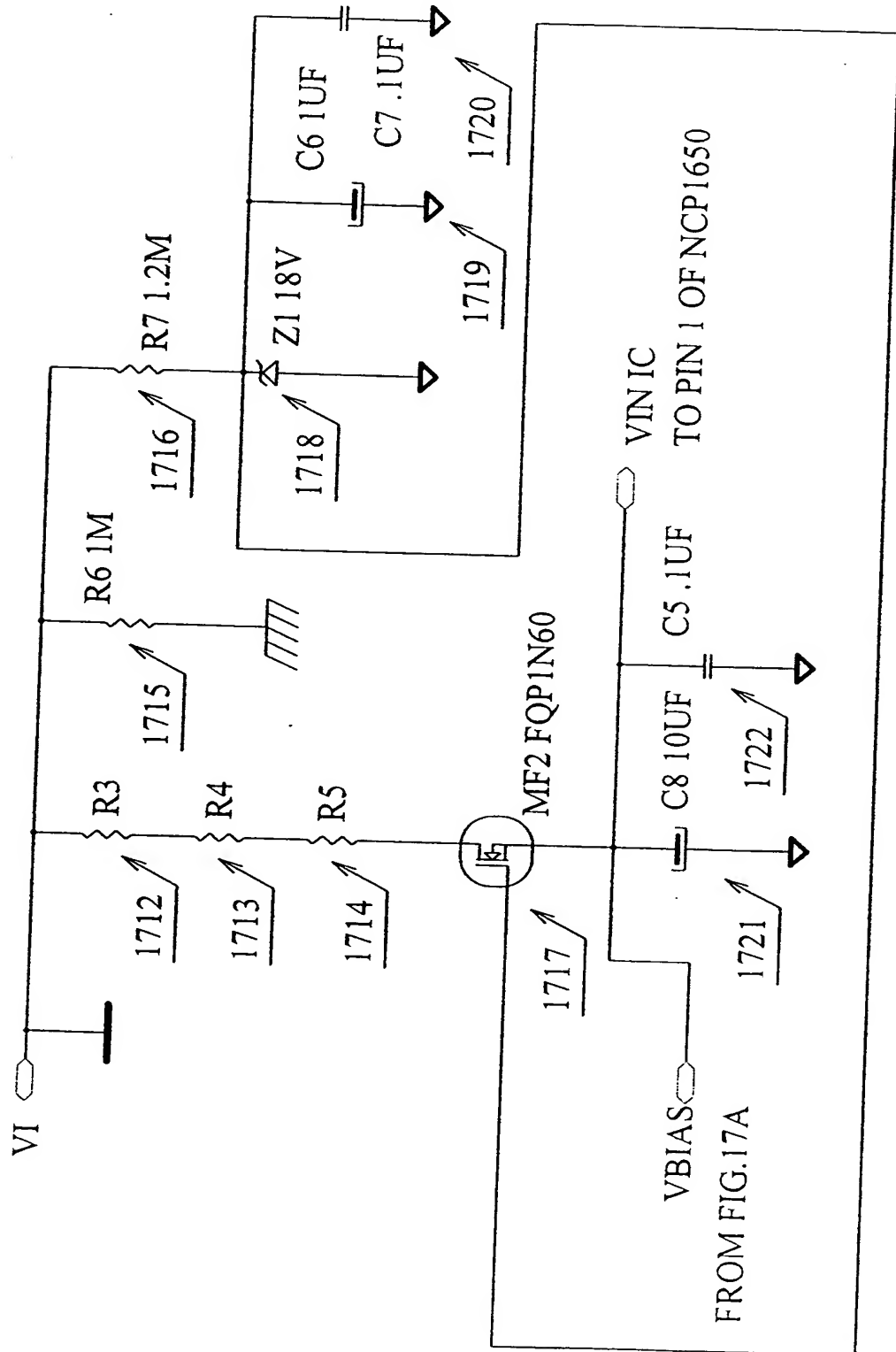


Fig. 17C

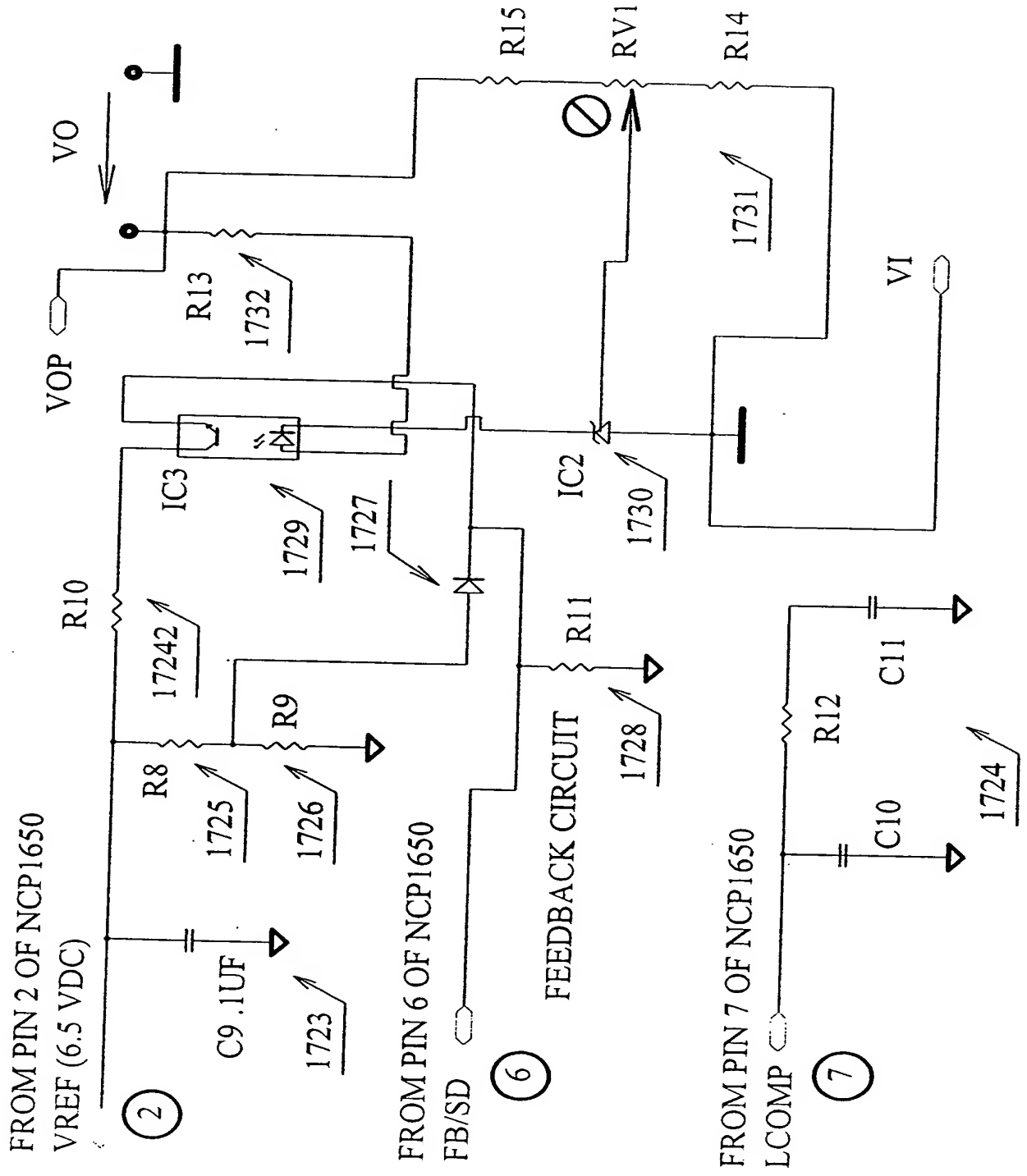


Fig. 17D

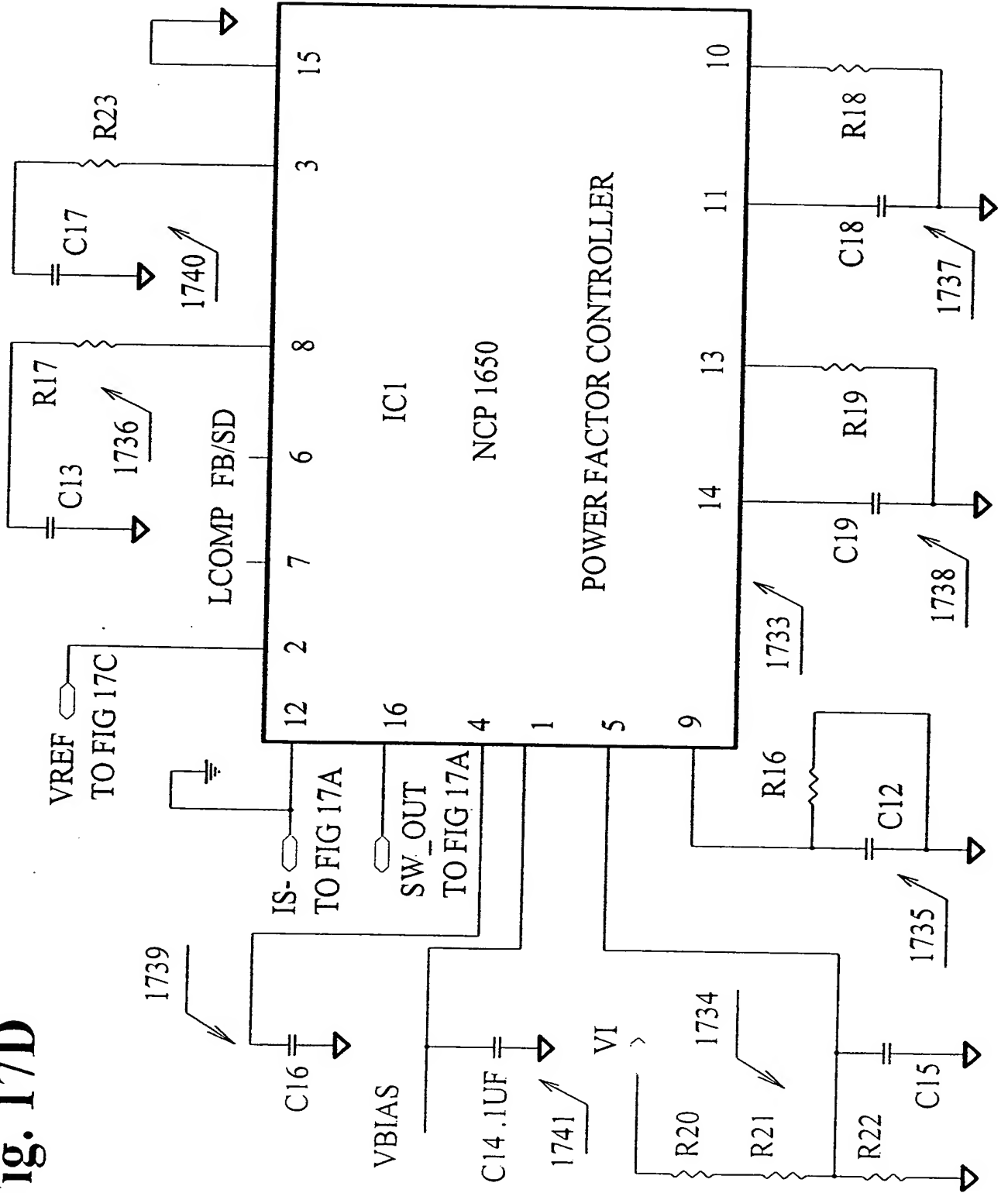


Fig. 17E

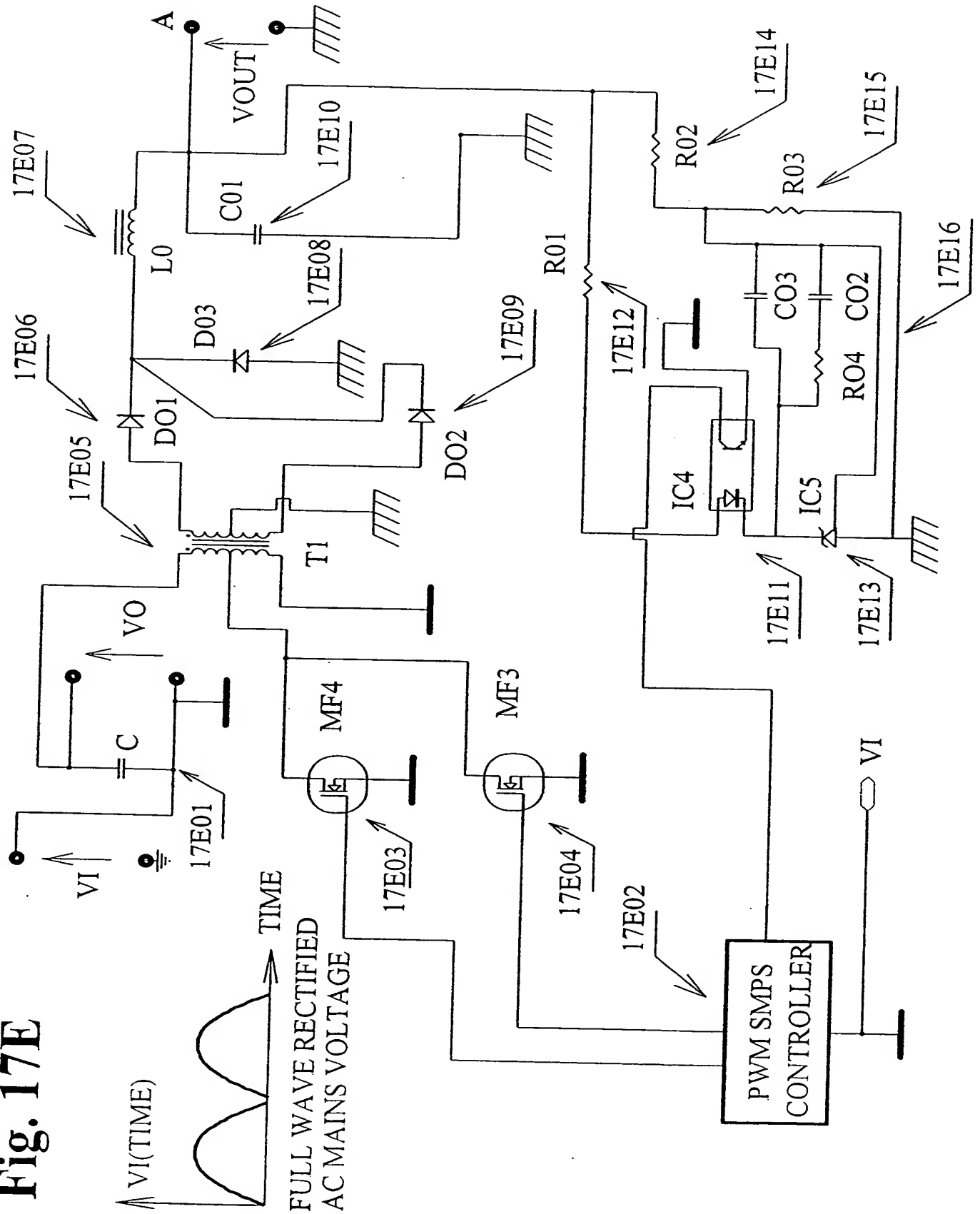


Fig. 17F

